MULTIPLICATIVELY TRANSTABLE CONIC SECTIONS WITH RESPECT TO FIXED COEFFICIENTS

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SUMMER SCHOOL ON GENERAL ALGEBRA AND ORDERED SETS

Blansko, Czech Republic September 7 – 12, 2025

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- **4.** CENTRES OF PARTIALLY TRANSTABLE CONIC SECTIONS



INTRODUCTION

WHAT IS TRANSTABILITY?

▶ the basic method of preservation

ADDITIVE TRANSTABILITY:

$$+$$
 $F(x+k,y-k)=F(x,y)$ for $k\in\mathbb{R}$ and $x,y\in\mathbb{R}$.

MULTIPLICATIVE TRANSTABILITY:

$$\bigcirc F\left(x \cdot k, \frac{y}{k}\right) = F(x, y) \text{ for } k \in \mathbb{R} \setminus \{0\} \text{ and } x, y \in \mathbb{R}.$$

SHIFT TRANSTABILITY:

$$\uparrow\downarrow$$
 $F(w,z)=F(x,y)$ for $x\prec w$, $z\prec y$ and $w,x,y,z\in L$.

FOR EXAMPLE: POLYNOMIALS

DEFINITION

We say that the polynomial p(x) is **Transtable** with the polynomial r(x) if the polynomial r(x) was created from the polynomial p(x) by **multiplying** the (nonzero) constant $k \in \mathbb{R}$ to one coefficient, and by **dividing** the same constant k from another coefficient.

⇒ The product of the coefficients is preserved (except for zero coefficients).

REMARK:

- Both polynomials must be of **the same degree**.
- Polynomials with zero coefficients are a problem because the product of the coefficients is equal to zero and the polynomials may not be transtable.
- This problem can be solved by dividing the entire set of polynomials into smaller classes based on **the number and position of the zero coefficients**.

TRANSTABILITY FOR CONIC SECTIONS

DEFINITION

Two conic sections K and L are said to be *Multiplicatively Transtable* if there exists a constant $k \in \mathbb{R} \setminus \{0\}$ such that by **multiplying one coefficient** and **dividing another coefficient** of the conic section K by the constant k we get the conic section L.

Specifically, for conic sections K_0 and L_0 with non-zero coefficients the **product of their coefficients is the same**, i.e. for conic sections

$$K_0: a_1x^2 + b_1y^2 + c_1xy + d_1x + e_1y + f_1 = 0,$$

 $L_0: a_2x^2 + b_2y^2 + c_2xy + d_2x + e_2y + f_2 = 0,$

this condition holds: $a_1 \cdot b_1 \cdot c_1 \cdot d_1 \cdot e_1 \cdot f_1 = a_2 \cdot b_2 \cdot c_2 \cdot d_2 \cdot e_2 \cdot f_2$.

REMARK:

- It is evident that the entire set of multiplicative transtable conic sections cannot be divided into equivalence classes based on the product of coefficients, with zero coefficients being the primary issue. However ...
- The set of transtable conic sections can be denoted [k] by a real number k representing the **product of non-zero coefficients**.
- For a conic section with a coefficient product equal to 0, additional information about the position of the zero coefficients is required, for instance [0_{y²,x,const}].
- Each non-zero real number corresponds to a single class, but the zero class [0] must be divided into 63 subclasses these are equivavalence classes for entire set of transtable conic sections.

FOR EXAMPLE

1. $K: \mathbf{1}x^2 + \mathbf{1}y^2 - \mathbf{1} = \mathbf{0}, K \in [0_{xy,x,y}]$

$$K_{2}: 2x^{2} + \frac{1}{2}y^{2} - 1 = 0$$

$$K_{3}: \frac{1}{2}x^{2} + 2y^{2} - 1 = 0$$

$$K_{4}: 2x^{2} + 1y^{2} - \frac{1}{2} = 0$$

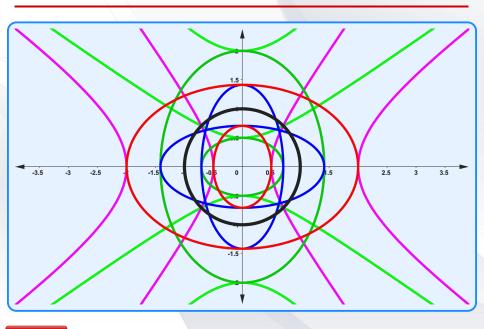
$$K_{5}: \frac{1}{2}x^{2} + 1y^{2} - 2 = 0$$

$$K_{6}: 1x^{2} + 2y^{2} - \frac{1}{2} = 0$$

$$K_{10}: 1x^{2} - 2y^{2} + \frac{1}{2} = 0$$

$$K_{11}: 1x^{2} - \frac{1}{2}y^{2} + 2 = 0$$

Shift of the two different NON-ZERO coefficients by 2.



FOR EXAMPLE

2.
$$K: \mathbf{1}x^2 + \mathbf{1}y^2 - \mathbf{1} = \mathbf{0}, K \in [0_{xy,x,y}]$$

$$K_{12}: 2x^{2} + 1y^{2} - 1 = 0$$

$$K_{13}: \frac{1}{2}x^{2} + 1y^{2} - 1 = 0$$

$$K_{18}: 1x^{2} + \frac{1}{2}y^{2} - 1 = 0$$

$$K_{18}: 1x^{2} - 2y^{2} - 1 = 0$$

$$K_{19}: 1x^{2} - \frac{1}{2}y^{2} - 1 = 0$$

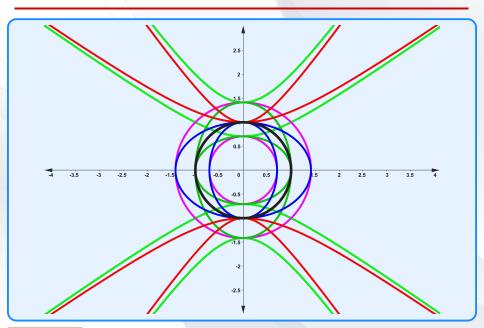
$$K_{15}: -\frac{1}{2}x^{2} + 1y^{2} - 1 = 0$$

$$K_{20}: 1x^{2} + 1y^{2} - 2 = 0$$

$$K_{16}: 1x^{2} + 2y^{2} - 1 = 0$$

$$K_{21}: 1x^{2} + 1y^{2} - \frac{1}{2} = 0$$

• Shift of the **ANY** two different coefficients by 2.



PARTIAL TRANSTABILITY

DEFINITION

A conic section *K* in the form

$$ax^2 + by^2 + cxy + dx + ey + f = 0$$

is said to be *Multiplicative Transtable with respect to* x^2 *and* y^2 with a conic section L if there **exists** $k \in \mathbb{R} \setminus \{0\}$ such that the conic section L has the form

$$(a \cdot k) x^2 + \frac{b}{k} y^2 + cxy + dx + ey + f = 0.$$

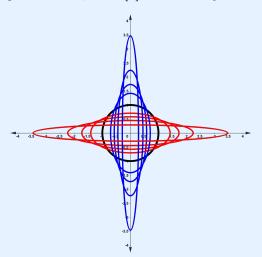
REMARK:

- Definition induces another 14 partial transtabilities.
- Complete transtability implies any partial transtability, but the reverse is not valid.

PARTIAL TRANSTABILITY

FOR EXAMPLE

3. $K: \mathbf{1}x^2 + \mathbf{1}y^2 - \mathbf{1} = \mathbf{0}, K \in [1] \text{ for } x^2 \text{ and } y^2$





INTERSECTION - PARTIALLY TRANSTABLE CONIC SECTIONS

THEOREM

Each two partially transtable conic sections have common points if and only if they are transtable with respect to x^2 and xy or y^2 and xy or x^2 and x or y^2 and y or xy and x or xy and y, i.e. there are no general common points for the 9 partial transtabilities.

Proof:

The proof is divided into **15** parts, for each partial transtability. Consider a conic section in the form:

$$ax^2 + by^2 + cxy + dx + ey + f = 0$$

Then ...

INTERSECTION – TRANSTABILITY WITH RESPECT TO x^2 AND y^2

Consider two arbitrary transtable conic sections K and L with respect to x^2 and y^2 :

$$K : ax^{2} + by^{2} + cxy + dx + ey + f = 0,$$

$$L : (a \cdot k) x^{2} + \frac{b}{k} y^{2} + cxy + dx + ey + f = 0.$$

In general **there are no intersections**. However, if we restrict some coefficients, we get:

1. The case a = 0 implies y = 0:

$$P_1^{x^2,y^2} = \left[-\frac{f}{d}, 0 \right]$$

2. The case b = 0 implies x = 0:

$$P_2^{x^2,y^2} = \left[0, -\frac{f}{e}\right]$$

FOR EXAMPLE

1. $K: -4x^2 + 7y^2 - 4xy + 5x + 2y - 4 = 0$

$$K_2: 12x^2 - \frac{7}{3}y^2 - 4xy + 5x + 2y - 4 = 0,$$

$$K_3: -\frac{4}{3}x^2 + 21y^2 - 4xy + 5x + 2y - 4 = 0,$$

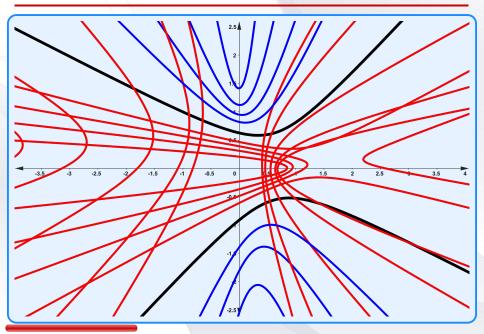
$$K_4: -20x^2 + \frac{7}{5}y^2 - 4xy + 5x + 2y - 4 = 0,$$

$$K_5: -\frac{4}{5}x^2 + 35y^2 - 4xy + 5x + 2y - 4 = 0,$$

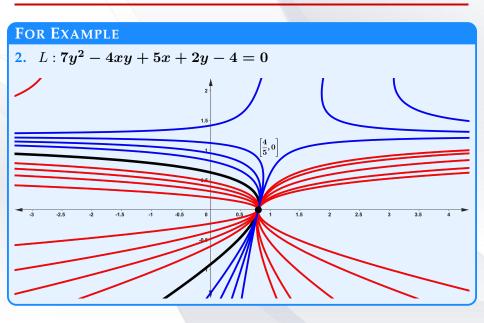
$$K_6: -\frac{1}{2}x^2 + 84y^2 - 4xy + 5x + 2y - 4 = 0,$$

THE COMMON POINTS: None

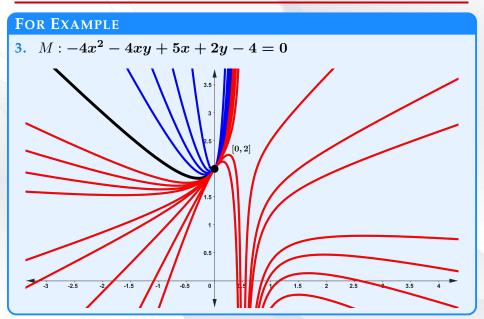
Intersection – Transtability with respect to x^2 and y^2



Intersection – Transtability with respect to x^2 and y^2



INTERSECTION – TRANSTABILITY WITH RESPECT TO x^2 AND y^2



Intersection – Transtability with respect to x^2 and xy

Consider two arbitrary transtable conic sections K and L with respect to x^2 and xy:

$$K : ax^{2} + by^{2} + cxy + dx + ey + f = 0,$$

$$L : (a \cdot k) x^{2} + by^{2} + \frac{c}{k} xy + dx + ey + f = 0.$$

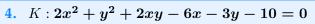
Then we obtain the **two** intersection points:

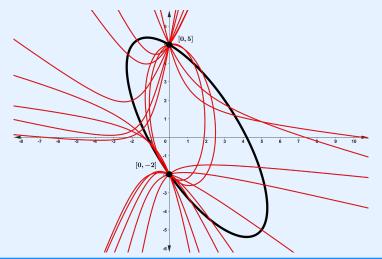
$$P_{1,2}^{x^2,xy} = [0,y],$$

where y is the root of the quadratic equation: $by^2 + ey + f = 0$. For a = 0, we get a **third** intersection:

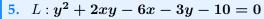
$$P_3^{x^2,xy} = \left[-\frac{f}{d}, 0 \right].$$

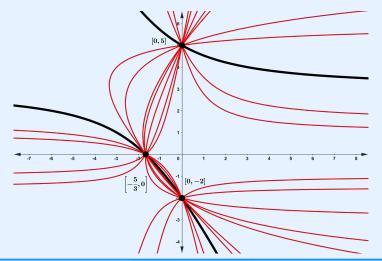
Intersection – Transtability with respect to x^2 and xy





Intersection – Transtability with respect to x^2 and xy





Intersection – Transtability with respect to x^2 and x

Consider two arbitrary transtable conic sections K and L with respect to x^2 and x:

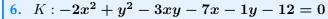
$$K : ax^{2} + by^{2} + cxy + dx + ey + f = 0,$$

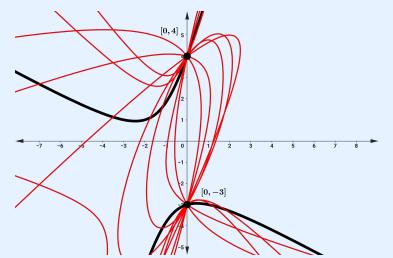
$$L : (a \cdot k) x^{2} + by^{2} + cxy + \frac{d}{k} x + ey + f = 0.$$

Then we obtain the **two** intersection points:

$$P_{1,2}^{x^2,x} = P_{1,2}^{x^2,xy}$$

INTERSECTION – TRANSTABILITY WITH RESPECT TO x^2 AND x





INTERSECTION – TRANSTABILITY WITH RESPECT TO x^2 AND y

Consider two arbitrary transtable conic sections K and L with respect to x^2 and y:

$$K : ax^{2} + by^{2} + cxy + dx + ey + f = 0,$$

$$L : (a \cdot k) x^{2} + by^{2} + cxy + dx + \frac{e}{k} y + f = 0.$$

In general **there are no intersections**. However, if we restrict some coefficients, we get:

1. The case a = 0 implies y = 0:

$$P_1^{x^2,y} = \left[-\frac{f}{d}, 0 \right]$$

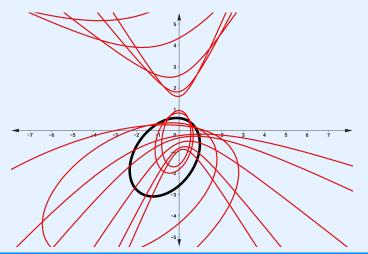
2. The case e = 0 implies x = 0:

$$P_{2,3}^{x^2,y} = [0,y],$$

where y is the root of the quadratic equation: $by^2 + f = 0$.

Intersection – Transtability with respect to x^2 and y





Consider two arbitrary transtable conic sections K and L with respect to x^2 and const:

$$K : ax^{2} + by^{2} + cxy + dx + ey + f = 0,$$

$$L : (a \cdot k) x^{2} + by^{2} + cxy + dx + ey + \frac{f}{k} = 0.$$

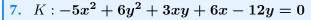
In general **there are no intersections**. However, if we restrict some coefficients, we get:

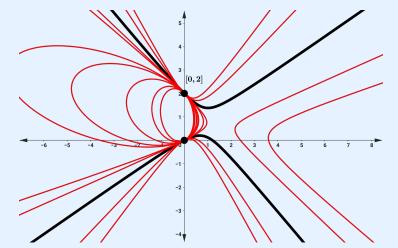
• The case f = 0 implies x = 0:

$$P_{1,2}^{x^2,const} = [0,y]$$

where y is the root of the quadratic equation: $by^2 + ey = 0$.

INTERSECTION – TRANSTABILITY WITH RESPECT TO x^2 AND const





INTERSECTION – TRANSTABILITY WITH RESPECT TO xy AND x

Consider two arbitrary transtable conic sections K and L with respect to xy and x:

$$\begin{split} K: ax^2 + by^2 + cxy + dx + ey + f &= 0, \\ L: ax^2 + by^2 + (c \cdot \mathbf{k}) \, xy + \frac{d}{\mathbf{k}} \, x + ey + f &= 0. \end{split}$$

Then we obtain the **two** intersection points:

$$P_{1,2}^{xy,x} = P_{1,2}^{x^2,xy}$$

If we restrict d = 0, we get:

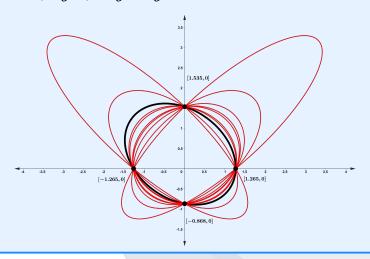
$$P_{3,4}^{xy,x} = P_{2,3}^{y^2,x} = [x,0]$$

where *x* is the root of the quadratic equation: $ax^2 + f = 0$.

Intersection – Transtability with respect to xy and x

FOR EXAMPLE

8. $K: 5x^2 + 6y^2 + 3xy - 4y - 8 = 0$



Consider two arbitrary transtable conic sections K and L with respect to xy and const:

$$K : ax^{2} + by^{2} + cxy + dx + ey + f = 0,$$

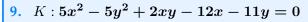
$$L : ax^{2} + by^{2} + (c \cdot \mathbf{k}) xy + dx + ey + \frac{f}{\mathbf{k}} = 0.$$

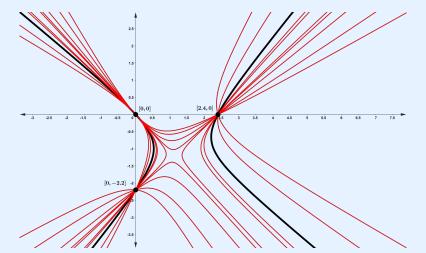
In general **there are no intersections**. However, if we restrict some coefficients, we get:

• The case f = 0 implies x = 0 or y = 0:

$$P_1^{xy,const} = \begin{bmatrix} 0, -\frac{e}{b} \end{bmatrix} \quad P_2^{xy,const} = \begin{bmatrix} -\frac{d}{a}, 0 \end{bmatrix} \quad P_3^{xy,const} = [0, 0]$$

INTERSECTION – TRANSTABILITY WITH RESPECT TO xy and const





INTERSECTION – TRANSTABILITY WITH RESPECT TO x AND y

Consider two arbitrary transtable conic sections K and L with respect to x and y:

$$K : ax^{2} + by^{2} + cxy + dx + ey + f = 0,$$

$$L : ax^{2} + by^{2} + cxy + (d \cdot \mathbf{k}) x + \frac{e}{\mathbf{k}} y + f = 0.$$

In general **there are no intersections**. However, if we restrict some coefficients, we get:

1. The case d = 0 implies:

$$P_{1,2}^{x,y} = [x,0],$$

where x is the root of the quadratic equation: $ax^2 + f = 0$.

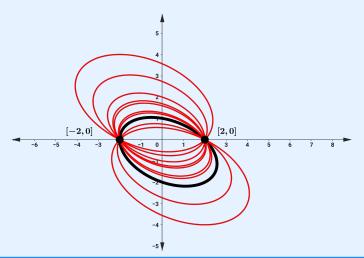
2. The case e = 0 implies:

$$P_{3,4}^{x,y} = [0,y],$$

where y is the root of the quadratic equation: $by^2 + f = 0$.

Intersection – Transtability with respect to x and y





Consider two arbitrary transtable conic sections K and L with respect to x and const:

$$K : ax^{2} + by^{2} + cxy + dx + ey + f = 0,$$

$$L : ax^{2} + by^{2} + cxy + (d \cdot \mathbf{k}) x + ey + \frac{f}{\mathbf{k}} = 0.$$

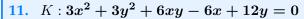
In general **there are no intersections**. However, if we restrict some coefficients, we get:

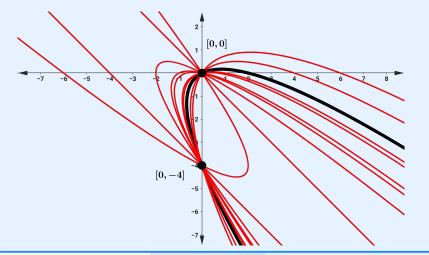
• The case f = 0 implies x = 0:

$$P_1^{x,const} = \begin{bmatrix} 0, -\frac{e}{b} \end{bmatrix} \quad P_2^{x,const} = [0, 0]$$

INTERSECTION – TRANSTABILITY WITH RESPECT TO x AND const

FOR EXAMPLE







CENTRE - PARTIALLY TRANSTABLE CONIC SECTIONS

LEMMA

If there is a centre C of a conic section $K : ax^2 + by^2 + cxy + dx + ey + f = 0$, then it is in the form:

$$C = \left[\frac{ce - 2bd}{4ab - c^2}; \frac{cd - 2ae}{4ab - c^2}\right].$$

THEOREM

The set of all centers of partially transstable conic sectios with respect to the given coefficients is a conic section except in the cases of partial transtabilities with respect to x^2 and xy or y^2 and xy or xy and x or xy and y, i.e. there are conic sectios of centers for the 11 partial transtabilities.

Proof:

The proof is divided into **15** parts, for each partial transtability. Consider a conic section in the form $ax^2 + by^2 + cxy + dx + ey + f = 0$. Then

CENTRE – TRANSTABILITY WITH RESPECT TO x^2 AND y^2

By complex calculations and verification using **GeoGebra** and **Wolfram Mathematica** software, we claim that the set of centres C_{x^2,y^2} is in the form:

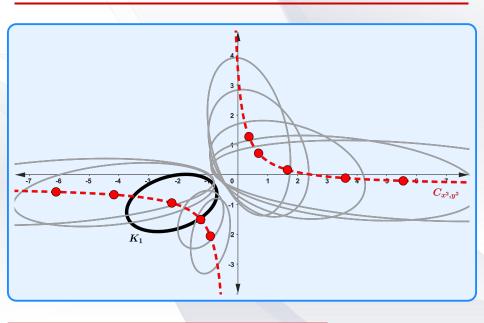
$$(c^2 - 4ab)xy + cdx + cey + de = 0.$$

FOR EXAMPLE

1.
$$K: 2x^2 + 3y^2 - 3xy - 6x + 9y - 9 = 0$$

$$C_{x^2,y^2}: -36xy - 14x - 10y + 35 = 0$$

CENTRE – TRANSTABILITY WITH RESPECT TO x^2 AND y^2

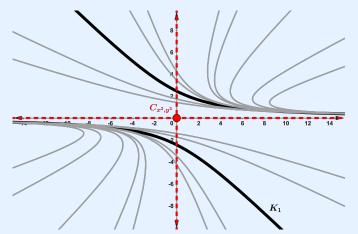


CENTRE – TRANSTABILITY WITH RESPECT TO x^2 AND y^2

FOR EXAMPLE

2. $L: y^2 + xy - 6 = 0$

The Conic Section of Centres: xy = 0



CENTRE – TRANSTABILITY WITH RESPECT TO x^2 AND xy

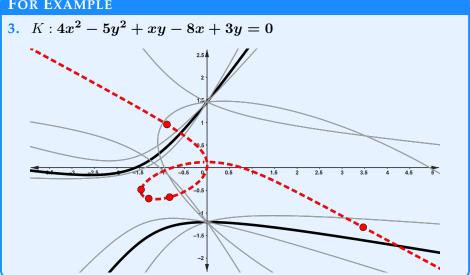
By complex calculations and verification using **GeoGebra** and **Wolfram Mathematica** software, we claim that the set of centres $C_{x^2,xy}$

does not form any conic section.

This set of centres is in the form of a "node".

CENTRE – TRANSTABILITY WITH RESPECT TO x^2 AND xy





CENTRE – TRANSTABILITY WITH RESPECT TO x^2 AND x

By complex calculations and verification using **GeoGebra** and **Wolfram Mathematica** software, we claim that the set of centres $C_{x^2,x}$ is in the form:

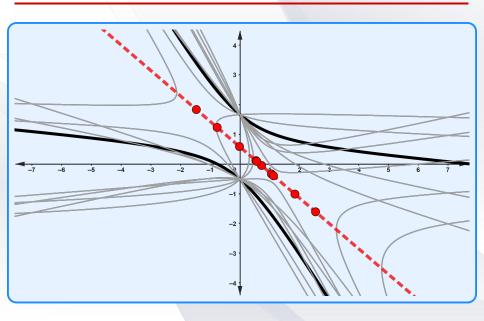
$$cx + 2by + e = 0.$$

FOR EXAMPLE

4.
$$K: x^2 + 7y^2 + 12xy - 7x - 8y - 6 = 0$$

$$C_{x^2,x}: \mathbf{12}x + \mathbf{14}y - \mathbf{8} = \mathbf{0}$$

CENTRE – TRANSTABILITY WITH RESPECT TO x^2 AND x



CENTRE – TRANSTABILITY WITH RESPECT TO x^2 AND y

By complex calculations and verification using **GeoGebra** and **Wolfram Mathematica** software, we claim that the set of centres $C_{x^2,y}$ is in the form:

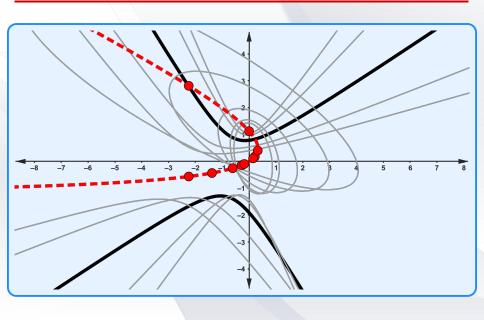
$$2bcy^{2} + c^{2}xy + (cd - 2ae)x + 2bdy = 0.$$

FOR EXAMPLE

5.
$$K: 9x^2 - 8y^2 - 8xy + 9x - 9y + 12 = 0$$

$$C_{x^2,y}$$
: $128y^2 + 64xy + 90x - 144y = 0$

CENTRE – TRANSTABILITY WITH RESPECT TO x^2 AND y



CENTRE – TRANSTABILITY WITH RESPECT TO x^2 AND const

By complex calculations and verification using **GeoGebra** and **Wolfram Mathematica** software, we claim that the set of centres $C_{x^2,const}$ is in the form:

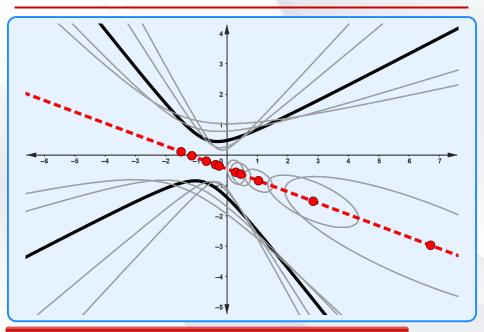
$$cx + 2by + e = 0$$
, i.e. $C_{x^2,const} = C_{x^2,x}$.

FOR EXAMPLE

6.
$$K: 8x^2 - 12y^2 - 9xy + 9x - 11y + 8 = 0$$

$$C_{x^2,const}$$
: $-9x - 24y - 11 = 0$

CENTRE – TRANSTABILITY WITH RESPECT TO x^2 AND const



CENTRE – TRANSTABILITY WITH RESPECT TO xy AND x

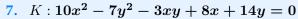
By complex calculations and verification using **GeoGebra** and **Wolfram Mathematica** software, we claim that the set of centres $C_{xy,x}$

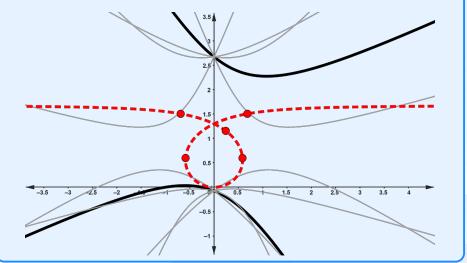
does not form any conic section.

This set of centres is in the form of a "node".

CENTRE – TRANSTABILITY WITH RESPECT TO xy and x

FOR EXAMPLE





CENTRE – TRANSTABILITY WITH RESPECT TO x AND y

By complex calculations and verification using **GeoGebra** and **Wolfram Mathematica** software, we claim that the set of centres $C_{x,y}$ is in the form:

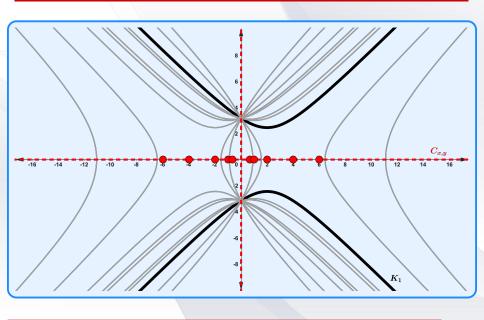
$$2acx^{2} + 2bcy^{2} + (c^{2} + 4ab)xy - de = 0.$$

FOR EXAMPLE

8.
$$K: -x^2 + y^2 + 4x - 10 = 0$$

$$C_{x,y}: -4xy = 0$$

CENTRE – TRANSTABILITY WITH RESPECT TO x AND y



CENTRE – TRANSTABILITY WITH RESPECT TO xy AND const

By complex calculations and verification using **GeoGebra** and **Wolfram Mathematica** software, we claim that the set of centres $C_{xy,const}$ is in the form:

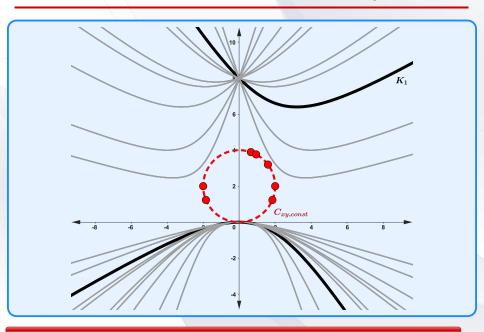
$$2ax^2 - 2by^2 + dx - ey = 0.$$

FOR EXAMPLE

9.
$$K: x^2 - y^2 - xy + 8y = 0$$

$$C_{xy,const}: 2x^2 + 2y^2 - 8y = 0.$$

CENTRE – TRANSTABILITY WITH RESPECT TO xy AND const



CENTRE – TRANSTABILITY WITH RESPECT TO x AND const

By complex calculations and verification using **GeoGebra** and **Wolfram Mathematica** software, we claim that the set of centres $C_{x,const}$ is in the form:

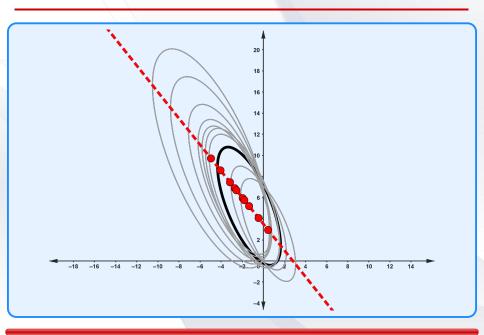
$$cx + 2by + e = 0$$
, i.e. $C_{x,const} = C_{x^2,x}$.

FOR EXAMPLE

10.
$$K: 7x^2 + 2y^2 + 5xy - 7x - 14y - 3 = 0$$

$$C_{x,const}: \mathbf{5x} + \mathbf{4y} - \mathbf{14} = \mathbf{0}$$

CENTRE – TRANSTABILITY WITH RESPECT TO x AND const



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