

On best approximations of matrix polynomials

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joint work with

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Ideal Arnoldi approximation problem

$$\min_{p \in \mathcal{M}_{m+1}} \|p(\mathbf{A})\| = \min_{p \in \mathcal{P}_m} \|\mathbf{A}^{m+1} - p(\mathbf{A})\|,$$

where \mathcal{M}_{m+1} is the class of **monic polynomials** of degree $m + 1$,
 \mathcal{P}_m is the class of polynomials of degree at most m .

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- Introduced in [Greenbaum and Trefethen, 1994], paper contains uniqueness result (\rightarrow story of the proof).
- The unique polynomial that solves the problem is called the $(m + 1)$ st **ideal Arnoldi polynomial** of \mathbf{A} , or the $(m + 1)$ st Chebyshev polynomial of \mathbf{A} .
- Some work on these polynomials in [Toh PhD thesis, 1996], [Toh and Trefethen, 1998], [Trefethen and Embree, 2005].

Matrix function best approximation problem

We consider the matrix approximation problem

$$\min_{p \in \mathcal{P}_m} \| f(\mathbf{A}) - p(\mathbf{A}) \|$$

$\| \cdot \|$ is the spectral norm (matrix 2-norm), $\mathbf{A} \in \mathbb{C}^{n \times n}$, f is analytic in neighborhood of \mathbf{A} 's spectrum.

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Well known: $f(\mathbf{A}) = p_f(\mathbf{A})$ for a polynomial p_f depending on values and possibly derivatives of f on \mathbf{A} 's spectrum.

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Does this problem have a unique solution $p_ \in \mathcal{P}_m$?*

- 1 General matrix approximation problems
- 2 Formulation of matrix polynomial approximation problems
- 3 Uniqueness results
- 4 Ideal Arnoldi versus ideal GMRES polynomials

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General matrix approximation problems

Given

- m linearly independent matrices $\mathbf{A}_1, \dots, \mathbf{A}_m \in \mathbb{C}^{n \times n}$,
- $\mathbb{A} \equiv \text{span} \{ \mathbf{A}_1, \dots, \mathbf{A}_m \}$,
- $\mathbf{B} \in \mathbb{C}^{n \times n} \setminus \mathbb{A}$,
- $\| \cdot \|$ is a matrix norm.

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This problem has a unique solution if $\| \cdot \|$ is strictly convex.

[see, e.g., Sreedharan, 1973]

Strictly convex norms

The norm $\|\cdot\|$ is **strictly convex** if for all \mathbf{X}, \mathbf{Y} ,

$$\|\mathbf{X}\| = \|\mathbf{Y}\| = 1, \quad \|\mathbf{X} + \mathbf{Y}\| = 2 \quad \Rightarrow \quad \mathbf{X} = \mathbf{Y}.$$

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Which matrix norms are strictly convex?

Let $\sigma_1 \geq \sigma_2 \geq \dots \geq \sigma_n$ be singular values of \mathbf{X} and $1 \leq p \leq \infty$.

The c_p -norm:
$$\|\mathbf{X}\|_p \equiv \left(\sum_{i=1}^n \sigma_i^p \right)^{1/p}.$$

- $p = 2$... Frobenius norm,
- $p = \infty$... spectral norm, matrix 2-norm, $\|\mathbf{X}\|_\infty = \sigma_1$,
- $p = 1$... trace (nuclear) norm.

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Theorem. If $1 < p < \infty$ then the c_p -norm is **strictly convex**.

[see, e.g., Ziętak, 1988]

Spectral norm (matrix 2-norm)

A useful matrix norm in many applications: [spectral norm](#)

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This norm **is not strictly convex**:

$$\mathbf{X} = \begin{bmatrix} \mathbf{I} & \\ & \varepsilon \end{bmatrix}, \quad \mathbf{Y} = \begin{bmatrix} \mathbf{I} & \\ & \delta \end{bmatrix}, \quad \varepsilon, \delta \in \langle 0, 1 \rangle.$$

Then we have, for each $\varepsilon, \delta \in \langle 0, 1 \rangle$,

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but if $\varepsilon \neq \delta$ then $\mathbf{X} \neq \mathbf{Y}$.

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but if $\varepsilon \neq \delta$ then $\mathbf{X} \neq \mathbf{Y}$.

Consequently: Best approximation problems in the spectral norm **are not guaranteed to have a unique solution**.

Matrix approximation problems in spectral norm

$$\min_{\mathbf{M} \in \mathbb{A}} \|\mathbf{B} - \mathbf{M}\| = \|\mathbf{B} - \mathbf{A}_*\|$$

$\mathbf{A}_* \in \mathbb{A}$ achieving the minimum is called a **spectral approximation** of \mathbf{B} from the subspace \mathbb{A} .

Open question: When does this problem have a unique solution?

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Zi̧tak's sufficient condition

Theorem [Zi̧tak, 1993]. If the residual matrix $\mathbf{B} - \mathbf{A}_*$ has an n -fold **maximal singular value**, then the spectral approximation \mathbf{A}_* of \mathbf{B} from the subspace \mathbb{A} is **unique**.

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Is this sufficient condition satisfied, e.g., for the ideal Arnoldi approximation problem?

General characterization of spectral approximations

General characterization by [Lau and Riha, 1981] and [Ziętak, 1993, 1996]
→ based on the [Singer's theorem](#) [Singer, 1970].

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Define $||| \cdot |||$ (trace norm, nuclear norm, c_1 -norm) and $\langle \cdot, \cdot \rangle$ by

$$|||\mathbf{X}||| = \sigma_1 + \cdots + \sigma_n, \quad \langle \mathbf{Z}, \mathbf{X} \rangle \equiv \text{tr}(\mathbf{Z}^* \mathbf{X}).$$

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Characterization: [Ziętak, 1996] $\mathbf{A}_* \in \mathbb{A}$ is a spectral approximation of \mathbf{B} from the subspace \mathbb{A} iff there exists $\mathbf{Z} \in \mathbb{C}^{n \times n}$, s.t.

$$|||\mathbf{Z}||| = 1, \quad \langle \mathbf{Z}, \mathbf{X} \rangle = 0, \quad \forall \mathbf{X} \in \mathbb{A},$$

and

$$\text{Re} \langle \mathbf{Z}, \mathbf{B} - \mathbf{A}_* \rangle = \|\mathbf{B} - \mathbf{A}_*\|.$$

Chebyshev polynomials of Jordan blocks

Theorem. Let \mathbf{J}_λ be the $n \times n$ Jordan block. Consider the ideal Arnoldi approximation problem

$$\min_{p \in \mathcal{M}_m} \|p(\mathbf{J}_\lambda)\| = \min_{\mathbf{M} \in \mathbb{A}} \|\mathbf{B} - \mathbf{M}\|,$$

where $\mathbf{B} = \mathbf{J}_\lambda^m$, $\mathbb{A} = \text{span}\{\mathbf{I}, \mathbf{J}_\lambda, \dots, \mathbf{J}_\lambda^{m-1}\}$. The minimum is attained by the polynomial $p_* = (z - \lambda)^m$ [Liesen and T., 2008].

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Proof. For $p = (z - \lambda)^m$, the residual matrix $\mathbf{B} - \mathbf{M}$ is given by

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Define $\mathbf{Z} \equiv e_1 e_{m+1}^T$. It holds that

$$\|\mathbf{Z}\| = 1, \quad \langle \mathbf{Z}, \mathbf{J}_\lambda^k \rangle = 0, \quad k = 0, \dots, m-1$$

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Zieta's sufficient condition

Theorem [Zieta, 1993]. If the residual matrix $\mathbf{B} - \mathbf{A}_*$ has an n -fold maximal singular value, then the spectral approximation \mathbf{A}_* of \mathbf{B} from the subspace \mathbb{A} is unique.

For the ideal Arnoldi approximation problem and the Jordan block \mathbf{J}_λ , we have shown that

$$\mathbf{B} - \mathbf{A}_* = \mathbf{J}_0^m.$$

One is $(n - m)$ -fold maximal singular value of $\mathbf{B} - \mathbf{A}_*$,
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The spectral approximation is unique [Greenbaum and Trefethen, 1994],
but, apparently, Zieta's sufficient condition is not satisfied!

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The problem and known results

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Known results

- If \mathbf{A} is **normal**, the problem reduces to the well studied scalar approximation problem on the spectrum of \mathbf{A} ,

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- For general \mathbf{A} - only a special case of $f(\mathbf{A}) = \mathbf{A}^{m+1}$ is known to have a unique solution [Greenbaum and Trefethen, 1994].

Reformulation of the problem

Let f be a polynomial of degree $m + \ell + 1$ ($m \geq 0$, $\ell \geq 0$). Then

$$f(z) = z^{m+1}g(z) + f_m z^m + \cdots + f_1 z + f_0,$$

where g is a polynomial of degree at most ℓ . Approximate f by p

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Without loss of generality we can consider the problem

$$\min_{h \in \mathcal{P}_m} \|\mathbf{A}^{m+1}g(\mathbf{A}) - h(\mathbf{A})\|,$$

where g is a given polynomial of degree at most ℓ .

Matrix polynomial approximation problems

We consider the problem

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Related problem:

$$\min_{g \in \mathcal{P}_\ell} \| \mathbf{A}^{m+1} g(\mathbf{A}) - h(\mathbf{A}) \|,$$

where h is a given polynomial of degree at most m .

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Matrix polynomial approx. problems - general notation

We consider matrix approximation problems of the form

$$\min_{\mathbf{M} \in \mathbb{A}} \|\mathbf{B} - \mathbf{M}\|.$$

1

$$\begin{aligned}\mathbf{B} &\equiv \mathbf{A}^{m+1}g(\mathbf{A}), & g \in \mathcal{P}_\ell \text{ given} \\ \mathbb{A} &\equiv \text{span}\{\mathbf{I}, \mathbf{A}, \dots, \mathbf{A}^m\},\end{aligned}$$

2

$$\begin{aligned}\mathbf{B} &\equiv h(\mathbf{A}), & h \in \mathcal{P}_m \text{ given} \\ \mathbb{A} &\equiv \text{span}\{\mathbf{A}^{m+1}, \mathbf{A}^{m+2}, \dots, \mathbf{A}^{m+\ell+1}\}.\end{aligned}$$

$\mathbf{B} \in \mathbb{C}^{n \times n} \setminus \mathbb{A}$ means that the minimum > 0 .

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Theorem [Liesen and T., 2008].

① Given $g \in \mathcal{P}_\ell$, the problem

$$\min_{h \in \mathcal{P}_m} \|\mathbf{A}^{m+1}g(\mathbf{A}) - h(\mathbf{A})\| > 0,$$

has the unique minimizer.

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- ② Let \mathbf{A} be nonsingular and $h \in \mathcal{P}_m$ given. Then the problem

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The nonsingularity in (2) cannot be omitted in general.

Idea of the proof (by contradiction)

Based on the proof by [\[Greenbaum and Trefethen, 1994\]](#).

Consider the problem

$$\min_{p \in \mathcal{G}_{\ell, m}^{(g)}} \|p(\mathbf{A})\|$$

where

$$\mathcal{G}_{\ell, m}^{(g)} \equiv \left\{ z^{m+1}g + h : g \in \mathcal{P}_{\ell} \text{ is given, } h \in \mathcal{P}_m \right\}.$$

Let q_1 and q_2 be two different solutions, $\|q_1(\mathbf{A})\| = \|q_2(\mathbf{A})\| = C$.

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Use q_1 and q_2 to construct the polynomial

$$q_\epsilon = (1 - \epsilon)q + \epsilon\tilde{q} \in \mathcal{G}_{\ell, m}^{(g)}$$

and show that, for sufficiently small ϵ ,

$$\|q_\epsilon(\mathbf{A})\| < C.$$

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Ideal Arnoldi versus ideal GMRES polynomials

Ideal Arnoldi and ideal GMRES problems

$$\min_{p \in \mathcal{M}_m} \|p(\mathbf{A})\|, \quad \min_{p \in \pi_m} \|p(\mathbf{A})\|.$$

The ideal Arnoldi polynomial is $(z - \lambda)^m$ [Liesen and T., 2008].

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For $\lambda \neq 0$, we can write

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$(1 - \lambda^{-1}z)^m$ is a candidate for solving ideal GMRES problem.

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No! Determination of ideal GMRES polynomials for \mathbf{J}_λ is very complicated and intriguing problem [T., Liesen and Faber, 2007].

Ideal Arnoldi and ideal GMRES polynomials for \mathbf{J}_λ

Theorem [T., Liesen and Faber, 2007]. The m th ideal GMRES polynomial is $(1 - \lambda^{-1}z)^m$ iff $0 \leq m < \frac{n}{2}$ and $|\lambda| \geq \varrho_{m,n-m}^{-1}$.

$\varrho_{k,n}$ is the radius of the polynomial numerical hull of degree k of an $n \times n$ Jordan block (independent of λ).

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Obviously, neither 1 nor the above polynomial are scalar multiples of the corresponding ideal Arnoldi polynomial.

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have a unique solution?

Related paper

- J. Liesen and P. Tichý, [On best approximations of polynomials in matrices in the matrix 2-norm, submitted, June 2008.]
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More details can be found at

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