Lipid rafts on cell membranes: modeling and analysis

Andrea POIATTI

andrea.poiatti@univie.ac.at

UNIVERSITY OF VIENNA

FWF ESPRIT GRANT N. ESP 552

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• Biological applications

2 Mathematical models for prescribed surface evolution

- Evolving surface setting
- Binary fluids on evolving surfaces



Biological applications

Cell membranes and lipid rafts

- Eukaryotic cell membranes consist of a heterogeneous but regulated environment serving as a dynamic platform for cell functions
- Membrane heterogeneity includes discrete membrane domains:
 Lipid rafts

Cholesterol associations with membrane lipids like sphingolipids



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(Morales-Penningston et al., 2010)

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Cell membranes and lipid rafts

- Lipid rafts believed to play an essential role in the regulation of protein activity
- Known to be central to the replication of some viruses like HIV
- Liquid ordered phase VS liquid disordered phase:

Liquid-Liquid Phase Separation on the cell membrane



Biological applications

The domain of the model equations

- **Changing cell shape** is crucial for the proper function of cellular processes, including **cell migration** (e.g., lymphocytes and stem cells)
- Lipid rafts formation changes the shape of the cell membranes: the shape depends on local inhomogeneities within the membrane



evolving surfaces embedded in ${\mathbb R}$



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Essential to consider

evolving surfaces embedded in \mathbb{R}^3

Evolving surface setting Binary fluids on evolving surfaces

The evolving surface setting

- $t \in [0, T]$, T > 0, evolving time
- Γ_0 : initial **closed** surface of a (regular) liposome, diameter 10 μ m
- $\Phi: [0, T] \times \Gamma_0 \to \mathbb{R}^3$, a sufficiently smooth flow map characterizing the evolution of Γ_0
- $\Gamma(t) := \Phi(t, \cdot)$ so that $\Phi^0_t := \Phi(t, \cdot) : \Gamma_0 \to \Gamma(t)$
- V_n : normal velocity field s.t., for any $t \in [0, T]$, for any $x \in \Gamma_0$,

$$\frac{d}{dt}\Phi_t^0(x) = \mathbf{V}_n(t,\Phi_t^0(x))$$

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A phase-field model for binary fluids on evolving surfaces

- φ ∈ [−1, 1]: relative concentration difference between the ordered and disordered phases (diffuse interface)
- We consider

 $\mu := -\Delta_{\Gamma(t)} \varphi + \Psi'(\varphi),$ chemical potential

✓ Ψ: Flory Huggins free energy density (potential), $0 < \theta < \theta_0$ $\Psi(\varphi) = \underbrace{\frac{\theta}{2}((1+\varphi)\ln(1+\varphi) + (1-\varphi)\ln(1-\varphi))}_{F(\varphi): \text{ convex and logarithmic}} - \frac{\theta_0}{2}\varphi^2$

• $\partial^{\circ} \varphi$ normal material time derivative

Evolving surface setting Binary fluids on evolving surfaces

A phase-field model for binary fluids on evolving surfaces

- Introduce a model for u as tangential fluid velocity
- Incompressible two-phase fluid: for any $t \in [0, T]$

$$\operatorname{div}_{\Gamma(t)}(\underbrace{\mathbf{V}_{n}+\mathbf{u}}_{\text{Total fluid velocity}}) \equiv 0 \quad \text{ on } \Gamma(t)$$

• This also entails inextensible material surface assumption:

$$\int_{\Gamma(t)} \operatorname{div}_{\Gamma(t)} \mathbf{V}_{\mathbf{n}} = \int_{\Gamma(t)} H(\mathbf{V}_{\mathbf{n}} \cdot \mathbf{n}) = 0$$

- Unmatched fluid viscosities $\nu = \nu(\varphi)$ and densities $\rho = \rho(\varphi)$
- Thermodynamically consistent model following avsimular derivation as in Abels-Garcke-Grün (2012)

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Binary fluids on evolving surfaces: the model

- P(x, t): normal projector on the tangential space at $x \in \Gamma(t)$
- $\nabla_{\Gamma(t)} \mathbf{u}$: covariant derivative of \mathbf{u}
- Introduce:

 $v_{\mathbf{n}} := \mathbf{V}_{\mathbf{n}} \cdot \mathbf{n}, \quad \mathbf{H} := \nabla_{\Gamma(t)} \mathbf{n},$ $H := \text{tr } \mathbf{H} \implies \text{double mean curvature}$ $\mathbf{J}_{\rho} = -\frac{\rho_1 - \rho_2}{2} \nabla_{\Gamma(t)}^{T} \mu \implies \text{extra flux term}$

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Binary fluids on evolving surfaces: the model

- Assuming that the velocity V_n is a priori prescribed, consider only the projected equation for u
- Find (\mathbf{u}, p, φ) such that, for any $(x, t) \in \bigcup_{t \in [0, T]} \Gamma(t) \times \{t\}$,

$$\begin{split} \rho \mathbf{P} \partial^{\circ} \mathbf{u} &+ ((\rho \mathbf{u} + \mathbf{J}_{\rho}) \cdot \nabla_{\Gamma(t)}) \mathbf{u} + \rho \mathbf{v_{n}} \mathbf{H} \mathbf{u} + \mathbf{v_{n}} \mathbf{H} \mathbf{J}_{\rho} \\ &- 2 \mathbf{P} \operatorname{div}_{\Gamma(t)}(\nu(\varphi) \mathcal{E}_{\mathcal{S}}(\mathbf{u})) + \nabla_{\Gamma(t)} \rho \\ &= - \mathbf{P} \operatorname{div}_{\Gamma(t)}(\nabla_{\Gamma(t)} \varphi \otimes \nabla_{\Gamma(t)} \varphi) + 2 \mathbf{P} \operatorname{div}_{\Gamma(t)}(\nu(\varphi) \mathbf{v_{n}} \mathbf{H}) + \frac{\rho}{2} \nabla_{\Gamma(t)}(\mathbf{v_{n}})^{2}, \\ &\operatorname{div}_{\Gamma(t)} \mathbf{u} = -\operatorname{div}_{\Gamma(t)} \mathbf{V_{n}} = - \mathbf{H} \mathbf{v_{n}}, \end{split}$$

$$\begin{split} \partial^{\circ}\varphi + \mathbf{u} \cdot \nabla_{\Gamma(t)}\varphi &= \Delta_{\Gamma(t)}\mu, \\ \mu &= -\Delta_{\Gamma(t)}\varphi + \Psi'(\varphi), \\ \mathbf{u}(0) &= \mathbf{u}_0, \quad \varphi(0) = \varphi_0 \end{split}$$



Evolving surface setting Binary fluids on evolving surfaces

Main result (Abels-Garcke-P., 2024)

- Assume V_n and (u_0, φ_0) sufficiently regular
- Well-posedness of global strong solutions on [0, T] such that

$$\begin{split} \mathbf{u} &\in L^{\infty}_{\mathbf{L}^{2}} \cap L^{2}_{\mathbf{H}^{2}} \cap H^{1}_{\mathbf{L}^{2}}, \quad p \in L^{2}_{H^{1}}, \\ \varphi &\in L^{\infty}_{H^{3}} \cap L^{2}_{H^{4}} \cap H^{1}_{H^{1}}, \\ |\varphi| &< 1 \quad \text{a.e. in } \Gamma(t) \quad \text{for a.a. } t \in [0, T], \\ \mu &\in L^{\infty}_{H^{1}} \cap L^{2}_{H^{3}} \cap H^{1}_{H^{-1}}, \end{split}$$

• Instantaneous strict separation property:

$$\exists \delta > 0: \sup_{t \in [0,T]} \|\varphi\|_{L^{\infty}(\Gamma(t))} \leq 1 - \delta$$

Questions: minimal assumptions on Ψ to get separation?
Do we need φ_0 strictly separated?

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Evolving surface setting Binary fluids on evolving surfaces

Classical approach: Moser-Trudinger (MT) inequality

We assume as in the logarithmic potential:

$$F''(s) \leq C e^{C|F'(s)|}, \qquad orall s \in (-1,1)$$

Variant of Moser-Trudinger inequality on Γ_0 (Fontana, 1993)

It holds:

$$\int_{\Gamma_0} e^{|f|} \leq C(\Gamma_0) e^{C ||f||_{H^1(\Gamma_0)}^2}, \qquad \forall f \in H^1(\Gamma_0),$$

• Use this inequality on the pullback of $F''(\varphi)$ on Γ_0 to get $F''(\varphi) \in L^{\infty}_{L^p}, \quad \forall p \in [2, \infty)$

© Strict separation property holds (Caetano-Elliott-Grasselli-P.,2023)

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An alternative to MT inequality: De Giorgi iterations

• New assumption (Gal & P., 2024): as $\delta \rightarrow 0^+$

$$\exists \gamma > \frac{1}{2}: \quad \frac{1}{F'(1-2\delta)} = O\left(\frac{1}{|\ln(\delta)|^{\gamma}}\right), \quad \frac{1}{|F'(-1+2\delta)|} = O\left(\frac{1}{|\ln(\delta)|^{\gamma}}\right)$$

✓ Use of **De Giorgi iteration** scheme for the **elliptic equation**:

$$\mu(t) = -\Delta_{\Gamma(t)}\varphi(t) + \Psi'(\varphi(t))$$

✓ More geometric approach to obtain

 $\exists \delta > 0: |\varphi(x,t)| \leq 1-\delta, \text{ for all } (x,t) \in \bigcup_{\substack{r \in \mathcal{L}, r \in \mathcal{L}, r \in \mathcal{L}}} |\varphi(x,t)| \leq 1-\delta, \text{ for all } (x,t) \in \bigcup_{\substack{r \in \mathcal{L}, r \in \mathcal{L}, r \in \mathcal{L}, r \in \mathcal{L}}} |\varphi(x,t)| \leq 1-\delta, \text{ for all } (x,t) \in \bigcup_{\substack{r \in \mathcal{L}, r \in \mathcal{L}, r \in \mathcal{L}, r \in \mathcal{L}}} |\varphi(x,t)| \leq 1-\delta, \text{ for all } (x,t) \in \bigcup_{\substack{r \in \mathcal{L}, r \in \mathcal{L}, r \in \mathcal{L}, r \in \mathcal{L}}} |\varphi(x,t)| \leq 1-\delta, \text{ for all } (x,t) \in \bigcup_{\substack{r \in \mathcal{L}, r \in \mathcal{L}, r \in \mathcal{L}, r \in \mathcal{L}}} |\varphi(x,t)| \leq 1-\delta, \text{ for all } (x,t) \in \bigcup_{\substack{r \in \mathcal{L}, r \in \mathcal{L}, r \in \mathcal{L}, r \in \mathcal{L}}} |\varphi(x,t)| \leq 1-\delta, \text{ for all } (x,t) \in \bigcup_{\substack{r \in \mathcal{L}, r \in \mathcal{L}, r \in \mathcal{L}, r \in \mathcal{L}}} |\varphi(x,t)| \leq 1-\delta, \text{ for all } (x,t) \in \bigcup_{\substack{r \in \mathcal{L}, r \in \mathcal{L}, r \in \mathcal{L}}} |\varphi(x,t)| \leq 1-\delta, \text{ for all } (x,t) \in \bigcup_{\substack{r \in \mathcal{L}, r \in \mathcal{L}, r \in \mathcal{L}}} |\varphi(x,t)| \leq 1-\delta, \text{ for all } (x,t) \in \bigcup_{\substack{r \in \mathcal{L}, r \in \mathcal{L}, r \in \mathcal{L}}} |\varphi(x,t)| \leq 1-\delta, \text{ for all } (x,t) \in \bigcup_{\substack{r \in \mathcal{L}, r \in \mathcal{L}, r \in \mathcal{L}}} |\varphi(x,t)| \leq 1-\delta, \text{ for all } (x,t) \in \bigcup_{\substack{r \in \mathcal{L}, r \in \mathcal{L}, r \in \mathcal{L}}} |\varphi(x,t)| \leq 1-\delta, \text{ for all } (x,t) \in \bigcup_{\substack{r \in \mathcal{L}, r \in \mathcal{L}, r \in \mathcal{L}}} |\varphi(x,t)| \leq 1-\delta, \text{ for all } (x,t) \in \bigcup_{\substack{r \in \mathcal{L}, r \in \mathcal{L}}} |\varphi(x,t)| \leq 1-\delta, \text{ for all } (x,t) \in \bigcup_{\substack{r \in \mathcal{L}, r \in \mathcal{L}}} |\varphi(x,t)| \leq 1-\delta, \text{ for all } (x,t) \in \bigcup_{\substack{r \in \mathcal{L}, r \in \mathcal{L}}} |\varphi(x,t)| \leq 1-\delta, \text{ for all } (x,t) \in \bigcup_{\substack{r \in \mathcal{L}, r \in \mathcal{L}}} |\varphi(x,t)| \leq 1-\delta, \text{ for all } (x,t) \in \bigcup_{\substack{r \in \mathcal{L}, r \in \mathcal{L}}} |\varphi(x,t)| \leq 1-\delta, \text{ for all } (x,t) \in \bigcup_{\substack{r \in \mathcal{L}, r \in \mathbb{L}}} |\varphi(x,t)| \leq 1-\delta, \text{ for all } (x,t) \in \bigcup_{\substack{r \in \mathcal{L}, r \in \mathbb{L}}} |\varphi(x,t)| \leq 1-\delta, \text{ for all } (x,t) \in \bigcup_{\substack{r \in \mathcal{L}, r \in \mathbb{L}} |\varphi(x,t)| \leq 1-\delta, \text{ for all } (x,t) \in \bigcup_{\substack{r \in \mathcal{L}} |\varphi(x,t)| \leq 1-\delta, \text{ for all } (x,t) \in \bigcup_{\substack{r \in \mathcal{L}, r \in \mathbb{L}} |\varphi(x,t)| \leq 1-\delta, \text{ for all } (x,t) \in \bigcup_{\substack{r \in \mathcal{L}, r \in \bigcup_{\substack{r \in \mathcal{L}} |\varphi(x,t)| \leq 1-\delta, \text{ for all } (x,t) \in \bigcup_{\substack{r \in \mathcal{L}, r \in \bigcup_{\substack{r \in \mathcal{L}} |\varphi(x,t)| \leq 1-\delta, \text{ for all } (x,t) \in \bigcup_{\substack{r \in \mathcal{L}, r \in \bigcup_{\substack{r \in \mathcal{L}, r \in \bigcup_{\substack{r \in \mathbb{L}} |\varphi(x,t)| \leq 1-\delta, \text{ for all } (x,t) \in \bigcup_{\substack{r \in \mathcal{L}, r \in \bigcup_{\substack{r \in \bigcup_{\substack{r \in \mathcal{L}, r \in \bigcup_{\substack{r \in \mathbb{L}} |\varphi(x,t)| < 1-\delta, \text{ for all } (x,t) \in \bigcup_{\substack{r \in \bigcup_{\substack{r \in \bigcup_{\substack{r \in \bigcup_{\substack{r \in \bigcup_{\substack{$

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Evolving surface setting Binary fluids on evolving surfaces

Strict separation of the initial datum φ_0

• Regularity assumptions to get strong solutions:

$$arphi_{\mathsf{0}}\in \mathsf{H}^2(\mathsf{\Gamma}_{\mathsf{0}}), \quad |arphi_{\mathsf{0}}|\leq 1, \quad -1<rac{\int_{\mathsf{\Gamma}_{\mathsf{0}}}arphi_{\mathsf{0}}}{|\mathsf{\Gamma}_{\mathsf{0}}|}<1,$$

$$\mu_0 := -\Delta_{\Gamma_0} \varphi_0 + \Psi'(\varphi_0) \in H^1(\Gamma_0)$$

- Repeat the De Giorgi's iteration scheme on μ₀
- We can prove that φ_0 is **automatically strictly separated**, i.e.,

 $\exists \delta_0 \in (0,1): \quad \|arphi_0\|_{L^\infty(\Gamma_0)} \leq 1$,

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- **Repeat** the **De Giorgi**'s iteration scheme on μ_0
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Perspectives

Further developments

- A priori given normal velocity V_n:
 - Extension to multi-component phase-field models
 - Applications to **optimal control** problems
- Not a priori given velocity:
 - Geometric evolution is part of the problem
 - Navier-Stokes systems (Jankuhn et al., 2018) for inextensible viscous materials:

$$\begin{cases} \partial^{\bullet} \mathbf{v} = -\nabla_{\Gamma(t)} \pi + 2\nu \operatorname{div}_{\Gamma(t)} \mathcal{E}_{S}(\mathbf{v}) + \pi H \mathbf{n}, \\ \operatorname{div}_{\Gamma(t)} \mathbf{v} = 0, \quad \mathbf{v}_{n} = \mathbf{v} \cdot \mathbf{n} \end{cases}$$

with v velocity field of the flow on $\Gamma(t)$ and ∂^{\bullet} material time rsitiat derivative with respect to v \implies Not enough regularity to close the estimates for v_n due to the coupling with π

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 \implies regularizing elastic term $-\Delta_{\Gamma(t)}H$ in the equation for v_n

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Short-time Existence of strong solutions Versität (Abels-Liu-P., 2025)

Perspectives

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- Possible couplings with bulk Navier-Stokes equations and/or surface Cahn-Hilliard equations
 - Strong solutions can in general only be local in time
 - From local-in-time to **global-in-time**:

e.g. (De Giorgi-type) varifold solutions

Navier-Stokes-Mullins-Sekerka flow (Abels-P., 2029

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 - Weak-strong uniqueness results



Thanks for your attention!



(Morales-Penningston et al., 2010)



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Thanks for your attention!



(Morales-Penningston et al., 2010)



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Navier-Stokes on elastic membranes

$$\begin{cases} \rho \mathbf{P} \partial^{\bullet} \mathbf{v} \\ = -\nabla_{\Gamma} \pi + \mu (\Delta_{\Gamma} \mathbf{v} + K \mathbf{v} + \nabla_{\Gamma} (v_{n} H) - 2(H \mathbf{P} - \mathbf{H}) \nabla_{\Gamma} v_{n}) - \rho v_{n} \cdot \partial^{\bullet} \mathbf{n} \\ \rho \partial^{\bullet} v_{n} = -2\mu (\operatorname{tr} (\mathbf{H} \nabla_{\Gamma} \mathbf{v}) + v_{n} \operatorname{tr} (\mathbf{H}^{2})) + \pi H + \rho \partial^{\bullet} \mathbf{n} \cdot \mathbf{v} \\ + C_{H} (\Delta_{\Gamma} H + H(H^{2}/2 - 2K) + H_{0}(2K - HH_{0}/2)) \\ \operatorname{div}_{\Gamma} \mathbf{v} = -v_{n} H \\ \partial^{\bullet} \rho = 0 \end{cases}$$

where $\mathbf{H} = \nabla_{\Gamma} \mathbf{n}$, K is the **Gauß curvature**, H_0 , K_0 are **positive constants**, and the **velocity** of the material surface is $\mathbf{v} + v_n \mathbf{n}$

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Cahn-Hilliard and Navier-Stokes on evolving surfaces

A priori prescribed evolution of the surface: weak solutions

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