On variational approaches to mixtures Prague, 5-7 February, Mixtures: Modeling, analysis and computing

Ilya Peshkov, Evgeniy Romenski, Michal Pavelka

ilya.peshkov@unitn.it University of Trento

February 6, 2025



医水黄医水黄

1 Introduction

2 Variational Formulation

ъ

590

・ロト ・御 ト ・ ヨト ・ ヨト



ъ

590

・ロト ・御 ト ・ ヨト ・ ヨト

What is a mixture?

Classical mixtures

Mixture control volume



February 6, 2025 4 / 13

ъ

・ロト ・ 同 ト ・ ヨ ト ・ ヨ ト

What is a mixture?

- Classical mixtures
- ② "Immiscible" mixtures

Mixture control volume



 $\alpha_a = \frac{v_a}{V}$ volume fraction of *a*-th phase $c_a = \frac{\rho_a}{\rho}$ mass fraction of *a*-th phase

э

• • = • • = •

What is a mixture?

- Classical mixtures
- **2** "Immiscible" mixtures

A three-phase flows



Mixture control volume



 $\alpha_a = \frac{v_a}{V}$ volume fraction of *a*-th phase $c_a = \frac{\varrho_a}{\rho}$ mass fraction of *a*-th phase

On variational approaches to mixtures

(日)

First principle approaches to mixtures

Multiphysics problems: multispicies plasmas, poroelasticity, granular flows, surface tension, mixtures + electrodynamics, dispersive solids (metamaterials), etc.

We need to rely on **first principle** approaches:

First principle approaches to mixtures

Multiphysics problems: multispicies plasmas, poroelasticity, granular flows, surface tension, mixtures + electrodynamics, dispersive solids (metamaterials), etc.

We need to rely on **first principle** approaches:

1 Homogenization/averaging techniques

$$\rho_{\alpha} = m_{\alpha} \int f_{\alpha} \, \mathrm{d} c_{\alpha}$$
$$\rho_{\alpha} u_{i}^{(\alpha)} = m_{\alpha} \int C_{i}^{(\alpha)} f_{\alpha} \, \mathrm{d} c_{\alpha}$$

Multiphysics problems: multispicies plasmas, poroelasticity, granular flows, surface tension, mixtures + electrodynamics, dispersive solids (metamaterials), etc.

We need to rely on **first principle** approaches:

1 Homogenization/averaging techniques

$$\rho_{\alpha} = m_{\alpha} \int f_{\alpha} \, \mathrm{d} \boldsymbol{c}_{\alpha}$$
$$\rho_{\alpha} u_{i}^{(\alpha)} = m_{\alpha} \int C_{i}^{(\alpha)} f_{\alpha} \, \mathrm{d} \boldsymbol{c}_{\alpha}$$

~

2 Energetic appoaches (Variational/Hamiltonian formulation)

$$S[\varphi] = \int L(\varphi, \dot{\varphi}, \nabla \varphi) d\mathbf{x} dt$$
$$\mathcal{H} = \mathcal{H}(\mathbf{p}, \mathbf{q}) \qquad \{A, B\} = \int A_{\mathbf{p}} \cdot B_{\mathbf{q}} - A_{\mathbf{q}} \cdot B_{\mathbf{p}} d\mathbf{x}$$

First principle approaches to mixtures

Multiphysics problems: multispicies plasmas, poroelasticity, granular flows, surface tension, mixtures + electrodynamics, dispersive solids (metamaterials), etc.

We need to rely on **first principle** approaches:

1 Homogenization/averaging techniques

$$\rho_{\alpha} = m_{\alpha} \int f_{\alpha} \, \mathrm{d} \boldsymbol{c}_{\alpha}$$
$$\rho_{\alpha} u_{i}^{(\alpha)} = m_{\alpha} \int C_{i}^{(\alpha)} f_{\alpha} \, \mathrm{d} \boldsymbol{c}_{\alpha}$$

0

2 Energetic appoaches (Variational/Hamiltonian formulation)

$$S[\varphi] = \int L(\varphi, \dot{\varphi}, \nabla \varphi) d\mathbf{x} dt$$
$$\mathcal{H} = \mathcal{H}(\mathbf{p}, \mathbf{q}) \qquad \{A, B\} = \int A_{\mathbf{p}} \cdot B_{\mathbf{q}} - A_{\mathbf{q}} \cdot B_{\mathbf{p}} d\mathbf{x}$$

$$E = \varepsilon(\rho, s) + \ldots + \frac{c^2}{2}A^2 + \ldots + \frac{1}{2}\nu^2$$

micro meso macro

Introduction 0000

and

UniTn

6 / 13

February 6, 2025

Moments method for gas mixtures (Gupta, Torrilhon, 2015, 10.1098/rspa.2014.0754)

$$\frac{Dm_{ijk}}{Dt} + m_{ijk}^{(\alpha)} \frac{\partial v_l}{\partial x_l} + \frac{\partial u_{ijkl}}{\partial x_l} + \frac{3}{7} \frac{\partial u_{(ij}}{\partial x_{k})} + 3m_{l\langle ij}^{(\alpha)} \frac{\partial v_k}{\partial x_l} + \frac{12}{5} q_{\langle i}^{(\alpha)} \frac{\partial v_k}{\partial x_j} + 3\sigma_{\langle ij}^{(\alpha)} \frac{\partial v_k}{\partial x_j} + 3\sigma_{\langle ij}^{(\alpha)} \frac{Dv_{k}}{Dt} - F_{k\rangle}^{(\alpha)} \right) = \mathcal{P}_{ijk}^{0(\alpha)}, \qquad (3.8)$$

$$\frac{Du_{ij}^{1(\alpha)}}{Dt} + u_{ij}^{1(\alpha)} \frac{\partial v_k}{\partial x_k} + \frac{\partial u_{ijk}^{1(\alpha)}}{\partial x_k} + \frac{2}{5} \frac{\partial u_{\langle i}^{2(\alpha)}}{\partial x_{j}} + 2u_{ijkl}^{0(\alpha)} \frac{\partial v_k}{\partial x_l} + \frac{6}{7} u_{\langle ij}^{1(\alpha)} \frac{\partial v_k}{\partial x_k} + \frac{4}{5} u_{k(i}^{1(\alpha)} \frac{\partial v_k}{\partial x_j} + \frac{14}{5} \Delta_{\alpha} \frac{\partial v_{\langle i}}{\partial x_{j}} + 14\rho_{\alpha}\theta_{\alpha}^2 \frac{\partial v_{\langle i}}{\partial x_{j}} + 2m_{ijk}^{(\alpha)} \left(\frac{Dv_k}{Dt} - F_k^{(\alpha)} \right) + \frac{28}{5} q_{\langle i}^{(\alpha)} \left(\frac{Dv_{j}}{Dt} - F_{j}^{(\alpha)} \right) = \mathcal{P}_{ij}^{1(\alpha)}, \qquad (3.9)$$

$$\frac{D\Delta_{\alpha}}{Dt} + \frac{7}{3} \Delta_{\alpha} \frac{\partial v_i}{\partial x_i} + \frac{\partial u_{i}^{2(\alpha)}}{\partial x_i} - 20\theta_{\alpha}\sigma_{ij}^{(\alpha)} \frac{\partial v_i}{\partial x_j} - 20\theta_{\alpha} \frac{\partial q_i^{(\alpha)}}{\partial x_i} + 15\rho_{\alpha}\theta_{\alpha}^2 \frac{\partial u_i^{(\alpha)}}{\partial x_i} + \frac{15\rho_{\alpha}\theta_{\alpha}^2}{\partial x_i} \frac{\partial u_i^{(\alpha)}}{\partial x_i} + 15\rho_{\alpha}\theta_{\alpha}^2 \frac{\partial u_i^{(\alpha)}}{\partial x_i} + 2m_{ij}^{(\alpha)} \frac{\partial v_i}{\partial x_i} + 8\left(q_i^{(\alpha)} - \frac{5}{2}\rho_{\alpha}\theta_{\alpha}u_i^{(\alpha)}\right) \left(\frac{Dv_i}{Dt} - F_i^{(\alpha)}\right)$$

$$(3.9)$$

$$(3.9)$$

On variational approaches to mixtures

1 Introduction

2 Variational Formulation

ъ

590

・ロト ・御 ト ・ ヨト ・ ヨト

Why variational formulation for mixtures (Stationary Action Principle)?

Many classical theories admit it:

Why variational formulation for mixtures (Stationary Action Principle)?

Many classical theories admit it:

General Relativity

Why variational formulation for mixtures (Stationary Action Principle)?

Many classical theories admit it:

- General Relativity
- 2 Electrodynamics

Why variational formulation for mixtures (Stationary Action Principle)?

Many classical theories admit it:

- General Relativity
- 2 Electrodynamics
- **3** Fluid and Solid mechanics

Why it's difficult?

$$S[\varphi] = \int L(\varphi, \dot{\varphi}, \nabla \varphi) d\mathbf{x} dt \longrightarrow \text{PDE:} \qquad \frac{\partial L_{\dot{\varphi}}}{\partial t} + \nabla \cdot L_{\nabla \varphi} = L_{\varphi} \text{ (Euler-Lagrange)}$$

Baer-Nunziato-type models:

$$\frac{\partial \boldsymbol{u}_a}{\partial t} + \nabla \cdot \left(\boldsymbol{u}_a \otimes \boldsymbol{v}_a + p_a \boldsymbol{I} \right) = \sum_{b=1}^N p_{I,ab} \nabla \alpha_b$$

э

590

イロト イポト イヨト イヨト

Why it's difficult?

$$S[\varphi] = \int L(\varphi, \dot{\varphi}, \nabla \varphi) d\mathbf{x} dt \longrightarrow \text{PDE:} \qquad \frac{\partial L_{\dot{\varphi}}}{\partial t} + \nabla \cdot L_{\nabla \varphi} = L_{\varphi} \text{ (Euler-Lagrange)}$$

Baer-Nunziato-type models:

$$\frac{\partial \boldsymbol{u}_a}{\partial t} + \nabla \cdot \left(\boldsymbol{u}_a \otimes \boldsymbol{v}_a + p_a \boldsymbol{I} \right) = \sum_{b=1}^N p_{I,ab} \nabla \alpha_b$$

Naive idea:

$$\boldsymbol{X}_1 = \hat{\boldsymbol{X}}_1(\boldsymbol{x}), \qquad \boldsymbol{X}_2 = \hat{\boldsymbol{X}}_2(\boldsymbol{x}) \qquad S[\hat{\boldsymbol{X}}_1, \hat{\boldsymbol{X}}_2] = \int L(\hat{\boldsymbol{X}}_1, \hat{\boldsymbol{X}}_2, \partial_t \boldsymbol{X}_1, \partial_t \boldsymbol{X}_2, \nabla \hat{\boldsymbol{X}}_1, \nabla \hat{\boldsymbol{X}}_2) d\boldsymbol{x} dt$$

э

イロト イポト イヨト イヨト

Romenski model for two-phase flows

Naive idea:

$$\boldsymbol{X}_1 = \hat{\boldsymbol{X}}_1(\boldsymbol{x}), \qquad \boldsymbol{X}_2 = \hat{\boldsymbol{X}}_2(\boldsymbol{x}) \qquad S[\hat{\boldsymbol{X}}_1, \hat{\boldsymbol{X}}_2] = \int L(\hat{\boldsymbol{X}}_1, \hat{\boldsymbol{X}}_2, \partial_t \boldsymbol{X}_1, \partial_t \boldsymbol{X}_2, \nabla \hat{\boldsymbol{X}}_1, \nabla \hat{\boldsymbol{X}}_2) d\boldsymbol{x} dt$$

э

イロト イポト イヨト イヨト

Romenski model for two-phase flows

Naive idea:

$$\boldsymbol{X}_1 = \hat{\boldsymbol{X}}_1(\boldsymbol{x}), \qquad \boldsymbol{X}_2 = \hat{\boldsymbol{X}}_2(\boldsymbol{x}) \qquad S[\hat{\boldsymbol{X}}_1, \hat{\boldsymbol{X}}_2] = \int L(\hat{\boldsymbol{X}}_1, \hat{\boldsymbol{X}}_2, \partial_t \boldsymbol{X}_1, \partial_t \boldsymbol{X}_2, \nabla \hat{\boldsymbol{X}}_1, \nabla \hat{\boldsymbol{X}}_2) d\boldsymbol{x} dt$$

SHTC approach:

$$\boldsymbol{X} = \hat{\boldsymbol{X}}(\boldsymbol{x}), \qquad \boldsymbol{\varphi}(\boldsymbol{x}) \qquad \boldsymbol{S}[\hat{\boldsymbol{X}}, \boldsymbol{\varphi}] = \int L(\hat{\boldsymbol{X}}, \boldsymbol{\varphi}, \boldsymbol{\partial}_t \boldsymbol{X}, \boldsymbol{\partial}_t \boldsymbol{\varphi}, \nabla \hat{\boldsymbol{X}}, \nabla \boldsymbol{\varphi}) d\boldsymbol{x} dt$$

 $\partial_t \varphi = \mu_1 - \mu_2$ chemical potential

 $\nabla \varphi = \boldsymbol{v}_1 - \boldsymbol{v}_2$ relative velocity

э

医水黄医水黄

Romenski model for two-phase flows

Naive idea:

$$\boldsymbol{X}_1 = \hat{\boldsymbol{X}}_1(\boldsymbol{x}), \qquad \boldsymbol{X}_2 = \hat{\boldsymbol{X}}_2(\boldsymbol{x}) \qquad S[\hat{\boldsymbol{X}}_1, \hat{\boldsymbol{X}}_2] = \int L(\hat{\boldsymbol{X}}_1, \hat{\boldsymbol{X}}_2, \partial_t \boldsymbol{X}_1, \partial_t \boldsymbol{X}_2, \nabla \hat{\boldsymbol{X}}_1, \nabla \hat{\boldsymbol{X}}_2) d\boldsymbol{x} dt$$

SHTC approach:

$$\boldsymbol{X} = \hat{\boldsymbol{X}}(\boldsymbol{x}), \qquad \varphi(\boldsymbol{x}) \qquad S[\hat{\boldsymbol{X}}, \varphi] = \int L(\hat{\boldsymbol{X}}, \varphi, \partial_t \boldsymbol{X}, \partial_t \varphi, \nabla \hat{\boldsymbol{X}}, \nabla \varphi) d\boldsymbol{x} dt$$

 $\partial_t \varphi = \mu_1 - \mu_2$ chemical potential

 $\nabla \varphi = \boldsymbol{v}_1 - \boldsymbol{v}_2$ relative velocity

UniTn

Euler-Lagrange: $\frac{\partial L_{\dot{\varphi}}}{\partial t}$ + $\nabla \cdot L_{\nabla \varphi} = L_{\varphi}$ (Euler-Lagrange)

イロト イポト イヨト イヨト

э.

Governing equations

Variational formulation:

 $\partial_t \rho + \nabla \cdot (\rho \boldsymbol{v}) = 0$

 $\partial_t(\rho \alpha_a) + \nabla \cdot (\rho \mathbf{v}) = -\Phi_a$

$$\partial_t (\rho \boldsymbol{v}) + \nabla \cdot (\rho \boldsymbol{v} \otimes \boldsymbol{v} + p \boldsymbol{I} + \boldsymbol{A}_a \boldsymbol{E}_{\boldsymbol{A}_a} + \boldsymbol{w}_a \otimes \boldsymbol{E}_{\boldsymbol{w}_a}) = \rho \boldsymbol{g}$$

$$\partial_t A + \boldsymbol{v} \cdot \nabla A + A \nabla \boldsymbol{v} = -\frac{1}{\tau} E_A$$

$$\partial_t \varrho_a + \nabla \cdot (\varrho_a \boldsymbol{\nu} + E_{\boldsymbol{w}_a}) = -\chi_a$$

$$\partial_t \boldsymbol{w}_a + \nabla (\boldsymbol{w}_a \cdot \boldsymbol{v} + E_{\varrho_a}) + (\nabla \times \boldsymbol{w}_a) \times \boldsymbol{v} = -\lambda_a$$

On variational approaches to mixtures

 $E = E_1(\rho_1, s_1, \ldots) + E_2(\rho_2, s_2, \ldots) + \ldots$

$$\boldsymbol{v} = \frac{\rho_1 \boldsymbol{v}_1 + \rho_2 \boldsymbol{v}_2 + \ldots + \rho_N \boldsymbol{v}_N}{\rho}$$

$$\boldsymbol{w}_a = \boldsymbol{v}_a - \boldsymbol{v}_N$$

• • • • • • •

Ferrari *et al*, JCP, (2025)

Governing equations

Variational formulation:

 $\partial_t \rho + \nabla \cdot (\rho \boldsymbol{v}) = 0$

 $\partial_t(\rho \alpha_a) + \nabla \cdot (\rho \mathbf{v}) = -\Phi_a$

$$\partial_t(\rho \boldsymbol{v}) + \nabla \cdot (\rho \boldsymbol{v} \otimes \boldsymbol{v} + p \boldsymbol{I} + \boldsymbol{A}_a \boldsymbol{E}_{\boldsymbol{A}_a} + \boldsymbol{w}_a \otimes \boldsymbol{E}_{\boldsymbol{w}_a}) = \rho \boldsymbol{g}$$

$$\partial_t A + \boldsymbol{v} \cdot \nabla A + A \nabla \boldsymbol{v} = -\frac{1}{\tau} E_A$$

$$\partial_t \varrho_a + \nabla \cdot (\varrho_a \boldsymbol{\nu} + E_{\boldsymbol{w}_a}) = -\chi_a$$

$$\partial_t \boldsymbol{w}_a + \nabla (\boldsymbol{w}_a \cdot \boldsymbol{v} + E_{\varrho_a}) + (\nabla \times \boldsymbol{w}_a) \times \boldsymbol{v} = -\lambda_a$$

Ferrari *et al*, ICP, (2025)

UniTn

On variational approaches to mixtures

Baer-Nunziato-type formulation

 $\frac{\partial u_{a,i}}{\partial t} + \frac{\partial (u_{a,i}v_{a,k} + P_a\delta_{ki} + \sigma_{a,ki}^{\rm e} + \sigma_{a,ki}^{\rm t})}{\partial x_k} = -c_a \sum_{k=1}^{\rm N} p_b \frac{\partial \alpha_b}{\partial x_i} + p_a \frac{\partial \alpha_a}{\partial x_i}$ $-c_a\sum_{h=1}^N \varrho_b\bar{w}_{b,k}\omega_{b,k,i}+\varrho_a\bar{w}_{a,k}\omega_{a,k,i}$ $-c_a \sum_{b=1}^{N} \rho_b s_b \frac{\partial T_b}{\partial x_i} + \rho_a s_a \frac{\partial T_a}{\partial x_i}$ $-c_a \sum_{i=1}^{N} \frac{\partial \sigma_{b,ki}^{e}}{\partial x_{k}} + \frac{\partial \sigma_{a,ki}^{e}}{\partial x_{k}}$ $+c_a \sum_{b=1}^{N} \rho_b \frac{\partial e_b^{\rm e}}{\partial x_i} - \rho_a \frac{\partial e_a^{\rm e}}{\partial x_i}$ February 6, 2025

Computational examples immiscible mixtures

A three-phase flows (gas, liquid, solid)



Ferrari <i>et al</i> , JCP, (2025)			୬୯୯
UniTn	On variational approaches to mixtures	February 6, 2025	12 / 13

Computational examples immiscible mixtures

Elastic collision (gas, solid, solid)



Ferrari *et al*, JCP, (2025)

In	11	Ľ'n
л		

February 6, 2025 12 / 13

Computational examples immiscible mixtures

Plastic collision (gas, solid, solid)



Ferrari *et al*, JCP, (2025)

UniTn

▶ 《 冊 ▶ 《 重 ▶ 《 重 ▶] 三 少 Q C February 6, 2025 12 / 13

Introduction 0000

Variational Formulation 00000●0

Computational examples immiscible mixtures

Plastic collision (gas, solid, solid)



Multicomponent mixtures

 Image: Image:

< □ > < 同

- Multicomponent mixtures
- 2 Poroelasticity

< 一型

- Multicomponent mixtures
- 2 Poroelasticity
- 3 Multicomponent plasmas with full electrodynamics

- Multicomponent mixtures
- 2 Poroelasticity
- **3** Multicomponent plasmas with full electrodynamics
- ④ General relativistic flows

- 1 Multicomponent mixtures
- 2 Poroelasticity
- 3 Multicomponent plasmas with full electrodynamics
- ④ General relativistic flows
- **5** Hyperbolic relaxation systems

- Multicomponent mixtures
- 2 Poroelasticity
- 3 Multicomponent plasmas with full electrodynamics
- ④ General relativistic flows
- **5** Hyperbolic relaxation systems
- **6** Thermodynamic consistency

February 6, 2025

- Multicomponent mixtures
- 2 Poroelasticity
- 3 Multicomponent plasmas with full electrodynamics
- 4 General relativistic flows
- **5** Hyperbolic relaxation systems
- **6** Thermodynamic consistency
- Variational and Hamiltonian structures

- 1 Multicomponent mixtures
- 2 Poroelasticity
- 3 Multicomponent plasmas with full electrodynamics
- ④ General relativistic flows
- **5** Hyperbolic relaxation systems
- **6** Thermodynamic consistency
- Variational and Hamiltonian structures
- **8** Structure preserving integrators