

**1. příklad [6b]**

Maximalizujte  $P[u(\cdot)] = \int_0^2 x(t) - u^2(t) dt$ , kde  $x' = u$ ,  $x(0) = 0$  a  $u : [0, T] \rightarrow \mathbb{R}$ .

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**2. příklad [7b]** Nechť

$$A = \begin{pmatrix} 1 & 1 \\ -1 & 1 \end{pmatrix}, \quad F(X) = \frac{1}{\sqrt{1+x^2+y^2}} \begin{pmatrix} -x^3 \\ -y^3 \end{pmatrix}.$$

Ukažte, že systém

$$X' = \epsilon AX + F(X)$$

- (a) nemá periodické řešení pro  $\epsilon \leq 0$ ;  
 (b) má netriviální periodické řešení pro každé  $\epsilon > 0$ .

*Návod: Bendixson a spol.*

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**3. příklad [7b]** Ukažte ověřením předpokladů příslušné věty, že soustava

$$\begin{aligned} x' &= \alpha z^3 \\ y' &= -y + x^2 \\ z' &= -2z - x^2 \end{aligned}$$

má v okolí počátku centrální varietu tvaru  $(y, z) = (\phi_1(x), \phi_2(x))$ . Rozhodněte v závislosti na parametru  $\alpha$ , zda je počátek stabilní a zda je asymptoticky stabilní. (Aproximujte c.v. vhodnou funkcí.)

① .... V. 18.11. [P.П. / Bolza.]

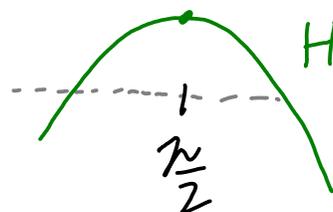
$$\left. \begin{aligned} r &= x - u^2, \quad g = 0 \\ f &= u \end{aligned} \right\} \Rightarrow H = ru + x - u^2$$

$$\begin{aligned} u &= u(t) \in \mathbb{R} \\ t &\in [0, 2] \end{aligned}$$

$$\frac{\partial H}{\partial u} = r - 2u$$

$$\frac{\partial^2 H}{\partial u^2} = -2 < 0$$

glob. max

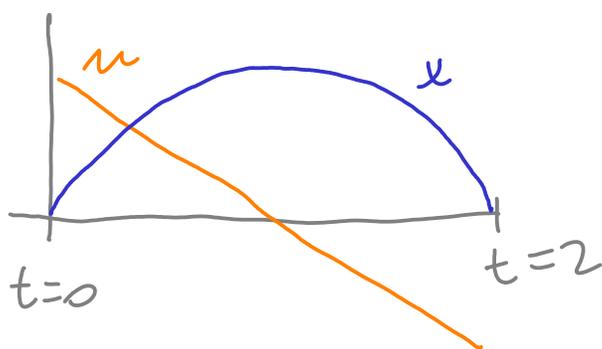


musný podm.:  $u(t) = \frac{1}{2} r(t)$

$$\left. \begin{aligned} \text{adj. nec: } r' &= -\frac{\partial H}{\partial x} = -1 \\ r(2) &= g'(x(2)) = 0 \end{aligned} \right\} \Rightarrow$$

$$\begin{aligned} r(t) &= 2 - t \\ u(t) &= 1 - \frac{t}{2} \end{aligned}$$

$$\begin{aligned} x(t) &= x(0) + \int_0^t u(s) ds \\ &= t - \frac{1}{4} t^2 \end{aligned}$$



? existence maxime?

② (ii)  $\varepsilon \leq 0$  ..... Ljapunov  $V = x^2 + y^2$

$$\dot{V} = 2xx' + 2yy' = 2\varepsilon(x^2 + y^2) - \frac{2(x^4 + y^4)}{\sqrt{1 + x^2 + y^2}}$$

$$\Rightarrow \dot{V} < 0 \quad \forall (x, y) \neq (0, 0)$$

V. 14.1. (LaSalle)    nebo V. 10.2 (Ljapunov 2)  $\Rightarrow (x(t), y(t)) \rightarrow (0, 0) \quad t \rightarrow +\infty$   
 speciálně:  $\nexists$  per. orbit.

jinak: V. 15.2. (Bendixson-Dulac)

$$\text{nis } X' = F(X) \Rightarrow$$

$$\text{div } F(X) = \frac{\partial}{\partial x} \left( \varepsilon(x+y) - \frac{x^3}{\sqrt{1+\dots}} \right) + \frac{\partial}{\partial y} \left( \varepsilon(-x+y) - \frac{y^3}{\sqrt{1+\dots}} \right)$$

$$\dots = \underbrace{2\varepsilon}_{\leq 0} - \frac{1}{(\sqrt{1+\dots})^3} \left( \underbrace{3(x^2+y^2)(1+x^2+y^2)}_{> (x^2+y^2)^2} - (x^4+y^4) \right)$$

$$> (x^2+y^2)^2 \geq (x^4+y^4)$$

$$\Rightarrow \text{div } F(X) < 0 \text{ n.v. v } \mathbb{R}^2$$

(mimo  $(0,0)$ )

$\Rightarrow \nexists$  periodicky' orbit.

(ii)  $\varepsilon > 0$  ... dnu v'it V. 15.1 (Poincaré-Bendixson)

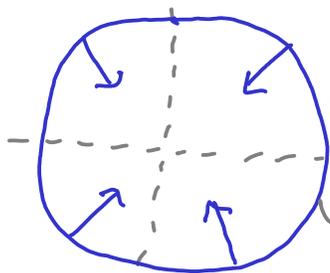
•  $\dot{V} < 0$  pro  $x^2+y^2 > R^2$ ,  $R > 0$  dost velke'

dk:  $\underbrace{(x^2+y^2)^2} = x^4 + \underbrace{2x^2y^2} + y^4 \leq \underbrace{2(x^4+y^4)}$

$$\leq x^4+y^4 \text{ (Young)}$$

$$\Rightarrow \dot{V} \leq (x^2+y^2) \left[ 2\varepsilon - \frac{x^2+y^2}{\sqrt{1+x^2+y^2}} \right]$$

$$< 0 \text{ pro } x^2+y^2 > R$$



$B(0, R)$  ... omezené, poz. inv.

• seci one'ni body?

$(0,0) \dots$  linearize  $A_0 = \begin{pmatrix} 1 & 1 \\ -1 & 1 \end{pmatrix}$

$$\sigma(A_0) = 1 \pm i\sqrt{2}$$

$\Rightarrow (0,0) \notin \omega(\mu_0)$  pro  $\mu_0 \neq (0,0)$

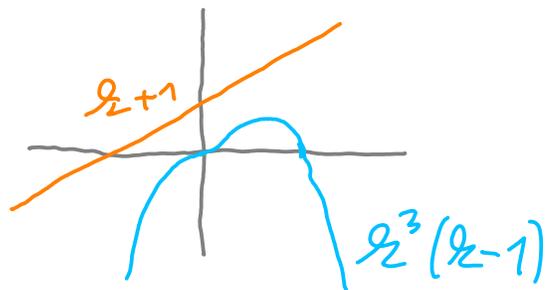
• Andime:  $\nexists$  jine' sec. body !!

dz: naji. podileni' ronic

$$\frac{x+y}{-x+y} = \frac{x^3}{y^3} \Rightarrow \frac{z+1}{-1+z} = z^3$$

$(x = zy)$

$$z+1 = z^3(z-1)$$



v.15.1.

CELKEN:  $\Rightarrow \forall \mu_0 \in B(0, R), \mu_0 \neq (0,0)$

$\omega(\mu_0) = \Gamma$  ↖ metric. per. orbit  
 $\sim B(0, R)$

③  $x \in \mathbb{R}^1 \dots$  cenná hru  $A = (0)$ ,  $f = \alpha r^3$   
 $(y, r) \in \mathbb{R}^2 \dots$  salá hru  $B = \begin{pmatrix} -1, 0 \\ 0, -2 \end{pmatrix}$ ,  $g = \begin{pmatrix} x^2 \\ -x^2 \end{pmatrix}$

v. 20.1.  $\Rightarrow$   $\exists$  c.n.  $M = \phi_1(x)$   
 $(\text{lokalizace})$   $R = \phi_2(x)$

aprotimace:

$$\begin{aligned} \Pi_1 &= (\phi_1(x) - y)' = \phi_1' x' - y' = \phi_1' (\alpha \phi_2^3) + \phi_1 - x^2 \\ \Pi_2 &= (\phi_2(x) - r)' = \phi_2' x' - r' = \phi_2' (\alpha \phi_2^3) + 2\phi_2 + x^2 \end{aligned}$$

zkusme:  $\left. \begin{aligned} \psi_1(x) &= c_1 x^2 \\ \psi_2(x) &= c_2 x^2 \end{aligned} \right\} \Rightarrow \left. \begin{aligned} c_1 &= 1 \\ c_2 &= -\frac{1}{2} \end{aligned} \right\} \text{ [chi=0]}$

chyba?  $\Pi_1(\psi_1, \psi_2) = \psi_1' \alpha \psi_2^3 = 2\alpha x \left(-\frac{1}{2}x^2\right)^3 = \mathcal{O}(x^7)$

$$\left[ \begin{aligned} \psi_1(x) &= x^2 \\ \psi_2(x) &= -\frac{1}{2}x^2 \end{aligned} \right]$$

(podobně pro  $\Pi_2$ )

$$\Rightarrow \left[ \begin{aligned} y &= \phi_1(x) = x^2 + \mathcal{O}(x^7) \\ r &= \phi_2(x) = -\frac{1}{2}x^2 + \mathcal{O}(x^7) \end{aligned} \right]$$

stabilité: stabilise (0,0)  $\iff$  stabilise 0 pro  $p' = \alpha \Phi_2^3(p)$

approximée:  $p' = \alpha \left( -\frac{1}{2} p^2 + \mathcal{O}(p^7) \right)^3$   
 $p' = \alpha \left( -\frac{1}{8} p^6 + \mathcal{O}(p^{11}) \right)$

$\alpha \neq 0 \implies$  non-stable  
(saddle point)

$\alpha = 0 \implies p' = 0$ ;  $\exists$ : stable,  
ne asympt.