

Incompressible Navier-Stokes-Fourier system

Goal: to extend Leray's programme to this system

Governing eqs

$$\text{div } v = 0$$

$$\Omega \subset \mathbb{R}^3, (0, T)$$

$$g(t, x) = g_* \in (0, \infty) \quad \text{everywhere}$$

$$g_* (\partial_t v + \text{div}(v \otimes v)) = \text{div} \bar{\Pi}$$

$$\bar{\Pi} = \bar{\Pi}^T$$

$$E := e + \frac{|v|^2}{2}$$

$$p_* \partial_t \left(e + \frac{|v|^2}{2} \right) + g_* (\text{div}(e + \frac{|v|^2}{2})) = \frac{\text{div}(\bar{\Pi} v)}{-\text{div} j_e}$$

2-nd law

$$g_* (\partial_t \gamma + \text{div}(\gamma \vec{v})) + \text{div} \vec{j}_\gamma = \zeta \quad \text{with } \zeta \geq 0$$

entropy method

Count eqs

$$\bar{\Pi} = -p \mathbf{I} + 2 \tilde{\nu}(e) Dv$$

$$\vec{j}_e = -k(e) \nabla e$$

Balance energy Take eq. for E and ζ : (Gauss

$$\begin{aligned} \frac{d}{dt} \int_{\Omega} g_* \left(e + \frac{|v|^2}{2} \right) dx + \int_{\partial \Omega} g_* \left(e + \frac{|v|^2}{2} \right) \vec{v} \cdot \vec{n} dS \\ + \int_{\partial \Omega} \vec{j}_e \cdot \vec{n} dS - \bar{\Pi} \vec{v} \cdot \vec{n} dS = 0 \end{aligned}$$

$= g_* |v|_e^2$

Boundary conditions

• $\vec{v} \cdot \vec{n} = 0$ or $(0, T) \times \partial\Omega$

internal
flows

• $-(S_h)_T = g^* v_T$ —||—

Navier slip
(stick-slip is
possible)

• $\vec{j}_e \cdot \vec{n} = \begin{cases} 0 & \\ -g^* |v_T|^2 & \end{cases}$

thermally isolated
body
energetically
conserved b.c's

Aux. cales:

$$T v \cdot n = (\Pi_h)_T \cdot v_T = (S_h)_T \cdot v_T$$

$$v \cdot n = 0$$

!! The analysis presented below does not work
for w-slip b.c's.

under b.c's in yellowed boxes:

$$\left[\frac{d}{dt} \int \rho_k \left(e + \frac{|v|^2}{2} \right) dx = 0 \right] \Rightarrow E(t) = E_0 \quad \forall t > 0$$

$$E(t) := \int \rho_k \left(e(t, x) + \frac{|v(t, x)|^2}{2} \right) dx$$

$$E_0 := \int \rho_k (e_0 + \frac{|v_0|^2}{2}) dx$$

where v_0, e_0 are initial data:

IC's

$$v(0, \cdot) = v_0 \quad \text{in } \Omega$$

$$e(0, \cdot) = e_0 \quad \text{in } \Omega$$

• $0 < v_* \leq v(e) \leq v^* < +\infty$

• $0 < k_* \leq k(e) \leq k^* < +\infty$.

✓ The simplest model relating internal energy e to temperature θ : $e = c_v \theta$ ($c_v > 0$)

$$S = S(E, \dots)$$

E } $S \rightarrow$ as $E \rightarrow$
 S

$$\frac{1}{\text{temperature}} = \frac{\partial S}{\partial E}$$

classical
thermodynamics

$$\frac{1}{\theta} := \frac{\partial \gamma}{\partial e}$$

$$\Leftrightarrow \frac{c_v}{e} = \frac{\partial \gamma}{\partial e} = \underline{\gamma'(e)}$$

$$\gamma = \gamma(e)$$

$$\gamma = c_v \ln e + c_*$$

quad law eq.

$$\vec{j}_\gamma = \frac{\vec{je}}{\theta} = c_v \frac{\vec{je}}{e}$$

$$\rho_* \frac{c_v}{e} \left(\partial_t e + \nabla \cdot (\vec{e} \vec{v}) \right) + \nabla \cdot \vec{e} \vec{v} = \xi$$

$$\nabla \cdot \vec{e} \vec{v} = c_v \frac{\vec{je}}{e}$$

$$-\frac{c_v}{e} \nabla \cdot (\kappa(e) \vec{je}) + \frac{c_v}{e^2} \kappa(e) \vec{je} \cdot \nabla e$$

$$\text{where } \xi = \frac{1}{\theta} \xi = \frac{c_v}{e} \xi =$$

$$\xi = \frac{c_v}{e} \left\{ 2\nu(e) |\nabla v|^2 + \frac{\kappa(e)}{e} |\nabla e|^2 \right\}$$

$$\rho_* (\partial_t e + \nabla \cdot (\vec{e} \vec{v})) - \nabla \cdot (\kappa(e) \vec{je}) = 2\nu(e) |\nabla v|^2$$

The same eq. is obtained if one multiply bal. of lin. mom. scalarly by \vec{v} , and subtract the result from the bal. of total energy:

On the level of weak solutions, it is open how to show the validity of

EQUALITY

$$p^*(\partial_t e + \operatorname{div}(e\vec{v})) - \operatorname{div}(\varepsilon(e)\nabla e) = 2v(e)|Dv|^2$$

However, we can add to a closed system of 5 eqs for 5 unknowns

$$\operatorname{div} v = 0, \quad (\text{BLM}) + (\text{BE})$$

ineq.

$$p^*(\partial_t e + \dots) - \operatorname{div}(\varepsilon(e)\nabla e) \geq 2v(e)|Dv|^2$$

admissible
weak sols

Why? Because subtract the last ineq. from balance of energy, we get

$$p^*\left(\partial_t \frac{|v|^2}{2} + \operatorname{div}\left(\frac{|v|^2}{2}\vec{v}\right)\right) + \operatorname{div}(p\vec{v})$$

$$- \operatorname{div}(2v(e)|Dv|^2) \leq 0$$

and noticing that for $v(e) = v^*$ we will get Caffarelli, Koch, Nirenberg ineq. for kinetic energy

Q: When these inequalities can be replaced by equalities?

$$\frac{1}{\theta} := \frac{\partial \gamma}{\partial e}$$

$$\left[\frac{c_v}{e} = \gamma'(e) \right]$$

$$e = c_v \theta \quad \& \quad \gamma = \gamma(e)$$

$$\gamma(e) = c_v \ln e + c_*$$

$$q_* \left(\frac{c_v}{e} \partial_t e + \frac{c_v}{e} v_i \frac{\partial e}{\partial x_i} \right) - \operatorname{div} \left(\frac{c_v k(e) \nabla e}{e} \right) =$$

$$- \frac{\operatorname{div}(c_v k(e) \nabla e)}{e} + c_v k(e) \frac{\nabla e \cdot \nabla e}{e^2} =$$

$$= c_v k(e) \frac{\nabla e \cdot \nabla e}{e^2} + c_v \frac{2v(e) |D(v)|^2}{e}$$

$$\xi = \theta \zeta$$

$$\vec{v} \cdot \vec{n} = 0 \text{ on } \partial \Omega$$

$$\begin{aligned} \int_{\Omega} q_* \left(e + \frac{|v|^2}{2} \right) dx &= \int_{\partial \Omega} \left(\vec{T} \vec{v} \cdot \vec{n} - \vec{j} \vec{v} \cdot \vec{n} \right) dS \\ &= \int_{\partial \Omega} (\vec{m}) \cdot \vec{v} dS \end{aligned}$$

stick / slip

$$\frac{1}{2} \int_{\Omega} \left(\partial_t v \right)^2 + 2v_x \int_{\Omega} |Dv|^2 = 0 \quad \leftarrow$$

≤ 0

$$\int_0^T \underbrace{\langle \partial_t v, \varphi \rangle}_{+ \varphi} + \text{c.t.} + v(Dv, D\varphi) = 0$$

$+ \varphi$

The energy eq. would hold if

$\varphi = v$ is admissible test function
in balance of lin-moments

Summary

At the level of smooth fcts (C^∞, C^1)
 but also at the level of weak solutions
 when v is admissible test f. in BLD_T ,
 then

(1)
$$\begin{cases} \operatorname{div} v = 0 \\ \partial_t v + \operatorname{div}(v \otimes u) = \operatorname{div}(\Pi v) \\ \partial_t e + \operatorname{div}(E v) = \operatorname{div}(\Pi v - j e) \end{cases}$$
 $E := e + \frac{|U|^2}{2}$

↑

(2)
$$\begin{cases} \operatorname{div} v = 0 \\ \partial_t v + \operatorname{div}(v \otimes u) = \operatorname{div}(\Pi v) \\ \partial_t e + \operatorname{div}(E v) = -\operatorname{div}(j e) + \underbrace{\Pi : D v}_{\geq 0} \end{cases} \in L^1(Q_T)$$

In 3D: this equivalence is open.

• (1) has better structure since all terms in eq. for (E) are in divergence form.

• However, eq. for e has good structure to show that $e \geq 0$ (or $e \geq e^* > 0$)

Formal apriori estimates

both (1) and (2)
are in our
disposal.

① Energy estimates

$$E(t) = e + \frac{\|u\|^2}{2}$$

$$\cdot \int_{\Omega} E(t) \leq \int_{\Omega} E_0 \Rightarrow \int_{\Omega} e \in L^{\infty}(0, T; L^2)$$

~~$\|u\|^2$~~ , $e \in L^{\infty}(0, T; L^1)$
(assuming $e \geq 0$.)

$$\cdot \int_{\Omega} \nabla L M \cdot \vec{v} = \int_0^T \int_{\Omega} 2v(e) |Dv|^2 dx dt < +\infty$$

+ $\int_0^T \int_{\partial\Omega} g_* |\nabla v|_*^2 d\sigma ds < +\infty$

Remark 1) Note that for liquids: $v \searrow$ as $e \nearrow$

• Reynolds (1900) $v(e) = \mu * \exp(-m*/e)$

• Vogel (1922) $v(e) = \mu * \frac{A*}{B* + e}$

for gas:
(compressible) $v \nearrow$ as $e \nearrow$

- * Feireisl, Novotný - (2011)
 - * Feireisl (2004)
 - * Feireisl, Kapr, Povaz (2017) - no temperature
- focused on
thermal phenomena
many of articles

(2)

Minimum principle for e

$$-\frac{\partial e}{\partial t} + v_x \frac{\partial e}{\partial x_x} - \operatorname{div}(k(e) \nabla e) = v(e) |Dv|^2$$

Goal: Assuming that $e(0, \cdot) = e_0 \geq e_* > 0$ in Ω , show that $e(t, x) \geq e_*$ in Q_T .

$$(e_* - e_0)^+ = 0 \text{ in } \Omega \Rightarrow (e_* - e)^+ = 0 \text{ in } Q_T$$

(*)

$$\frac{\partial (e_* - e)}{\partial t} + v_x \frac{\partial (e_* - e)}{\partial x_x} - \operatorname{div}(k(e) \nabla (e_* - e)) = -v(e) |D(v)|^2 \leq 0$$

Multiplying (*) by $(e_* - e)^+$,

$$\frac{1}{2} \frac{d}{dt} \int_{\Omega} [(e_* - e)^+]^2 + \int_{\Omega} v_x \frac{\partial}{\partial x_x} [(e_* - e)^+]^2 + \int_{\Omega} k(e) \nabla (e_* - e) \cdot \nabla (e_* - e)^+ dx \leq 0$$

by parts
 $\operatorname{div} v = 0$
 $v \cdot n = 0$
 on $\partial\Omega$.

$$\int_0^t ds$$

$$\Rightarrow \int_{\Omega} [(e_* - e(t, x))^+]^2 = \int_{\Omega} [(e_* - e_0)^+]^2 dx = 0$$

$e(t, x) \geq e_*$
 a.e. in Q_T

③ Goal: to get info on ∇e ?

$T: Dv$

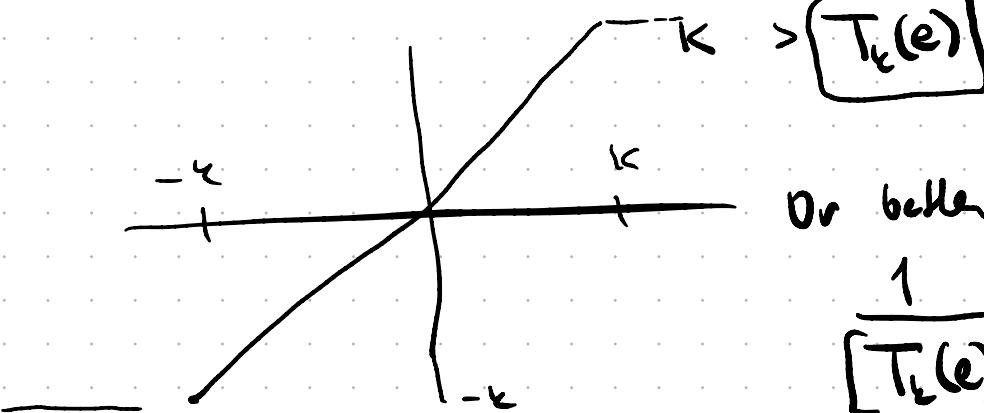
We use

$$\frac{\partial e}{\partial t} + v_x \frac{\partial e}{\partial x_2} - \operatorname{div}(z(e) \nabla e) = \underbrace{v(e)/Dv^2}_{\in L^1}^2$$

$\frac{1}{e^\lambda} \in L^\infty(Q_T)$

$\lambda > 0$

$e \geq e^* \Rightarrow 0 < \frac{1}{e^\lambda} \leq \frac{1}{(e^*)^\lambda}$



Or better

$$\frac{1}{[T_\epsilon(e)]^\lambda}$$

and after getting the estimate

let $\lambda \rightarrow \infty$

Hw: DO THE FOLLOWING STEPS FOR $\frac{1}{[T_\epsilon(e)]^\lambda}$

Galloët, Bocecardo 1991
Bocecardo, Murat

$\lambda > 0$

$$\begin{aligned} \int_Q k(e) \nabla e \cdot \nabla \frac{1}{e^\lambda} &= \int_Q k(e) \nabla e \cdot \frac{1}{e^{\lambda+1}} \nabla e + \int_Q k(e) \nabla e \cdot \frac{1}{e^{\lambda+1}} \nabla \left(\frac{1}{e^\lambda}\right) \\ &= -\lambda \int_Q k(e) \nabla e \cdot \frac{1}{e^{\lambda+1}} \nabla e = -\lambda \int_Q k(e) \frac{\nabla e}{e^{\lambda+1}} \cdot \frac{\nabla e}{e^{\lambda+1}} \\ &\quad + \frac{1}{1-\lambda} \int_Q \nabla e \cdot \nabla \left(\frac{1}{e^\lambda}\right) \\ &= -\frac{4\lambda}{1-\lambda} \int_Q k(e) \left(\nabla e \frac{1-\lambda}{2}\right)^2 \stackrel{>0}{=} 0 \\ &\quad + \frac{1}{1-\lambda} \int_Q \frac{2}{\nabla x_2} e^{1-\lambda} \in L^1(Q) \\ &\quad \leq - \int_Q \frac{\partial e}{\partial t} \frac{1}{e^\lambda} - \int_Q v_x \frac{\partial e}{\partial x_2} \frac{1}{e^\lambda} + \int_Q v(e) |Dv|^2 \frac{1}{e^\lambda} \\ &\quad \leq -\frac{1}{1-\lambda} \int_Q \frac{\partial e}{\partial t} \frac{1}{e^{1-\lambda}} + \int_Q v(e) |Dv|^2 \frac{1}{e^\lambda} < +\infty \end{aligned}$$

Here $\int_0^T \int_{\Omega} |\partial e^{\frac{1-\lambda}{2}}|^2 dx < +\infty$ $\forall \lambda > 0$ ($\lambda < 1$)
 we see that $\frac{\sqrt{e}}{\sqrt{e}}$ is almost ^{odd} in $L^2(Q)$
 is odd in $L^\infty(L^2)$

One can interpolate information that

$$e^{\frac{1}{2}} \in L^\infty(L^2) \text{ and } \partial e^{\frac{1-\lambda}{2}} \in L^2(L^2)$$

Similarly
 $v \in L^{6/3}(Q)$



$$v \in L^\infty(L^2) \cap L^2(W^{1,2})$$

$$e \in L^{\frac{6}{3}-\varepsilon}(Q_T)$$

Hölder

$$\partial v \in L^{\frac{6}{3}-\varepsilon}(Q_T)$$

(4) Our concept of sol. is based on PDE system (1),
 where eq (1)₃, i.e. balance of energy, takes the form

$$\begin{aligned} \frac{\partial}{\partial t} \left(e + \frac{|v|^2}{2} \right) + \nabla \cdot \frac{\partial}{\partial x_3} \left(e + \frac{|v|^2}{2} + p \right) - \operatorname{div}(v(e)\nabla e) &= \operatorname{div}(2\mu \nabla v) \\ \frac{\partial}{\partial t} \left(e + \frac{|v|^2}{2} \right) + \nabla \cdot \underbrace{\left(e + \frac{|v|^2}{2} + p \right)}_{T = pI + 2\mu \nabla v} - \operatorname{div}(v(e)\nabla e) &= \operatorname{div}(2\mu \nabla v) \end{aligned}$$

This formulation
 needs to determine p .

We need uniform estimate on p

From BLM, applying div :

$$-\Delta p = \operatorname{div} \operatorname{div} (v \otimes v - v(e) \nabla v)$$

\boxed{p}

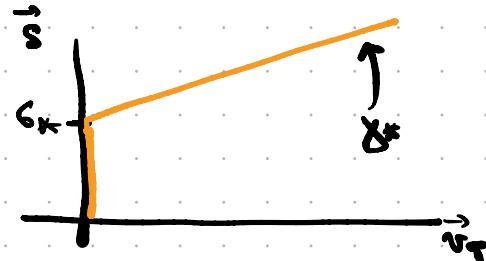
should behave as

$$\begin{aligned} v \otimes v - v(e) \nabla v &\in L^2(Q_T) \\ &\subseteq L^{\frac{6}{3}}(Q_T) \end{aligned}$$

$$\Rightarrow p \in L^{\frac{6}{3}}(Q_T)$$

BUT THIS IS INDEED POSSIBLE
 TO SHOW EXCEPT NO-SUP BC.

In order to have the result for almost no-slip bc's,
we consider stick-slip bc



$$\vec{s} = (-\dot{S}_h) \vec{\tau}$$

$$g^* v_T = \frac{(\vec{s} - \vec{S}_h)^+ s}{|\vec{s}|}$$

$$\text{or } (\partial_T) \times \vec{S} \vec{\tau}$$

It holds:

For any date (reasonable) \exists
(suitable) weak solution to NSE wth
with stick-slip bc's in the sense of
weak form of (1).

Construction of approximation. Problem (P) is approximated
by (P_m) , where (P_m) :

$$-\frac{1}{2} \operatorname{div}(G_m(|v|^2)v) v$$

$$\begin{aligned} & \operatorname{div} v = 0 \\ & \frac{\partial v}{\partial t} + \operatorname{div}(G_m(|v|^2)v) v = -\nabla p \\ & \frac{\partial e}{\partial t} + \operatorname{div}(ev) - \operatorname{div}(e\nabla e) = 2v(e)|\nabla v|^2 \\ & \operatorname{div}(-\dots v) + G_m(|v|^2) v_i v_j \frac{\partial v_j}{\partial x_i} = \operatorname{div}(-) + -\frac{1}{2} |\nabla v|^2 \operatorname{div}(G_m(|v|^2)v) \\ & + \frac{1}{2} |p|^2 \end{aligned}$$

$$v(0, \cdot) = v_0, \quad e(0, \cdot) = e_0$$

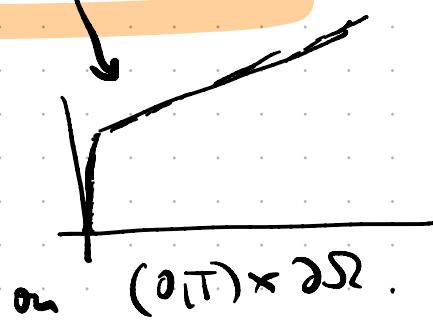
$$\vec{N} \cdot \vec{v} = 0$$

$$g^* v_T = \frac{(\vec{s} - \vec{S}_h)^+ \vec{s}}{|\vec{s}|} + \frac{1}{m} \vec{s}$$

$$\text{on } (0, T) \times \partial\Omega$$

HW: Write

$$\vec{s} = \tilde{\vec{s}}(v_T) \vec{\tau}$$



$$\text{on } (0, T) \times \partial\Omega.$$

$$q \cdot n = 0$$

Lecture, Jan 4, 2021 = 43×47

$$-\varepsilon \hat{p} + \operatorname{div} \hat{v} = 0$$

$$\partial_t \hat{v} + \operatorname{div} (\mathbf{G}_m(\cdot) \hat{v} \otimes \hat{v}) + \frac{1}{2} \operatorname{div} (\mathbf{G}_m(\cdot) \hat{v}) \hat{v} + \partial_t \hat{v} (\mathbf{G}_m(\cdot) \hat{v}) = -\nabla p$$

How to get uniform estimates for the pressure:

$$\int p \operatorname{div} \hat{w} = \dots \int \partial_t \hat{v} \cdot \hat{w}$$

$$(v, p, e) = (\hat{v}, \hat{p}, \hat{e})$$

Tale

$$\begin{cases} \operatorname{div} \hat{w} = p \\ w = 0 \text{ or } \partial \Omega \end{cases}$$

NO-SLIP

$$\begin{aligned} (\hat{z}, -\Delta \hat{q}) &= (p, \hat{t}) && \text{Homogeneous} \\ -\Delta \hat{q} &= \partial_t p && \text{Neumann} \\ \hat{q} |_{\partial \Omega} &= 0 && \text{problem} \end{aligned}$$

However for stick-slip and other slipping bc's

$$w = -\nabla z$$

$$-\Delta z = p$$

$$\frac{\partial z}{\partial n} = \nabla t \cdot n = w \cdot n = 0$$

$$\|z\|_{H^2} \leq C \|p\|_2$$

$$\begin{aligned} \int \|\hat{p}\|^2 &= \int |p|^2 = - \int \partial_t v \cdot \nabla z = - \int \partial_t \operatorname{div} v \cdot z \\ &= - \int \partial_t p z = -\varepsilon \int p (-\Delta_0) \partial_t p \leq 0 \end{aligned}$$

$$\int |\hat{p}''|^2 = \int |p|^2 = - \int \partial_t v \cdot \nabla z = \dots$$

$$= - \int (\partial_t v \operatorname{div} + \partial_t \nabla g) \cdot \nabla z = - \int \partial_t \nabla g \cdot \nabla z$$

$$v = \nabla \operatorname{div} + \nabla g$$

$$= -\frac{1}{\varepsilon} \int \partial_t |\nabla g|^2 \leq 0$$

$$\begin{aligned} -\Delta \hat{g} &= \operatorname{div} v \\ \frac{\partial \hat{g}}{\partial n} &= 0 \end{aligned}$$

$$= \varepsilon p$$

$$(\nabla g, \nabla t) = (\varepsilon p, z)$$

$$z = \frac{g}{\varepsilon}$$

On RHS we also have e.g.

$$\left| - \int_{\Omega} \underbrace{v(e)}_{L^\infty} \frac{\nabla v}{L^2} \cdot \nabla z \right| \stackrel{*}{\leq} \|Dv\|_2 \|z\|_{2,2}$$
$$\stackrel{x}{\leq} C \|Dv\|_2 \|p\|_2$$

$U_2 \|_{2,2} \leq C \|p\|_2$

$$\|p\|_2^2 \leq \underbrace{\dots}_{\leq 0} + C \|Dv\|_2 \|p\|_2$$

$\underbrace{C \|Dv\|_2^2 + \frac{1}{4} \|p\|_2^2}$



[Having ω -approximation, we collect the uniform estimates]

From these estimates: there is subsequence

(v^n, p^n, e^n) such that

$$v^n \rightharpoonup v \quad L^\infty(L^2) \cap L^2(W_{n,\text{div}}^{1/2})$$

$$\partial_t v^n \rightarrow \partial_t v \quad (L^4(W_{n,\text{div}}^{1/2}))^*$$

$$v^n \rightharpoonup v \quad L^q(L^q) \quad \text{if } q \in [1, \frac{10}{3}]$$

strong

$$v^n \rightharpoonup v \quad L^q(0,T; L^q(\Omega)) \quad \text{if } q \in [1, \frac{8}{3}]$$

strong

$$e^n \rightarrow e \quad L^{\frac{5}{4}-\varepsilon}(W^{1, \frac{5}{4}-\varepsilon})$$

$$e^n \rightarrow e \quad L^q(L^q) \quad q \in [1, \frac{5}{3}]$$

strong

$$\partial_t e^n = \cancel{\partial_t(e)(Dv)} - \cancel{\text{div}(ev)} - \cancel{\nu(e)\partial_e} \downarrow L^1$$

$$s^n \rightarrow s \quad L^2(L^2(\Omega)) \quad \partial_t e^n \text{ bdd in } L^1(0,T; W^{1,q}(\Omega)) \quad q > 10 > 3$$

$$e \geq e_*$$

Recall

$$\text{stick-slip} \quad N_T = \frac{1}{\delta_*} \frac{(|S| - \delta_*)^+}{|S|} S$$

$$+ \frac{1}{n\delta_*} S$$

$$\int s^n(u) \leq c$$

$$\int |S^n|^2 \leq c$$

About stress.

$\cdot W^{1,2}(\Omega) \hookrightarrow L^2(\partial\Omega)$
 $\cdot W^{1,2}(\Omega) \hookrightarrow W^{\frac{1}{2},2}(\partial\Omega)$
 $\underbrace{\cdot}_{1 \geq s > \frac{1}{2}} \quad \cdot \underline{W^{s,2}(\Omega)} \hookrightarrow W^{s-\frac{1}{2},2}(\partial\Omega)$

$\|v\|_{s,2} \leq \|v\|_{1,2}^{\lambda = s} \|v\|_{0,2}^{1-\lambda}$ s

Taking $\sqrt[s]{}$ power

$\|v\|_{s,2}^{\frac{2}{s}} \leq \|v\|_{1,2}^2 \|v\|_{0,2}^{\frac{(1-s)^2}{s}}$ L²(0,T; L²) L²(W^{1,2})

$\left[\int_0^T \|v\|_{s,2}^{\frac{2}{s}} dt < +\infty \right]$

$\left[\int_0^T \|v\|_{0,2}^{\frac{2}{3-2s}} dt < +\infty \right]$

$W^{s,2}(\Omega) \hookrightarrow W^{\frac{s-1}{2},2}(\partial\Omega)$ L²(\partial\Omega)

$\bar{q} = \frac{3-2s}{4}$

When $\frac{2}{s} = \frac{4}{3-2s} \Rightarrow s = \frac{3}{4}$

$\Rightarrow \left[\int_0^T \|v\|_{\frac{8}{3}}^{\frac{8}{3}} dt < +\infty \right]$

Conclusion: $L^2(W^{1,2}) \cap L^\infty(L^2)$

Take weak form. for \tilde{v}^n , use \tilde{v}^n as test function

and Add weak form for \tilde{e}^n with test function \tilde{u}

$$E^n = \frac{1}{2} \tilde{v}^n \tilde{v}^n + \tilde{e}^n$$

$$\partial_t E^n + \operatorname{div}(E \tilde{v}^n) + \operatorname{div}(\tilde{p} \tilde{v}^n) + \operatorname{div}(2\mu(\tilde{e}) \operatorname{Div} \tilde{v}^n)$$

$$\operatorname{div}\left(\left(\frac{1}{2} \tilde{v}^n \tilde{v}^n - \frac{1}{2} \tilde{v}^n \tilde{v}^n G_n(\tilde{v}^n)\right) + \frac{1}{2} \int_0^{\tilde{v}^n} G_n(s) ds\right) \tilde{v}^n$$

In the weak form also the term $\int_{\Omega} \tilde{v}^n \cdot \tilde{v}^n$ appear



$$\text{Now: } n \rightarrow \infty$$

$$\sim \tilde{v}^n \tilde{v}^n$$

\tilde{v}^n bdd

$$L^{10/3}$$

$$\begin{aligned} & \operatorname{div}(\nabla K(\tilde{e}^n)) \\ &= \Delta K(\tilde{e}^n) \end{aligned}$$

It remains:

$$v_T = f(s)$$

$$0 \leq \int_{\partial \Omega} (f(s) - f(z)) \cdot (s^n - z) dS$$

$$v_T = \frac{1}{n} s^n$$

$n \rightarrow \infty$

$$0 \leq \int_{\partial \Omega} (v_T - f(z)) \cdot (s - z) dS$$

$$\Rightarrow v_T = f(s)$$

and then
use Riesz's
idea
 $z = s \pm \epsilon \varphi$