

1. INTRODUCTION

Functional analysis (FA) is a study of the mappings
 $L : X \rightarrow Y$

where X, Y are vector spaces over the field of scalars K
 where K stands for real numbers $\mathbb{R}$ or complex numbers $\mathbb{C}$.

The vector spaces X, Y are (usually) equipped with additional structures that allows one to talk a continuity of the mappings etc.

X with scalar product $(\cdot, \cdot)_X$ pre-Hilbert spaces or spaces with inner product or scalar-product spaces

X with norm $\|\cdot\|_X$ normed spaces

X with distance $d(\cdot, \cdot)$ metric spaces

X with topology τ topological (vector) spaces.

[Q: Why "functional" analysis? [A: An important subclass of the mappings are those where $Y = K$, i.e. $L : X \rightarrow K$ maps points (vectors) of X into the numbers. Such mappings are called functionals.

► LINEAR FA studies LINEAR mappings L (see definition below)

- generalizes tools and the results of linear algebra; studies similarities/differences and connections between X 's so that $\boxed{\dim X < +\infty}$ and X 's with $\boxed{\dim X = \infty}$

- provides an elegant way to solve linear ODE and/or PDE problems

► NONLINEAR FA analyzes NONLINEAR mappings L and includes

- fixed-point theory
- bifurcation theory
- calculus of variation and optimal theory

A central topic in both areas is the question of compactness (distinguishes X with $\dim X < +\infty$ to those X with $\dim X = +\infty$).

History of FA is ~~now~~ connected with

- (i) John von NEUMANN (1926) following the goal to develop mathematical foundation of quantum mechanics:

|| there is a correspondence between the point in a Hilbert space of the norm 1 and a physical state of quantum system

- (ii) Jean LERAY (1929-34) following the work of

theoretical physicist Carl-Wilhelm Oseen on theoretical foundation of hydrodynamics, i.e. on Navier-Stokes equations.

|| Leray worked ^{the} solution of the nonlinear system of PDEs as a point in the vector space.

→ founder of modern analysis.

2. LINEAR OPERATORS BETWEEN BANACH SPACES

In the first year (2nd semester), we use $\mathbb{R}^d$ to gradually build definitions and relations for Hilbert, Banach (normed), metric and topological vector spaces.

Let us do it differently now. | Given a vector space X over the field of numbers $\mathbb{K}$ (where $\mathbb{K} = \mathbb{R}$ or $\mathbb{C}$), we wish to introduce a distance $d(\cdot, \cdot): X \times X \rightarrow \mathbb{R}$ between the points of X . With distance we can specify topology (open, closed sets), convergence, continuity of mappings, convergence of series etc.

Since X has the algebraic structure of vector space, the distance d should be consistent with the structure.

It is thus natural to require:

(P1) $d(x+z, y+z) = d(x, y) \quad \forall x, y, z \in X$ (invariance of distance w.r.t. the translation)

(P2) $d(\lambda x, \lambda y) = |\lambda| d(x, y) \quad \forall x, y \in X, \forall \lambda \in \mathbb{K}$ ("invariance" w.r.t. scaling)

(P3) $B_r(x_0) := \{y \in X; d(x_0, y) < r\}$ is convex for all $x_0 \in X$, $\forall r > 0$.

The invariance (P1) implies that $d(\cdot, \cdot)$ is determined once we specify the function $x \mapsto \|x\|_X := d(x, 0)$ called norm. The story of FA can start from here.

L1/3

Definition Let X be a vector space over K (field of numbers).
 Then a map $x \mapsto \|x\|_X : X \mapsto \mathbb{R}$ is called norm on X
 if it satisfies:

(N1) $\forall \|x\|_X = 0 \Leftrightarrow x = 0;$

(N2) $\|\lambda x\| = |\lambda| \|x\| \quad \forall x \in X \quad \forall \lambda \in K;$

(N3) $\|x+y\| \leq \|x\| + \|y\| \quad \forall x, y \in X.$

$(X, \|\cdot\|_X)$ is then called a normed space.

Assertion 1 (Norm generates a distance) Let $(X, \|\cdot\|_X)$ be a normed space. Then

$$d(x, y) := \|x - y\|_X$$

defines the distance between the points of X , i.e.

(D1) $d(x, y) \geq 0$ and $d(x, y) = 0 \Leftrightarrow x = y$
 $\forall x, y \in X$

(D2) $d(x, y) = d(y, x) \quad \forall x, y \in X$

(D3) $d(x, z) \leq d(x, y) + d(y, z) \quad \forall x, y, z \in X$

Moreover, this distance fulfills the properties (P1)-(P3) above.

Pf • (D1) follows directly from (N1).

• To prove (D2), we write

$$d(y, x) = \|y - x\|_X = \|(-1)(x - y)\|_X \stackrel{(N2)}{=} |(-1)| \|x - y\|_X = \|x - y\|_X = d(x, y).$$

• (D3) follows from (N3) as follows:

$$d(x, z) = \|x - z\| = \|x - y + y - z\| \stackrel{(N3)}{\leq} \|x - y\| + \|y - z\| = d(x, y) + d(y, z)$$

• (P1) is a consequence of the definition

• (P2) $d(\lambda x, \lambda y) = \|\lambda x - \lambda y\| = \|\lambda(x - y)\| \stackrel{(N2)}{=} |\lambda| \|x - y\| = |\lambda| d(x, y).$

• (P3) • It is enough, due to (P1), to prove (P3) for the balls centered at the origin. Let $x, y \in B_r(0)$, and $\theta \in (0, 1)$. Then

$$\|\theta x + (1-\theta)y\| \leq \|\theta x\| + \|(1-\theta)y\| \leq \theta \|x\| + (1-\theta)\|y\|$$

$$\leq \theta r + (1-\theta)r = r$$

Having $(X, \|\cdot\|_X)$ or $(X, d(\cdot, \cdot))$, we can define open and closed balls, and then open sets (each point has a ball contained in the set), closed sets (their complement is open) and thus topology.

Furthermore, for $\{x_n\}_{n=1}^\infty \subset X, x \in X$:

- $x_n \rightarrow x$ in $X \stackrel{\text{def}}{=} \|x_n - x\|_X \rightarrow 0$ as $n \rightarrow \infty$
- $\{x_n\}$ is Cauchy $\equiv \forall \varepsilon > 0 \exists n_0 \forall n, m \geq n_0 \|x_n - x_m\|_X < \varepsilon$
- $\sum_{n=1}^\infty x_n \in X \equiv \forall \varepsilon > 0 \exists N_0 \forall n \geq N_0 \forall m \in \mathbb{N} \left\| \sum_{k=n}^m x_k \right\| < \varepsilon$
- $\sum_{n=1}^\infty x_n = x \equiv \left\| x - \sum_{n=1}^N x_n \right\|_X \rightarrow 0$ as $N \rightarrow \infty$.

Replacing norm $\|\cdot\|_X$ by the metric $d(\cdot, \cdot)$ we get the analogous definitions of concepts in any metric space.

Def. $\left. \begin{matrix} (X, (\cdot, \cdot)_X) \\ (X, \|\cdot\|_X) \\ (X, d(\cdot, \cdot)) \end{matrix} \right\}$ is $\begin{cases} \text{Hilbert} \\ \text{Banach} \\ \text{Fréchet} \end{cases}$ space $\stackrel{\text{def}}{=} \left[\begin{matrix} \text{Every Cauchy sequence} \\ \text{is converging in } X \end{matrix} \right]$

- Examples ^{*)}
- $(\mathbb{R}^d, \|\cdot\|_p), 1 \leq p \leq +\infty$ are Banach spaces, for $p=2$ Hilbert.
 - $(C(\bar{\Omega}), \|f\|_\infty := \max_{x \in \bar{\Omega}} |f(x)|)$ is Banach
 - $(C(\Omega), \int_\Omega |f| dx)$ is not complete
 - $(C^1(\bar{\Omega}), \|f\|_{C^1(\bar{\Omega})} := \|f\|_\infty + \sum_{i=1}^d \left\| \frac{\partial f}{\partial x_i} \right\|_\infty)$ is Banach
 - $(C^1(\bar{\Omega}), \|f\|_{C^1(\bar{\Omega})} := \|f\|_\infty)$ is not
 - $(l_p, \|\cdot\|_{l_p}) = \left(\left\{ x = \{x_n\}_{n=1}^\infty; \sum_{n=1}^\infty |x_n|^p < \infty \right\}; \left\| x \right\|_{l_p} := \left(\sum_{n=1}^\infty |x_n|^p \right)^{1/p} \right)$ are, for $1 \leq p \leq +\infty$, Banach

l_2 is a Hilbert space (By abstract Fourier series theory, we know that each separable Hilbert space is isometric to l_2 .)

Note that looking at l_p as a vector space, one can get the meaning only to finite summation.

*) that we know and we studied there earlier.

Hence; while $\text{span}\{e_1, \dots, e_N\} = \mathbb{R}^d$ for $\{e_i\}_{i=1}^N$ being $1 \leq N \leq d$ canonical bases,

in ℓ_p : $\text{span}\{e_1, \dots, e_N, \dots\} \subsetneq \ell_p$

Here, we get only those sequences that have only finite non-zero components.

• $(L^p(\Omega), \|\cdot\|_{L^p(\Omega)})$ are Banach, for $1 \leq p \leq \infty$, even Hilbert for $p=2$.

classes of functions that may differ on the sets of zero measure

Examples (we did not investigate yet) For $1 \leq p \leq \infty, k \in \mathbb{N}$

• $W^{k,p}(\Omega) := \{f \in L^p(\Omega); D^\alpha f \in L^p(\Omega) \forall \alpha = (\alpha_1, \dots, \alpha_d) \text{ with } |\alpha| \leq k\}$

are Banach spaces with

$$\|f\|_{W^{k,p}(\Omega)} := \left(\sum_{|\alpha| \leq k} \|D^\alpha f\|_p^p \right)^{1/p}$$

SOBOLEV SPACES.

• For $p=2$:

$H^k(\Omega) := W^{k,2}(\Omega)$ are Hilbert spaces

For example

$(H^1_0(\cdot, \cdot), \cdot)_{H^1_0}$; $(fg)_{H^1_0} = \int_{\Omega} fg(x) + \sum_{i=1}^d \int_{\Omega} \frac{\partial f}{\partial x_i} \frac{\partial g}{\partial x_i} dx$

if $fg: \Omega \rightarrow \mathbb{R}$.

Topology (and hence metric, norm or scalar product) enables us to talk about continuity of mappings.

Let $(X, \|\cdot\|_X)$, $(Y, \|\cdot\|_Y)$ be two normed spaces over the same field K . 1/6

Def. we say that $f: X \rightarrow Y$ is continuous in X
 $\Leftrightarrow \forall x_0 \in X \quad \forall \epsilon > 0 \quad \exists \delta > 0 \quad \|x - x_0\|_X < \delta \Rightarrow \|f(x) - f(x_0)\|_Y < \epsilon$

$$\Leftrightarrow x_n \xrightarrow{n \rightarrow \infty} x_0 \Rightarrow f(x_n) \rightarrow f(x_0)$$

For X, Y as above, we say that f is bounded if it maps bounded sets in X into bounded sets in Y .

For X, Y as above.

Def. • A mapping

$L: \text{Dom}(L) \subset X \rightarrow Y$ is linear

if • $L(x+y) = Lx + Ly \quad \forall x, y \in \text{Dom } L$
 • $L(\alpha x) = \alpha Lx \quad \forall x \in \text{Dom } L, \forall \alpha \in K$

Here, $\text{Dom}(L)$ is called domain; it is a subspace of X where L is defined.

The sets

- $\text{Range } L = \text{Im } L = \{y \in Y; y = Lx \text{ for certain } x \in \text{Dom } L\}$
- $\text{Ker } L = \text{Null } L = \{x \in \text{Dom } L; Lx = 0\}$

are called image resp. kernel (or null space)
 • L is nonlinear $\Leftrightarrow L$ is not linear.

Def. (boundedness of linear operator) Let $L: X \rightarrow Y$ be linear ($\text{Dom } L = X$). We say that L is bounded

if $\|L\| := \sup_{\|x\|_X \leq 1} \|Lx\|_Y < +\infty$

Note that if L is linear & bounded and $x \neq 0$ then

$$\|L(x)\|_Y = \left\| \|x\|_X L\left(\frac{x}{\|x\|_X}\right) \right\|_Y = \|x\|_X \left\| L\left(\frac{x}{\|x\|_X}\right) \right\|_Y \leq \|L\| \|x\|_X$$

$\frac{x}{\|x\|_X} \in B_X(0)$

which implies that bounded sets (in X) are mapped into bounded sets in Y .

The above inequality holds for L linear bounded:

$$\|Lx\|_Y \leq \|L\| \|x\|_X \quad \forall x \in X.$$