Lecture 9 | 28.04.2025

Marginal models for non-normal response

GLM extensions for the longitudinal data

Marginal models

- primary interest is given to the conditional mean structure
- □ separate models for the mean and the covariance structure

Random effects models

□ one equation used to account for both—the mean and the covariance

D mostly used when some subject specific inference is of the main interest

Transition models

- primary interest again with respect to the mean structure
- □ the correlation structure due to historical observations within the subject

All three categories of the regression models for correlated (repeated) observations above lead to the same model (with the same interpretation) for the Gaussian type of the data but for the discrete data different models typically produce different interpretations (due to the non-linearity involved n the models)

In marginal models, the conditional mean structure of the dependent variable is modeled separately from the within subject correlation. In hierarchical models the conditional mean and the correlation of repeated observations is modeled simultaneously.

Marginal models

- □ For simplicity, let $\mathbf{Y}_i = (Y_{i1}, ..., Y_{in_i})^{\top}$ denote a vector of $n_i \in \mathbb{N}$ correlated binary responses for some individual $i \in \{1, ..., N\}$
- □ The idea is to model P[Y_i = y |X_i], for y ∈ {0,1}^{⊗n_i} by using the marginals of the joint distribution (conditionally on X_i)
- **D** The saturated model has $2^{n_i} 1$ parameters and different "marginals"
 - \Box First order marginals $\mu_j = P[Y_{ij} = 1]$, for $j = 1, \ldots, n_i$
 - □ Second order marginals $\mu_{jk} = P[Y_{ij} = 1, Y_{ik} = 1]$, for $j \neq k$
 - **□** Third order marginals $\mu_{jkl} = P[Y_{ij} = 1, Y_{ik} = 1, Y_{ikl} = 1]$, for $j \neq k \neq l$ **□** ...

D The n_i^{th} order marginal $\mu_{1,...,N} = P[\mathbf{Y}_i = \mathbf{1}]$, where $\mathbf{1} = (1,...,1)^\top \in \mathbb{R}^{n_i}$

- □ Which marginals should be used in the model and how should they explain the overall joint probability $P[\mathbf{Y}_i = \mathbf{y} | \mathbb{X}_i]$ (always conditionally on \mathbb{X}_i)
 - □ full log-linear model
 - Iog-linear model for the first and higher order marginals (GEE formulation)
 - Bahadur model for the first order marginals and correlations
 - \Box marginal model for μ_j and marginal odds ratios
 - 🔲 ...

Full log-linear model

- □ the joint probability $P[\mathbf{Y}_i = \mathbf{y}]$ for $\mathbf{y} = (y_1, \dots, y_{n_i})^\top \in \{0, 1\} \times \dots \{0, 1\}$ can be expressed as $P[\mathbf{Y}_i = \mathbf{y}] = P[Y_{i1} = y_1 \land Y_{i2} = y_2 \land \dots \land Y_{in_i} = y_{n_i}]$
- □ there are many options how to define a saturated model (with 2^{n_i} total parameters but only $2^{n_i} 1$ free parameters)
- one commonly used model (proposed by Bishop et al. 1975) is a log-linear model which can be formulated as

$$P[\mathbf{Y}_{i} = \mathbf{y}] = c(\theta_{i}) \exp\left\{\sum_{j=1}^{n} \theta_{ij}^{(1)} y_{j} + \sum_{j_{1} < j_{2}} \theta_{ij_{1}j_{2}}^{(2)} y_{j_{1}} y_{j_{2}} + \dots + \theta_{ij_{1}\dots j_{n_{i}}}^{(n_{i})} y_{j_{1}} \dots y_{j_{n_{i}}}\right\}$$

for $\theta_{i} = (\theta_{i1}^{(1)}, \dots, \theta_{in_{i}}^{(1)}, \theta_{i12}^{(2)}, \dots, \theta_{i1\dots n_{i}}^{(n_{i})})^{\top} \in \mathbb{R}^{2^{n_{i}-1}}$ which is the canonical vector of the unknown model parameters (where $\theta_{ij}^{(1)}$ are conditional log odds and $\theta_{i\dots}^{(k)}$ for $k \geq 2$ are conditional log odds ratios)

□ however, the association between Y_j and Y_k depends on all other values of Y_l for $l \neq j, k$, respectively

$$\log\left[\frac{P[Y_{ij} = 1 | Y_{ik} = y_k, Y_{il} = 0 \forall l \neq j, k]}{P[Y_{ij} = 0 | Y_{ik} = y_k, Y_{il} = 0 \forall l \neq j, k]}\right] = \theta_{ij}^{(1)} + \theta_{ijk}^{(2)} y_k$$

□ it would be more interesting to model $P[Y_j = 1 | \mathbf{X}] = E[Y_j | \mathbf{X}] = \mu_j$ (respectively $P[Y_{ij} = 1 | \mathbf{X}_i] = E[Y_{ij} | \mathbf{X}_i] = \mu_{ij}$, for a given subject $i \in \{1, ..., N\}$)

Log-linear model: Marginal means and the rest

D Technically, the marginal means $\mu_j = P[Y_j = 1 | X]$ can be extracted as

$$\begin{split} \mathcal{P}[\mathbf{Y} = \mathbf{y}] &= c(\theta) \exp\bigg\{\sum_{j=1}^n \theta_j^{(1)} y_j + \dots\bigg\} \\ &= c(\mu, \theta_2) \exp\bigg\{\mathbf{y}^\top \mu + \tilde{\mathbf{y}}^\top \tilde{\theta}\bigg\}, \end{split}$$

where $\boldsymbol{y} = (y_1, \dots, y_n)^{\top}$, $\boldsymbol{\mu} = (\theta_1, \dots, \theta_n)^{\top}$, and $\tilde{\boldsymbol{\theta}} = (\theta_{12}, \dots, \theta_{1...n})^{\top}$ with $\tilde{\boldsymbol{y}} = (y_1y_2, y_1y_3, \dots, \prod_{j=1}^n y_j)^{\top}$ (conditional odds ratios)

An alternative parametrization adopted by Bahadur (1961) where

$$P[\mathbf{Y} = \mathbf{y}] = \prod_{j=1}^{n} \mu_{j}^{y_{j}} (1 - \mu_{j})^{y_{j}} \times \left(1 + \sum_{j < k} \rho_{jk} r_{j} r_{k} + \dots + \rho_{1...n} r_{1} \dots r_{n}\right),$$

here $R_{i} = (\mathbf{Y}_{i} - \mu_{i})/\sqrt{\mu_{i}(1 - \mu_{i})}$ $\rho_{ij} = E[R_{i}R_{j}]$ and so on up to

where $R_j = (Y_j - \mu_j) / \sqrt{\mu_j (1 - \mu_j)}$, $\rho_{jk} = E[R_j R_k]$, and so on, up to $\rho_{1...n} = E[R_1 ... R_n]$ (conditional correlations)

Third alternative: Marginal odds ratios

- □ Conditional odds ratios are unconstrained by the means but they are difficult to interpret and the interpretation depends on the number of repeated observations $n \in \mathbb{N}$
- □ Conditional correlations are straightforward to interpret but they are restricted by the means (in a nontrivial form) and, therefore, also by *X*
- □ An alternative between, proposed by Liang et al.(1992), uses the marginal odds ratios

$$\gamma_{jk} = \frac{P[Y_j = 1, Y_k = 1]P[Y_j = 0, Y_k = 0]}{P[Y_j = 1, Y_k = 0]P[Y_j = 0, Y_k = 1]}$$

and their log-contrasts

$$\begin{split} \zeta_{j_1j_2|j_3} &= \log OR(Y_{j_1}, Y_{j_2}|Y_{j_3} = 1) - \log OR(Y_{j_1}, Y_{j_2}|Y_{j_3} = 0) \\ \zeta_{j_1j_2|j_3j_4} &= \log OR(\cdot|1, 1) - \log OR(\cdot|0, 1) - \log OR(\cdot|1, 0) + \log OR(\cdot|0, 0) \\ \zeta_{j_1j_2|j_3j_4j_5} &= \dots \text{ (expressions become quite complicated-conditioning on all combinations of } Y_{j_h}, Y_{j_k} \text{ and } Y_{j_k}) \end{split}$$

□ The model uses the marginal means μ_1, \ldots, μ_n and the marginal odds ratios γ ... (for simplicity, some restriction is imposed on the γ ... parameters...)

Marginal models towards GEE

Mean structure

The marginal (conditional) expectation of the response depends (non-linearly) on a linear combination of the explanatory variables (i.e., linear predictor)

$$h(\mu_{ij}) = \mathbf{X}_{ij}^{\top} \boldsymbol{\beta}, \quad \text{for } \mu_{ij} = E[Y_{ij} | \mathbf{X}_{ij}] \text{ and } \boldsymbol{\beta} \in \mathbb{R}^{p}$$

for a known, strictly monotone, and twice continuously differentiable function h

Variance structure

The marginal (conditional) variance of the response depends on the marginal mean (and, optionally, some other overdispersion parameter $\phi > 0$) as

$$Var(Y_{ij}|X_{ij}) = v(\mu_{ij})\phi, \text{ for } \phi > 0$$

for a known positive and continuously differentiable function v

Covariance structure

The correlation between two observations Y_{ij} and Y_{ik} (within the same subject $i \in \{1, ..., N\}$) is assumed to be modeled as

$$Cor(Y_{ij}, Y_{ik} | \mathbf{X}_{ij}, \mathbf{X}_{ik}) = \rho(\mu_{ij}, \mu_{ik}, \alpha), \text{ for } \alpha \in \mathbb{R}^{q}$$

for a known covariance function ρ

Key pivots of the marginal models

- □ Instead of specifying the whole distribution (i.e., the exponential family of distributions) which is required, for instance, for the likelihood based estimation in GLM, only a specification of the first two moments (and their mutual relationship) is provided (quasi-likelihood and GEE instead)
- □ For $\mathbf{Y}_i = (\mathbf{Y}_{i1}, \dots, \mathbf{Y}_{in_i})^{\top}$ and $\mathbb{X}_i = (\mathbf{X}_{i1}, \dots, \mathbf{X}_{in_i})^{\top}$ we separately specify the mean $E[\mathbf{Y}_i | \mathbb{X}_i] = \mathbb{X}_i \beta$ and the covariance $Var[\mathbf{Y}_i | \mathbb{X}_i] = \mathbb{V}_i(\mathbb{X}_i, \beta, \phi, \alpha)$
- As the distribution is not provided the likelihood based on the data can not be constructed. Therefore, in a sense, this is not a parametric model (where the parameters specify the whole distribution) but rather a semi-parametric one (the parameters only specify the first two moments)
- □ In a log-linear model (with the first (β) and higher order (α) marginals) the score function for $\beta \in \mathbb{R}^p$ leads to a GEE formulation with the equations

$$rac{\partial oldsymbol{\mu}}{\partial eta^ op} [\mathit{Var}(oldsymbol{Y})]^{-1}(oldsymbol{Y}-oldsymbol{\mu}) = oldsymbol{0}$$

□ Therefore, in order to use the quasi-likelihood estimation approach appropriately, one has to correctly specify both, the mean and the variance-covariance function (structure)

Overview: Maximum likelihood for GLM

- □ for some generic random vector $(Y, \mathbf{X}^{\top})^{\top} \sim F_{(Y, \mathbf{X})}$ we assume that $f(y|\mathbf{X}) = \exp\{\phi^{-1}(y\theta \psi(\theta)) + c(y, \phi)\}$ (i.e., the exponential family)
- □ the linear predictor $\theta = \mathbf{X}^{\top}\beta$ is associated with the conditional mean $E[Y|\mathbf{X}] = \mu$ via the link function g, such that $g(\mu) = \theta \equiv \theta(\beta) = \mathbf{X}^{\top}\beta$
- □ as far as $f(y|\mathbf{X})$ is a probability density function, it holds that $\int (y|\mathbf{X}) dy = 1$ (by integrating with respect to an appropriate measure)
- □ thus, the first and the second partial derivatives of $\int (y|\mathbf{X}) dy = 1$ with respect to θ (scores) yield the following two equations

$$\frac{\partial}{\partial \theta} : \int [y - \psi'(\theta)] f(y|\mathbf{X}) dy = 0$$

and

$$rac{\partial^2}{\partial heta^2} : \int [\phi^{-1}(y - \psi'(heta))^2 - \psi''(heta)]f(y|oldsymbol{X}) \mathrm{d}y = 0$$

which gives $\mu = E[Y|X] = \psi'(\theta)$ and $Var[Y|X] = \phi \psi''[(\psi')^{-1}(\mu)]$

Score equations under MLE

- □ for the random sample $\mathcal{D}_{S} = \{(Y_{i}, X_{i}); i = 1, ..., N\}$ we have $f(y|X_{i}) = \exp\{\phi^{-1}(y\theta_{i} - \psi(\theta_{i})) + c(y, \phi)\}$ where $\theta_{i} = X_{i}^{\top}\beta \equiv \theta_{i}(\beta)$
- □ as $\theta_i = \mathbf{X}_i^\top \beta$ and we aim to estimate the unknown parameter vector $\beta \in \mathbb{R}^p$, we need partial derivatives with respect to $\beta \in \mathbb{R}^p$
- Log-likelihood

$$\ell(eta,\phi,\mathcal{D}_{\mathcal{S}}) = rac{1}{\phi}\sum_{i=1}^{N}[Y_i heta_i-\psi(heta_i)] + \sum_{i=1}^{N}c(Y_i,\phi)$$

 \Box First order derivatives wrt. β

$$\frac{\partial \ell(\boldsymbol{\beta}, \phi, \mathcal{D}_{\boldsymbol{\mathcal{S}}})}{\partial \boldsymbol{\beta}} = \frac{1}{\phi} \sum_{i=1}^{N} \frac{\partial \theta_i}{\partial \boldsymbol{\beta}} [\boldsymbol{Y}_i - \psi'(\theta_i)]$$

Score equations for β

$$\mathcal{S}(oldsymbol{eta}) = \sum_{i=1}^{N} rac{\partial heta_i}{\partial oldsymbol{eta}} [Y_i - \psi'(heta_i)] = \mathbf{0}$$

Score equations under MLE – continuation

• since $\mu_i = \psi'(\theta_i)$ and $v_i = v(\mu_i) = \psi''(\theta_i)$ the score equations become $S(\beta) = \sum_{i=1}^{N} \frac{\partial \mu_i}{\partial \beta} v_i^{-1} [Y_i - \psi'(\theta_i)] = \mathbf{0}$

and, thus, the estimation of $\beta \in \mathbb{R}^{\rho}$ depends on the exponential distribution only through the mean μ_i and the variance function $v_i = v(\mu_i)$

- the solution to the equations above is obtained numerically (e.g., Newton-Raphson, iterative re-weighted LS, Fisher scoring)
- □ the inference about $\beta \in \mathbb{R}^{\rho}$ is based on the classical maximum likelihood theory (i.e., asymptotic Wald tests, likelihood ratio tests, score tests)
- Let the estimation of the over-dispersion parameter based on residuals

$$\widehat{\phi} = \frac{1}{N - p} \sum_{i=1}^{N} \frac{[Y_i - \widehat{\mu}_i]^2}{v_i(\widehat{\mu}_i)}$$

General Estimating Equations (GEE)

□ for independent observations Y_1, \ldots, Y_N (within the GLM framework) the corresponding score equations for estimating $\beta \in \mathbb{R}^p$ are

$$S(\boldsymbol{\beta}) = \sum_{i=1}^{N} \frac{\partial \mu_i}{\partial \boldsymbol{\beta}} \mathsf{v}_i^{-1} [Y_i - \mu_i] = \mathbf{0}$$

□ for longitudinal observations Y_1, \ldots, Y_n (within the GEE framework) the score equations for $\beta \in \mathbb{R}^p$ can be seen as a multivariate extension

$$\mathcal{S}(oldsymbol{eta}) = \sum_{i=1}^N \sum_{j=1}^{n_i} rac{\partial \mu_{ij}}{\partial oldsymbol{eta}} \mathsf{v}_{ij}^{-1}[Y_{ij} - \mu_{ij}] = oldsymbol{0}$$

which can be also expressed in a more common (as a sum of independent subjects) matrix notation

$$\mathcal{S}(\boldsymbol{\beta}) = \sum_{i=1}^{N} \mathbb{D}_{i}^{\top} [\mathbb{V}_{i}(\boldsymbol{\alpha})]^{-1} [\boldsymbol{Y}_{i} - \boldsymbol{\mu}_{i}] = \boldsymbol{0}$$
where $\mathbb{D}_{i} = \left(\frac{\partial \mu_{ij}}{\partial \beta_{k}}\right)_{j,k=1}^{n_{i},p}$ and $\mathbb{V}_{i}(\boldsymbol{\alpha}) \equiv \mathbb{V}_{i}(\mathbb{X}_{i}, \boldsymbol{\beta}, \boldsymbol{\phi}, \boldsymbol{\alpha})$

Correlation structure within $\mathbf{Y}_i \in \mathbb{R}^{n_i}$

□ Note, that the variance matrix *Var*[*Y*_{*i*}|X_{*i*}] is relatively complex and specific structural decomposition is typically used to model the variance-covariance structure more carefully

 $Var[\boldsymbol{Y}_i|\mathbb{X}_i] = \mathbb{V}_i(\mathbb{X}_i, \boldsymbol{\beta}, \boldsymbol{\phi}, \boldsymbol{\alpha}) = \boldsymbol{\phi} \mathbb{A}_i^{1/2}(\boldsymbol{\beta}) \mathbb{R}_i(\boldsymbol{\alpha}) \mathbb{A}_i^{1/2}(\boldsymbol{\beta})$

where the matrix $\mathbb{A}_i^{1/2}(\beta)$ models the variance of the repeated observations for the given subject $i \in \{1, ..., N\}$

$$\mathbb{A}_i^{1/2}(\boldsymbol{\beta}) = \left(\begin{array}{ccc} \sqrt{\mathsf{v}_{i1}(\mu_{i1})} & \dots & \mathbf{0} \\ \vdots & \ddots & \vdots \\ \mathbf{0} & \dots & \sqrt{\mathsf{v}_{in_i}(\mu_{in_i})} \end{array}\right)$$

and the correlation of the repeated observations is modeled by $\mathbb{R}_i(lpha)$

Recall, that the covariances and variances follow from the mean structure... for modeling purposes we specify the mean structure and the correlations (i.e., the working correlation matrix)

Statistical properties and inference

□ the GEE estimates of $\beta \in \mathbb{R}^{p}$ are consistent even if the working correlation matrix is incorrect (they may not be efficient though!)

$$\sqrt{N}(\widehat{\beta}_N - \beta) \underset{as.}{\sim} N_{\rho}(\mathbf{0}, \mathbb{I}_0^{-1} \mathbb{I}_1 \mathbb{I}_0^{-1})$$

where \mathbb{I}_0 is the limit matrix of $\sum_{i=1}^{N} \mathbb{D}_i^{\top} [\mathbb{V}_i(\beta)]^{-1} \mathbb{D}_i$ and, analogously also \mathbb{I}_1 is the limit matrix of $\sum_{i=1}^{N} \mathbb{D}_i^{\top} [\mathbb{V}_i(\beta)]^{-1} Var(\mathbf{Y}_i) [\mathbb{V}_i(\beta)]^{-1} \mathbb{D}_i$

- □ note that if the variance matrix $Var(Y_i)$ is correctly specified, the asymptotic variance only reduces to \mathbb{I}_0^{-1} (i.e., the likelihood variance)
- □ the estimate for \mathbb{I}_1 can be obtained by replacing $Var(\mathbf{Y}_i)$ by $(\mathbf{Y}_i \hat{\mu}_i)(\mathbf{Y}_i \hat{\mu}_i)^\top$ which usually leads to a good estimate of \mathbb{I}_1 even if it is a bad estimate for $Var(\mathbf{Y}_i)$

Alternatives and extensions

Prentice's two sets of GEE

(two sets of GEE equations—one to obtain the estimates for β and the other one to get the estimates for α)

GEE based on linearization

(linearization in a form of $Y_{ij} = \mu_{ij} + \varepsilon_{ij}$, where $\varepsilon_{ij} = \mu_{ij}$ with probability $1 - \mu_{ij}$ and $\varepsilon_{ij} = 1 - \mu_{ij}$ with probability μ_{ij})

□ GEE2 up to GGEk generalizations

(extended marginal mean structure considering the first and second (possibly up to kth order) marginals and pairwise associations)

Alternating Logistic Regression (ALR)

(parameters β and α are estimated in two separate alternating regression formulations that are iterated until convergence)

Summary

- Marginal models for correlated observations are specifically suitable for population interpretation and population based inference
- □ Different strategies can be used to build the model using the marginals of the joint distribution $P[\mathbf{Y}_i = \mathbf{y} | \mathbb{X}_i]$ for some $\mathbf{y} \in \mathbb{R}^{n_i}$
- Different models imply different interpretation of the estimated parameters and also different limitations for a practical utilization
- □ For a subject specific interpretation another models need to be used for instance, models with random effects