

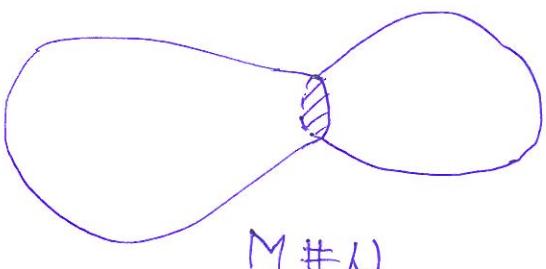
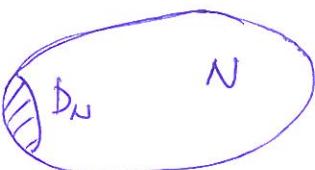
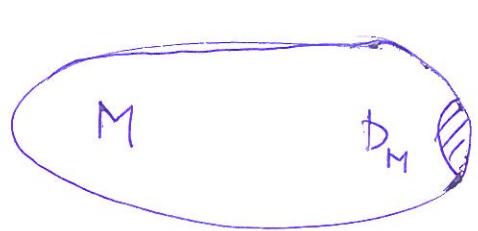
SURFACE TOPOLOGY

RH1

We give an informal account. For more details, see e.g. [Hirsch M.W., Differential Topology, Springer, N.Y., 1994].

Let M, N be compact, connected and orientable surfaces. Here a surface means a topological surface (the same definition as for RS but we make no assumption on transition functions, they are just homeomorphisms).

We define the connected sum $M \# N$ as follows. We choose small discs D_M^* in M and D_N in N and cut them out. Then we glue the boundary circles of D_M and D_N together to form $M \# N$, see the figure below:

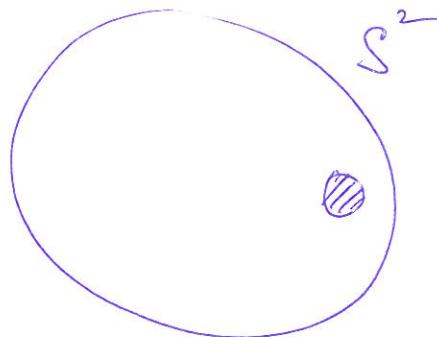


$$\xrightarrow{*} D_M \approx D_N$$

Examples

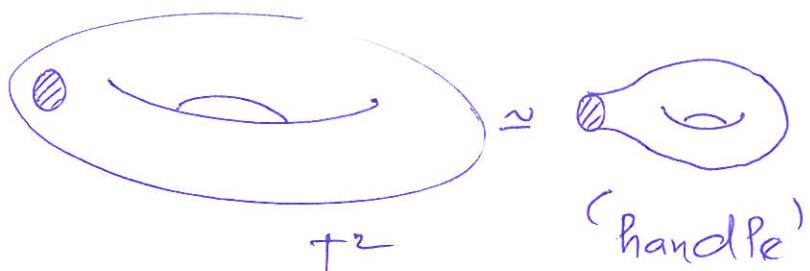
- $\Sigma_0 := S^2$

the unit spheres in \mathbb{R}^3



- $\Sigma_1 := S^2 \# T^2 \simeq T^2$

the tori
in \mathbb{R}^3



- $\Sigma_2 := S^2 \# T^2 \# T^2 \simeq T^2 \# T^2 \simeq$



Define inductively $\Sigma_{g+1} := \Sigma_g \# T^2$, $g \in \mathbb{N}_0$.

so we get Σ_g by adding g handles to the sphere S^2 .

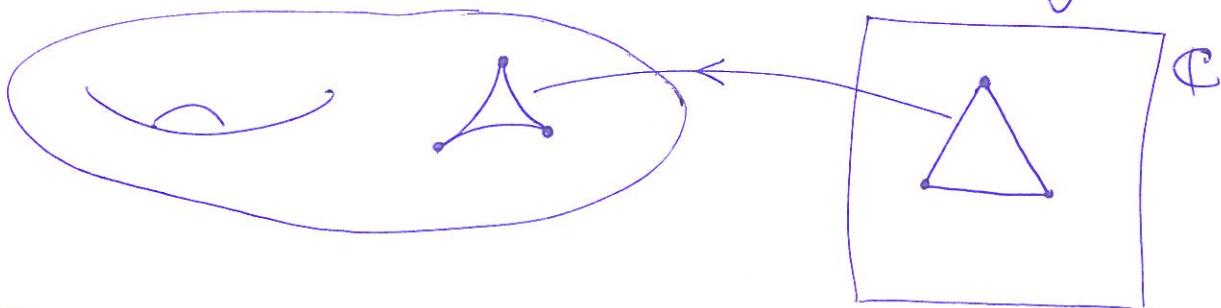
Theorem: If X is a compact, connected and orientable surface then there is a unique $g \in \mathbb{N}_0$ such that $X \simeq \Sigma_g$. We write $g(X) := g$ and call it the genus of X . Here \simeq means the topological equivalence (i.e., being homeomorphic to).

Remark: In particular, this is true for $\mathbb{R}S^1$.

The Euler characteristic

Let X be a compact, connected and orientable surface. It is known that X has a finite triangulation, i.e., there are (triangles) $\Delta_1, \dots, \Delta_k$ on X such that $X = \bigcup_{j=1}^k \Delta_j$ and

- each Δ_j is homeomorphic to a closed non-trivial triangle in \mathbb{C} ; so it is clear what are the vertices and the edges of Δ_j .



- for if $j, \Delta_i \cap \Delta_j$ is either \emptyset , the common vertex, or the common edge.
- every edge of the triangulation is common just to two triangles

defines
$$\chi(X) := V - E + F$$

where V is the number of the vertices

E ——— ——— edges) and
 F ——— ——— triangles (faces)
 of the given triangulation on X .

Theorem

$\chi(X)$ does not depend on the

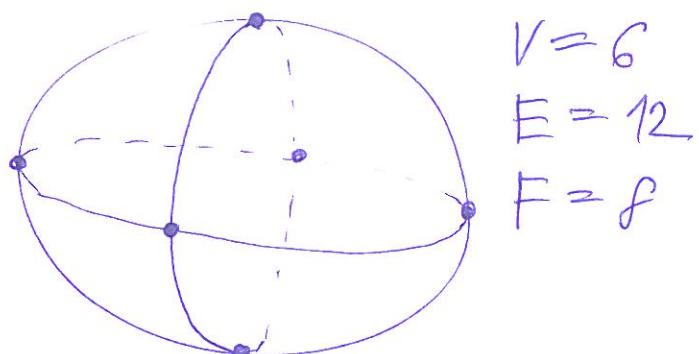
RH4

choice of a triangulation of X , it is
a topological invariant.

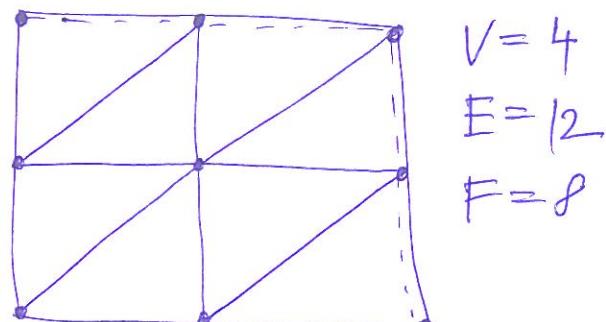
We call $\chi(X)$ the Euler characteristic of X .

Examples

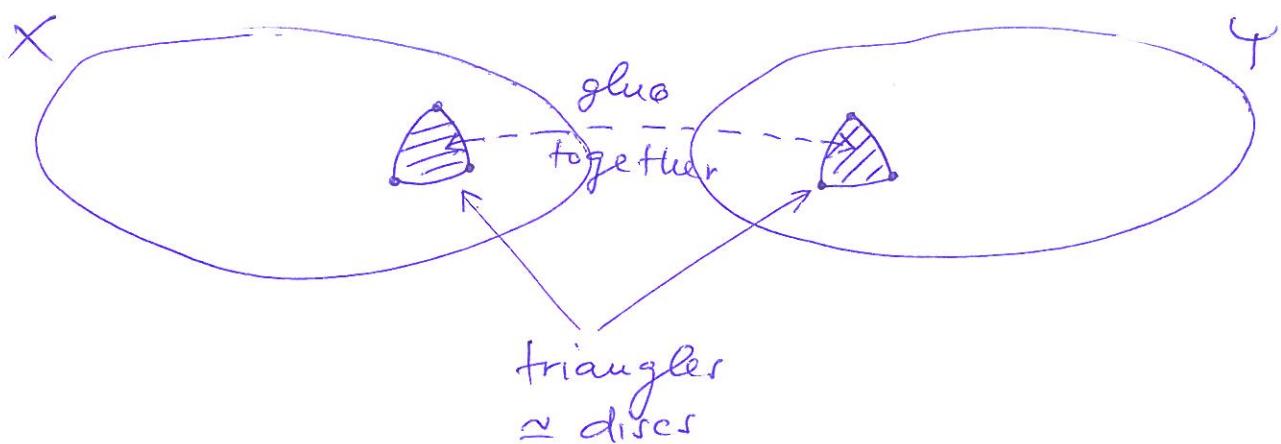
① $\chi(S^2) = 2$



② $\chi(T^2) = 0$



③ $\chi(X \# Y) = \chi(X) + \chi(Y) - 2$



$$V = V_x + V_y - 3$$

$$E = E_x + E_y - 3$$

$$F = F_x + F_y - 2$$

$$④. \quad \boxed{\chi(\Sigma_g) = 2 - 2g}$$

RHS

Indeed, by ③, we have $\chi(\Sigma_g) = \chi(\Sigma_{g-1}) - 2$

Riemann - Hurwitz THEOREM.

THEOREM Let $f : X \rightarrow Y$ be a non-constant holomorphic map between compact and connected R.S.s. Then

$$(RH) \quad \chi(X) = \deg(f) \chi(Y) - b(f)$$

where the branching index $b(f)$ is defined by

$$b(f) := \sum_{x \in X} (n_f(x) - 1).$$

Here $n_f(x)$ is the multiplicity of f at x or its value at x .

Remark: d) $b(f) = \sum_{x \in X} (n_f(x) - 1) =$

x is a critical point for f

(only finitely many)

$$= \sum_{y \in Y} \sum_{\substack{x \in f^{-1}(y) \\ [y] \text{ is a critical value for } f}} (n_f(x) - 1) = \sum_{y \in Y} (\deg(f) - |f^{-1}(y)|).$$

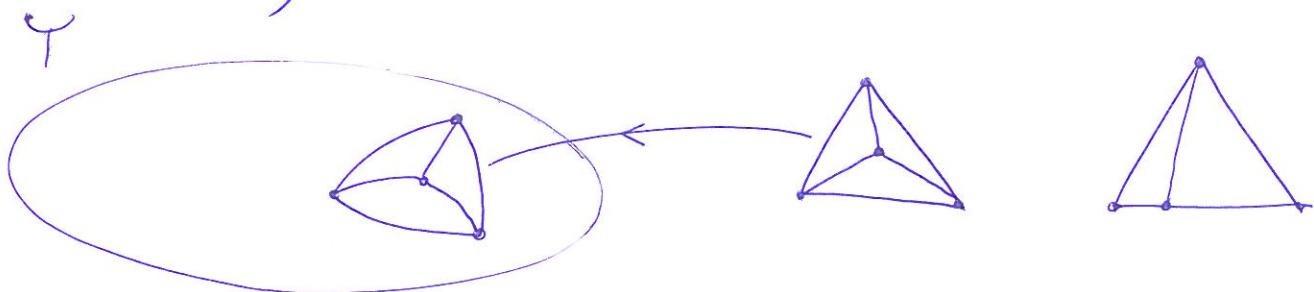
Here $|A|$ is the number of elements of a set RHS

A. Hence, for a given $y \in Y$, $\deg(f)$ is the number of solutions of $y = f(x)$ if multiplications are counted but $|f^{-1}(y)|$ is the number of 'real' solutions of the same equation. To summarize, $b(f)$ is the total number of 'missing' solutions.

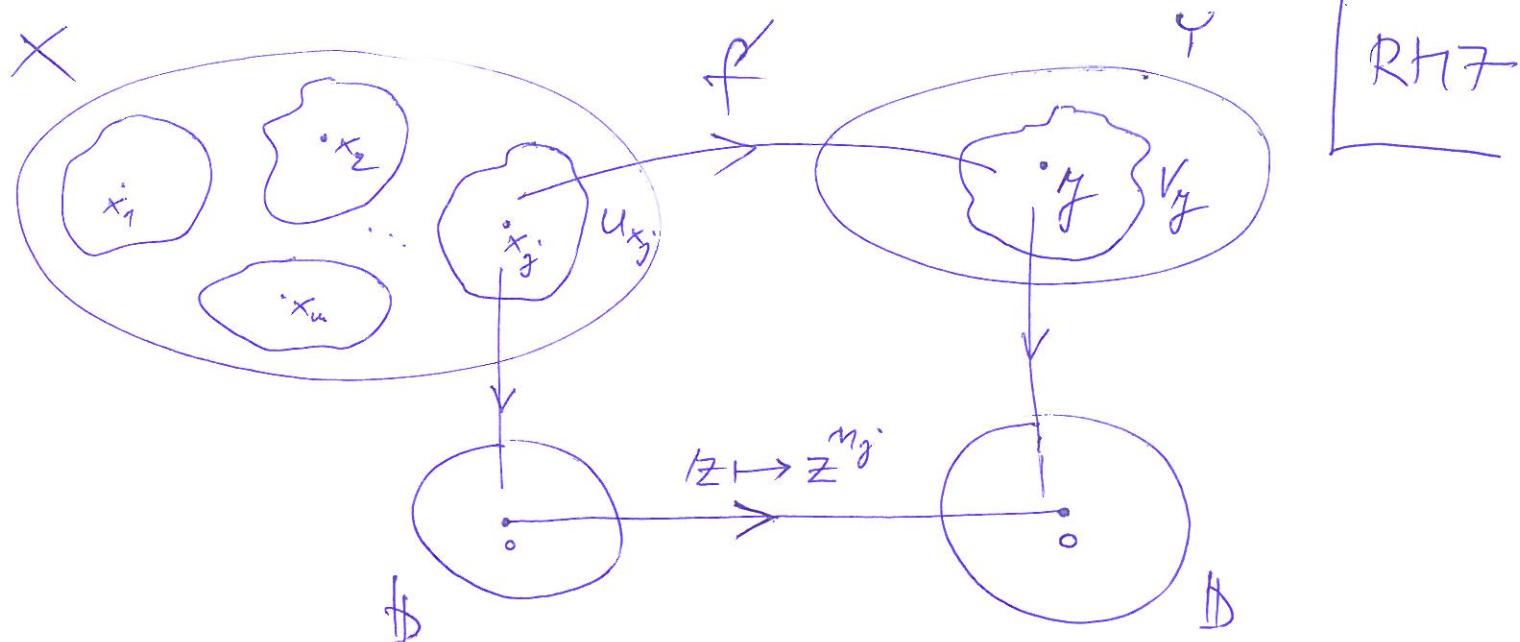
(ii) By Theorem, $b(f)$ is even.

Proof (sketch): Let us consider a triangulation $\Delta_1, \dots, \Delta_k$ of Y .

(i) WLOG, we can assume that all critical values of f are vertices of the given triangulation. Otherwise, we refine it.



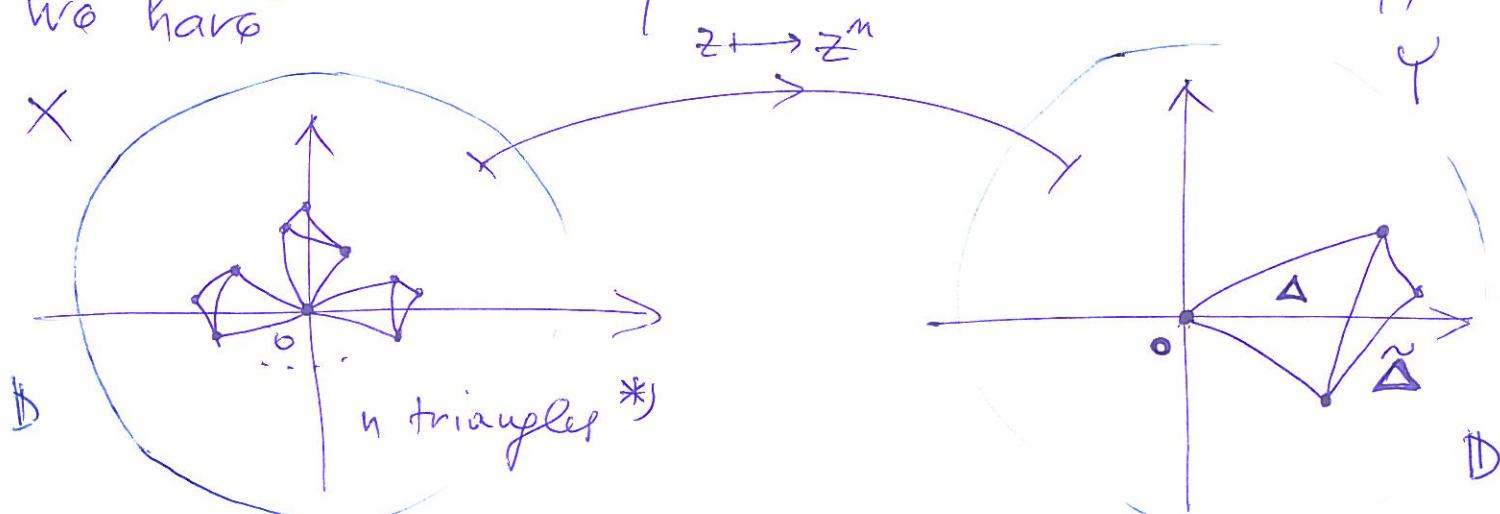
(ii) Let $y \in Y$ and $f^{-1}(y) = \{x_1, \dots, x_n\}$. There are an open set V_y in Y and pairwise disjoint open sets U_{x_1}, \dots, U_{x_n} in X such that $y \in V_y$, $x_j \in U_{x_j}$, and each $f|_{U_{x_j}}: U_{x_j} \xrightarrow{\text{onto}} V_y$ looks like $z \mapsto z^{m_j}$ for some $m_j \in \mathbb{N}$. See a proof of Theorem on degrees.



Choose a finite subcover V_{y_1}, \dots, V_{y_r} of Y .

WLOG, we can assume that every triangle of the given triangulation of Y lies in a certain V_{y_j} .

(iii) Then the preimage of the triangulation of Y under f gives a triangulation of X . Locally, we have



Then $F_X = \deg(f) F_Y$, $E_X = \deg(f) E_Y$,

$$V_X = \deg(f) V_Y - b(f).$$

Indeed, $f^{-1}(\Delta)$ has $2 \cdot \deg(f) + |f^{-1}(\Delta)| = \beta \cdot \deg(f) - (\deg(f) - |f^{-1}(\Delta)|)$ vertices.

* We can lift ~~connected~~ simply connected spaces. 