

2.5 Parameterizations of a linear model

DATA: $(Y_i, Z_i^T)^T, i=1, \dots, n$
(that we primarily observe)

remember: $X_i = t(Z_i)$ are regressors used
in the model that allow to assume
 $E(Y_i | Z_i = z) = X_i^T \beta, X_i = t(Z_i)$
for some β

- one set Z_1, \dots, Z_n of observed covariates
→ ∞ many different sets of regressors
 X_1, \dots, X_n can be proposed (based
on different transformations t)
→ not necessarily "different" models

Def. 2.7 Equivalent linear models

Assume two linear models

$M_1: Y | X_1 \sim (X_1 \beta, \sigma^2 I_n), X_1$ matrix $n \times k, \text{rank}(X_1) = r,$

$M_2: Y | X_2 \sim (X_2 \beta, \sigma^2 I_n), X_2$ matrix $n \times \ell, \text{rank}(X_2) = r.$

We say that models M_1 and M_2 are equivalent
if their regression spaces are the same.
That is, if $\mathcal{N}(X_1) = \mathcal{N}(X_2).$

equivalent models

$$\Rightarrow \bullet H = X_1 (X_1^T X_1)^{-1} X_1^T = X_2 (X_2^T X_2)^{-1} X_2^T$$

• same \hat{Y} , U , SSE , MSE , ...

- two (or more) different parameterizations of the same situation

- different interpretation of regression coefficients

Example 1 Change of units of regressor

Y = consumption of a car [l/100km]

Z = weight of a car [kg] $\rightarrow z_1, \dots, z_n$

$$X_1 = Z \quad M_1: E(Y|Z=z) = \beta_0 + \beta_1 z$$

$$X_1 = \begin{pmatrix} 1 & z_1 \\ \vdots & \vdots \\ 1 & z_n \end{pmatrix} \quad \beta_1 = \text{change in } E(Y|\dots) \text{ related to } 1 \text{ kg change in a weight}$$

$$X_2 = \frac{Z}{1000} \quad (= \text{weight in tons})$$

$$M_2: E(Y|Z=z) = \beta_0 + \beta_1 \left(\frac{z}{1000}\right)$$

$$X_2 = \begin{pmatrix} 1 & \frac{z_1}{1000} \\ \vdots & \vdots \\ 1 & \frac{z_n}{1000} \end{pmatrix} \quad \beta_1 = \text{change in } E(Y|\dots) \text{ related to } 1 \text{ ton change in a weight}$$

Example 2 Two sample problem

$Y = \text{height [cm]}$

$Z = \text{gender} \in \{0, 1\} \rightarrow z_1, \dots, z_n$

(WLG): upon reordering of data

$$\begin{pmatrix} z_1 \\ \vdots \\ z_{n_0} \\ z_{n_0+1} \\ \vdots \\ z_{n_0+m_1} \end{pmatrix} = \begin{pmatrix} 0 \\ \vdots \\ 0 \\ 1 \\ \vdots \\ 1 \end{pmatrix}$$

- we need to "model" $E(Y|Z=z)$, $z \in \{0, 1\}$
 $\rightarrow \mu_0 := E(Y|Z=0)$, $\mu_1 := E(Y|Z=1)$

- regression space

$$= \left\{ \begin{pmatrix} \mu_0 \\ \vdots \\ \mu_0 \\ \mu_1 \\ \vdots \\ \mu_1 \end{pmatrix} : \mu_0, \mu_1 \in \mathbb{R} \right\}$$

\rightarrow any model matrix X , whose $\mathcal{R}(X)$ is the above space must be of the form

$$X = \begin{pmatrix} x_0^T \\ \vdots \\ x_0^T \\ x_1^T \\ \vdots \\ x_1^T \end{pmatrix} \quad \begin{array}{l} x_0 \neq 0 \\ x_1 \neq 0 \\ x_0 \neq x_1 \end{array}$$

with $\text{rank}(X) = 2$

\rightarrow if used in a linear model $\mu_0 = x_0^T \beta$
 $\mu_1 = x_1^T \beta$

POSSIBLE CHOICES OF x_0, x_1

(i) Group means, $\beta = (\beta_0, \beta_1)^T$

$$x_0 = (1, 0)^T \rightarrow \mu_0 = x_0^T \beta = \beta_0$$

$$x_1 = (0, 1)^T \rightarrow \mu_1 = x_1^T \beta = \beta_1$$

(ii) ~~Group~~ Group differences, $\beta = (\beta_0, \beta_1)^T$

$$x_0 = (1, 0)^T \rightarrow \mu_0 = x_0^T \beta = \beta_0$$

$$x_1 = (1, 1)^T \rightarrow \mu_1 = x_1^T \beta = \beta_0 + \beta_1$$

$$\beta_0 = \mu_0$$

$$\beta_1 = \mu_1 - \mu_0$$

(iii) Deviations from the means of the means, $\beta = (\beta_0, \beta_1)^T$

$$x_0 = (1, 1)^T \rightarrow \mu_0 = x_0^T \beta = \beta_0 + \beta_1$$

$$x_1 = (1, -1)^T \rightarrow \mu_1 = x_1^T \beta = \beta_0 - \beta_1$$

$$\beta_0 = \frac{\mu_0 + \mu_1}{2}$$

$$\beta_1 = \mu_0 - \frac{\mu_0 + \mu_1}{2}$$

$$= \frac{\mu_0 + \mu_1}{2} - \mu_1$$

(iv) Orthonormal basis, $\beta = (\beta_0, \beta_1)^T$

$$x_0 = \left(\frac{1}{\sqrt{n_0}}, 0 \right)$$

$$x_1 = \left(0, \frac{1}{\sqrt{n_1}} \right)$$

$$X = \begin{pmatrix} \frac{1}{\sqrt{n_0}} & 0 \\ \vdots & \vdots \\ \frac{1}{\sqrt{n_0}} & 0 \\ 0 & \frac{1}{\sqrt{n_1}} \\ \vdots & \vdots \\ 0 & \frac{1}{\sqrt{n_1}} \end{pmatrix} \begin{matrix} n_0 \text{ rows} \\ \\ \\ n_1 \text{ rows} \end{matrix}$$

(= Q)

$$\rightarrow \mu_0 = x_0^T \beta = \frac{1}{\sqrt{m_0}} \beta_0$$

$$\beta_0 = \sqrt{m_0} \cdot \mu_0$$

$$\mu_1 = x_1^T \beta = \frac{1}{\sqrt{m_1}} \beta_1$$

$$\beta_1 = \sqrt{m_1} \cdot \mu_1$$

Easy homework:

$$\vec{Y} = \begin{pmatrix} Y_1 \\ \vdots \\ Y_{m_0} \\ Y_{m_0+1} \\ \vdots \\ Y_{m_0+m_1} \end{pmatrix}$$

$$\bar{Y}_0 := \frac{1}{m_0} \sum_{i=1}^{m_0} Y_i$$

$$\bar{Y}_1 := \frac{1}{m_1} \sum_{i=m_0+1}^{m_0+m_1} Y_i$$

$$\vec{\beta} = \begin{pmatrix} \beta_0 \\ \beta_0 \\ \beta_1 \\ \beta_1 \\ \vdots \\ \beta_1 \end{pmatrix}$$

$$SS_e = \sum_{i=1}^{m_0} (Y_i - \bar{Y}_0)^2 + \sum_{i=m_0+1}^{m_0+m_1} (Y_i - \bar{Y}_1)^2$$

$$\nu_e = n - 2$$

2.6 Matrix algebra and a method of least squares

Linear model $Y|X \sim (X\beta, \sigma^2 I_n)$

$$\text{rank}(X_{n \times k}) = k$$

Quantities to calculate for the LSE:

$$H = X(X^T X)^{-1} X^T, \quad M = I_n - H$$

$$\hat{Y} = HY = X(X^T X)^{-1} X^T Y$$

$$\text{var}(\hat{Y}|X) = \sigma^2 H = \sigma^2 [X(X^T X)^{-1} X^T]$$

$$U = MY = Y - \hat{Y}$$

$$\text{var}(U|X) = \sigma^2 M = \sigma^2 (I_n - H)$$

$$\hat{\beta} = (X^T X)^{-1} X^T Y, \quad \text{var}(\hat{\beta}|X) = \sigma^2 (X^T X)^{-1}$$

→ QR decomposition

→ SVD decomposition

of X

QR & LSE

$$\text{rank}(X_{n \times k}) = k \rightarrow X = Q \cdot R$$

$$Q_{n \times k} = (q_1, \dots, q_k)$$

= orthonormal basis of $\mathcal{R}(X)$

$$R = \text{upper } \Delta$$

$$Q^T Q = I_k, \quad \underline{Q \cdot Q^T = H}$$

$$X^T X = R^T \underbrace{Q^T Q}_I R = R^T R$$

\equiv Cholesky (square root) decomposition of $X^T X$,
special case of LU decomp.

$$(X^T X)^{-1} = (R^T R)^{-1} = \underbrace{R^{-1} (R^{-1})^T}_{\text{easy}}$$

$$\det(X^T X) = \det(R^T R) = (\det R)^2 = \left(\prod_{j=0}^{k-1} r_{jj} \right)^2$$

$$\det((X^T X)^{-1}) = (\det(X^T X))^{-1}$$

• solution to normal eq.

$$X^T X \beta = X^T Y$$

$$R^T R \beta = R^T Q^T Y$$

$$\textcircled{R} \beta = \underbrace{Q^T Y}_{\text{RHS}}$$

Δ

\hookrightarrow easy to solve

• meaning of $c = Q^T Y = (c_1, \dots, c_k)^T$ (effects in R)

$$\hat{Y} = H Y = Q \cdot \underbrace{Q^T Y}_c = \sum_{j=1}^k c_j q_j$$

\downarrow coeffs. of linear combination
for basis of $\mathcal{V}(X)$
to get \hat{Y}