

The Numerical Stability of Block CGS Variants

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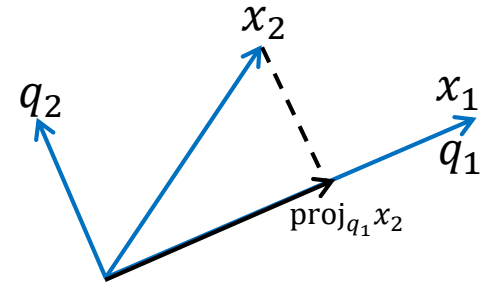
The Gram-Schmidt process

Given a set of linear independent vectors x_1, \dots, x_n , we want to compute a set of orthogonal vectors q_1, \dots, q_n such that $\text{span}\{x_1, \dots, x_n\} = \text{span}\{q_1, \dots, q_n\}$

Gram-Schmidt process:

$$q_1 = x_1, \quad q_k = x_k - \sum_{j=1}^{k-1} \frac{\langle q_j, x_k \rangle}{\|q_j\|^2} q_j, \quad k \geq 2$$

To get orthonormal vectors, $\hat{q}_k = q_k / \|q_k\|$, for all k



Each vector x_k can be expressed as a linear combination of q_1, \dots, q_k .

So with $X = [x_1 \cdots x_n]$, $Q = [q_1 \cdots q_n]$, this means we can write

$$X = QR,$$

where columns of R give the coefficients of the aforementioned linear combinations, and thus R is upper triangular.

Finite Precision

- What happens in finite precision?
 - On a real computer, every time we perform a floating point operation, we may incur a small roundoff error
 - Over a whole computation, these tiny errors can accumulate or can be amplified
 - The result:
 - \bar{Q} no longer has exactly orthonormal columns!
 - $\bar{Q}\bar{R}$ is no longer exactly the same as X !
 - This can affect applications downstream

Measures of Error

Let \bar{Q} and \bar{R} denote computed QR factors of a matrix X .

How far is \bar{Q} from having orthonormal columns?

“Loss of orthogonality”: $\|I - \bar{Q}^T \bar{Q}\|$

How close is $\bar{Q}\bar{R}$ to X ?

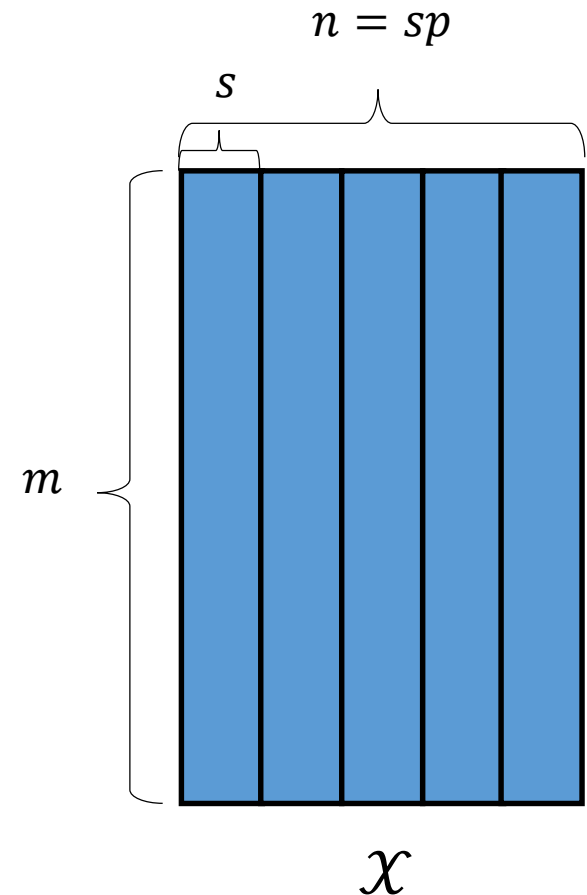
Relative residual norm: $\frac{\|X - \bar{Q}\bar{R}\|}{\|X\|}$

How close is $\bar{R}^T \bar{R}$ to $X^T X$?

Relative Cholesky residual norm: $\frac{\|X^T X - \bar{R}^T \bar{R}\|}{\|X\|^2}$

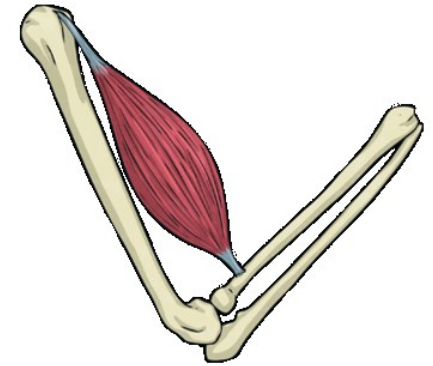
Block Gram-Schmidt

- Sometimes we may want to use a block version of Gram-Schmidt
- Performance reasons (e.g., BLAS3)
- Block Krylov subspace methods
 - Better convergence
 - Simultaneously solve multiple RHSes
- s -step Krylov subspace methods



- How do we define a block Gram-Schmidt algorithm?
- We need 2 parts:
 - The “skeleton”: A block Gram-Schmidt algorithm for interblock orthogonalization
 - The “muscle”: A non-block orthogonalization algorithm for intrablock orthogonalization (“local QR”, “panel factorization”)
 - Need not be Gram-Schmidt-based
 - We will refer to this routine as “**IntraOrtho()**”
- For example: block CGS (BCGS) for orthogonalizing between blocks, Householder QR for orthogonalizing within blocks:

$$\text{BCGS} \circ \text{HouseQR}(\mathcal{X})$$



<https://www.twinkl.com/illustration/contracted-muscle-arm-bone-skeleton-movement-anatomy-biceps-science-ks2>

Notation

- Calligraphic letters for the whole block matrices ($\mathcal{X}, \mathcal{Q}, \mathcal{R}$)
- Regular letters for the individual block quantities (X, Q, R)
- Bars denote computed (inexact) quantities

- m : number of rows in input matrix
- n : number of columns in input matrix ($n = ps$)
- p : number of blocks
- s : number of columns per block

$$m \geq n > p > s$$

$$\mathcal{X} = [X_1, X_2, \dots, X_p], \quad \mathcal{X} \in \mathbb{R}^{m \times n}, \quad X_i \in \mathbb{R}^{m \times s}$$

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Economic QR factorization: $\mathcal{X} = \mathcal{Q}\mathcal{R}$, $\mathcal{Q} \in \mathbb{R}^{m \times n}$, $\mathcal{R} \in \mathbb{R}^{n \times n}$

$$\mathcal{Q} = [Q_1, Q_2, \dots, Q_p], \quad \mathcal{R} = \begin{bmatrix} R_{1,1} & R_{1,2} & \cdots & R_{1,p} \\ & R_{2,2} & \cdots & R_{2,p} \\ & & \ddots & \vdots \\ & & & R_{p,p} \end{bmatrix}$$

$$Q_{1:j} = [Q_1, \dots, Q_j], \quad R_{1:j,k} = \begin{bmatrix} R_{1,k} \\ \vdots \\ R_{j,k} \end{bmatrix}$$

CGS and CGS-P

- Pessimistic bound due to [Kiełbasiński, 1974]: If $O(\varepsilon)\kappa(X) < 1$,

$$\|I - \bar{Q}^T \bar{Q}\| \leq O(\varepsilon)\kappa^{s-1}(X)$$

for $X \in \mathbb{R}^{m \times s}$

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$$\begin{aligned} R_{1:k,k+1} &= Q_{1:k}^T x_{k+1} \\ w &= x_{k+1} - Q_{1:k} R_{1:k,k+1} \end{aligned}$$

Let $\phi = \|x_{k+1}\|$, $\psi = \|R_{1:k,k+1}\|$

CGS:

$$R_{k+1,k+1} = \|w\| \left(= \sqrt{\phi^2 - \psi^2} \right)$$

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CGS:

$$R_{k+1,k+1} = \|w\| \left(= \sqrt{\phi^2 - \psi^2} \right)$$

CGS-P:

$$R_{k+1,k+1} = \sqrt{\phi - \psi} \cdot \sqrt{\phi + \psi}$$

Block CGS

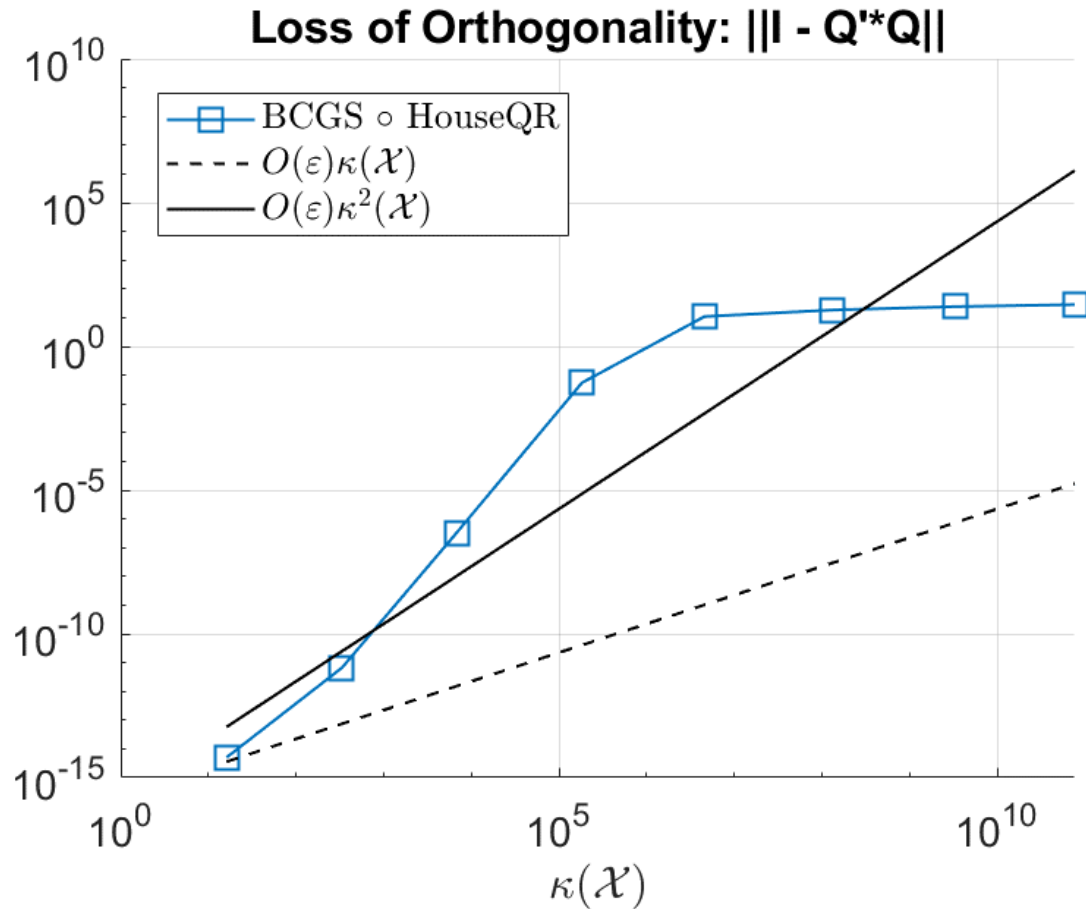
```
[ $\mathcal{Q}$ ,  $\mathcal{R}$ ] = BCGS( $\mathcal{X}$ )
1: [ $\mathbf{Q}_1, R_{11}$ ] = IntraOrtho( $\mathbf{X}_1$ )
2: for  $k = 1, \dots, p - 1$  do
3:    $\mathcal{R}_{1:k, k+1} = \mathcal{Q}_{1:k}^T \mathbf{X}_{k+1}$ 
4:    $\mathbf{W} = \mathbf{X}_{k+1} - \mathcal{Q}_{1:k} \mathcal{R}_{1:k, k+1}$ 
5:   [ $\mathbf{Q}_{k+1}, R_{k+1, k+1}$ ] = IntraOrtho( $\mathbf{W}$ )
6: end for
7: return  $\mathcal{Q} = [\mathbf{Q}_1, \dots, \mathbf{Q}_p]$ ,  $\mathcal{R} = (R_{jk})$ 
```

No existing proof of the loss of orthogonality in BCGS!

Conjecture: Even if our IntraOrtho has $O(\varepsilon)$ loss of orthogonality, BCGS is just as bad as CGS:

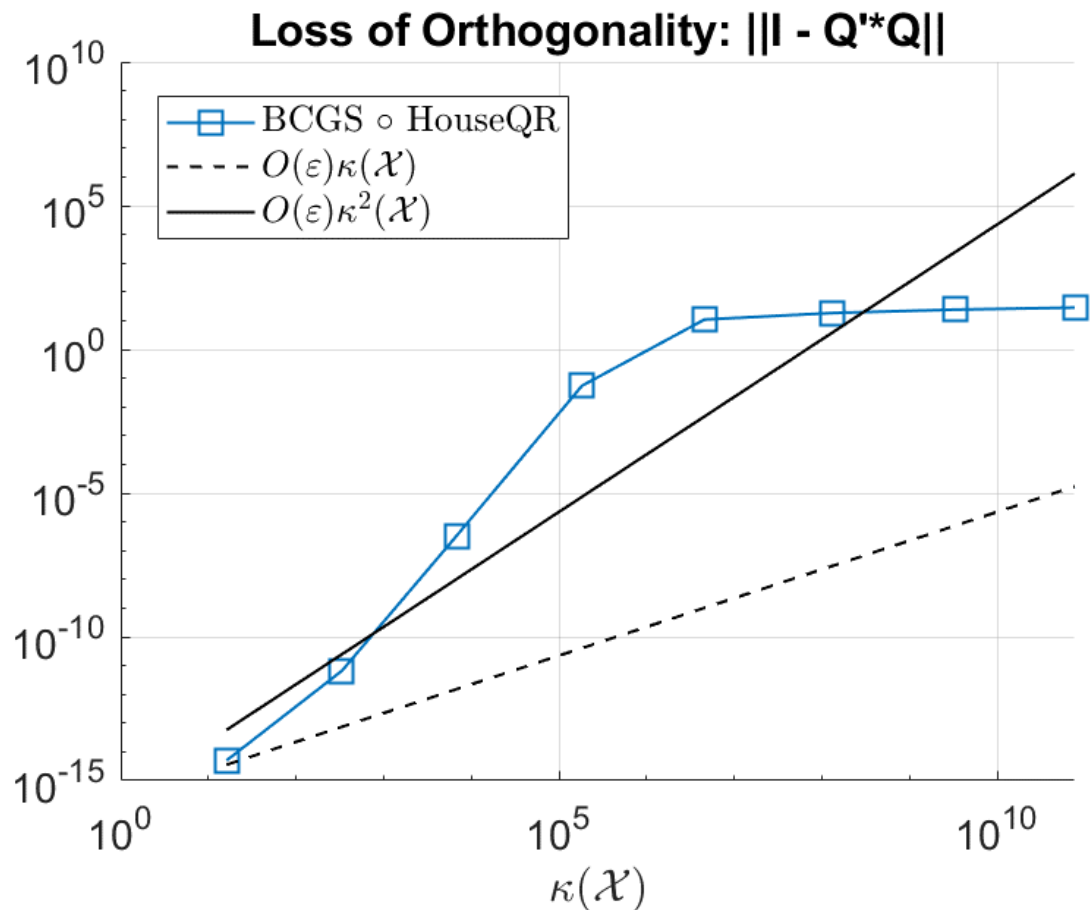
$$\|I - \bar{\mathcal{Q}}^T \bar{\mathcal{Q}}\| \leq O(\varepsilon) \kappa^{n-1}(\mathcal{X})$$

“Glued” matrices from [Smoktunowicz, Barlow, Langou, 2006]
 $m = 1000, p = 50, s = 4$



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BCGS loss of orthogonality is **not** $O(\epsilon)\kappa^2(\mathcal{X})$!

Block Pythagorean CGS

$$W_{k+1} = X_{k+1} - Q_{1:k}R_{1:k,k+1}$$

$$[Q_{k+1}, R_{k+1,k+1}] = \text{IntraOrtho}(W_{k+1})$$

$$[Q, R] = \text{BCGS}(X)$$

1: $[Q_1, R_{11}] = \text{IntraOrtho}(X_1)$

2: **for** $k = 1, \dots, p - 1$ **do**

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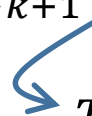
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$$\rightarrow = W_{k+1}^T W_{k+1} + R_{1:k,k+1}^T R_{1:k,k+1}$$

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$$R_{k+1,k+1} = \text{chol}(X_{k+1}^T X_{k+1} - R_{1:k,k+1}^T R_{1:k,k+1}) = \text{chol}(T_{k+1}^T T_{k+1} - P_{k+1}^T P_{k+1})$$

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$$R_{k+1,k+1} = \underbrace{\text{chol}(X_{k+1}^T X_{k+1} - \mathcal{R}_{1:k,k+1}^T \mathcal{R}_{1:k,k+1})}_{\text{BCGS-PIP}} = \underbrace{\text{chol}(T_{k+1}^T T_{k+1} - P_{k+1}^T P_{k+1})}_{\text{BCGS-PIO}}$$

$[\mathcal{Q}, \mathcal{R}] = \text{BCGS}(\mathcal{X})$

1: $[Q_1, R_{11}] = \text{IntraOrtho}(X_1)$

2: **for** $k = 1, \dots, p-1$ **do**

3: $\mathcal{R}_{1:k,k+1} = \mathcal{Q}_{1:k}^T X_{k+1}$

6: **end for**

7: **return** $\mathcal{Q} = [Q_1, \dots, Q_p], \mathcal{R} = (R_{jk})$

BCGS-PIP and BCGS-PIO

```

[Q, R] = BCGS(X)
1: [Q1, R11] = IntraOrtho(X1)
2: for k = 1, ..., p - 1 do
3:   R1:k,k+1 = Q1:k^T Xk+1
4:   W = Xk+1 - Q1:k R1:k,k+1
5:   [Qk+1, Rk+1,k+1] = IntraOrtho(W)
6: end for
7: return Q = [Q1, ..., Qp], R = (Rjk)
    
```



[Q, R] = BCGS-PIP(X)

```

1: [Q1, R11] = IntraOrtho(X1)
2: for k = 1, ..., p - 1 do
3:   [R1:k,k+1; Zk+1] = [Q1:k Xk+1]^T Xk+1
4:   [redacted]
5:   Wk+1 = Xk+1 - Q1:k R1:k,k+1
6:   Qk+1 = Wk+1 Rk+1,k+1^-1
7: end for
    
```

[Q, R] = BCGS-PIO(X)

```

1: [Q1, R11] = IntraOrtho(X1)
2: for k = 1, ..., p - 1 do
3:   R1:k,k+1 = Q1:k^T Xk+1
4:   [~, [Tk+1; Pk+1]] = IntraOrtho([Xk+1; R1:k,k+1])
5:   [redacted]
6:   Wk+1 = Xk+1 - Q1:k R1:k,k+1
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8: end for
    
```

- See [C., Lund, Rozložník, Thomas, 2020] and [C., Lund, Rozložník, 2021]
- BCGS-PIP also developed independently by [Yamazaki, Thomas, Hoemmen, Boman, Świrydowicz, Elliott, 2020]; called “CGS+CholQR”

New Stability Results for BCGS-PIP/PIO

Let $\mathcal{X} \in \mathbb{R}^{m \times n}$ be a matrix whose columns are organized into p blocks of size s , let ε denote the unit roundoff, and assume that

$$O(\varepsilon)\kappa^2(\mathcal{X}) < 1.$$

Suppose we execute BCGS-PIP \circ IntraOrtho(\mathcal{X}) or BCGS-PIO \circ IntraOrtho(\mathcal{X}).

If for all X , IntraOrtho(X) computes factors \bar{Q} and \bar{R} that satisfy

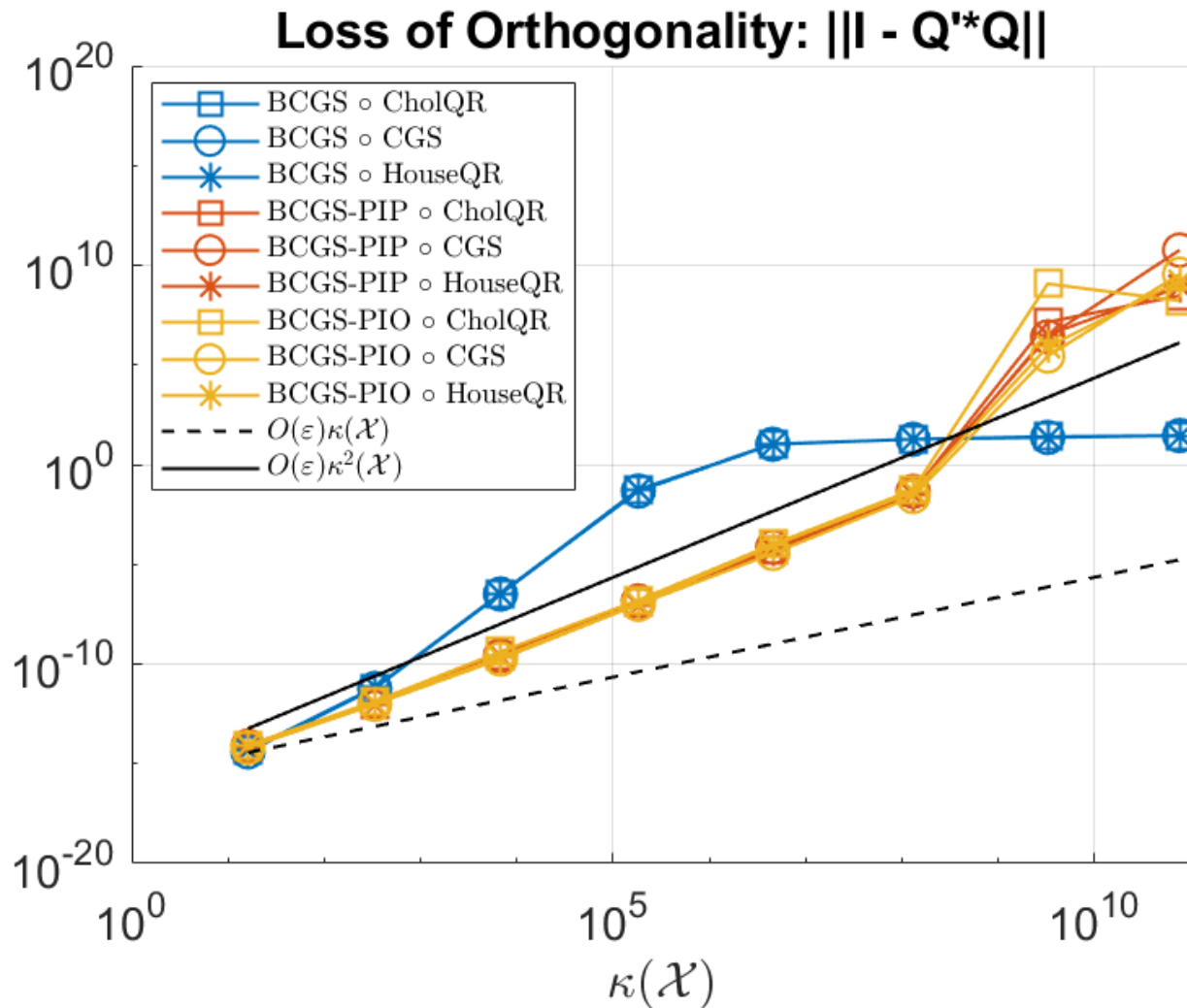
$$\begin{aligned} \bar{R}^T \bar{R} &= X^T X + \Delta E, & \|\Delta E\| &\leq O(\varepsilon)\|X\|^2, \quad \text{and} \\ \bar{Q} \bar{R} &= X + \Delta D, & \|\Delta D\| &\leq O(\varepsilon)(\|X\| + \|\bar{Q}\| \|\bar{R}\|), \end{aligned}$$

then the factors \bar{Q} and \bar{R} satisfy

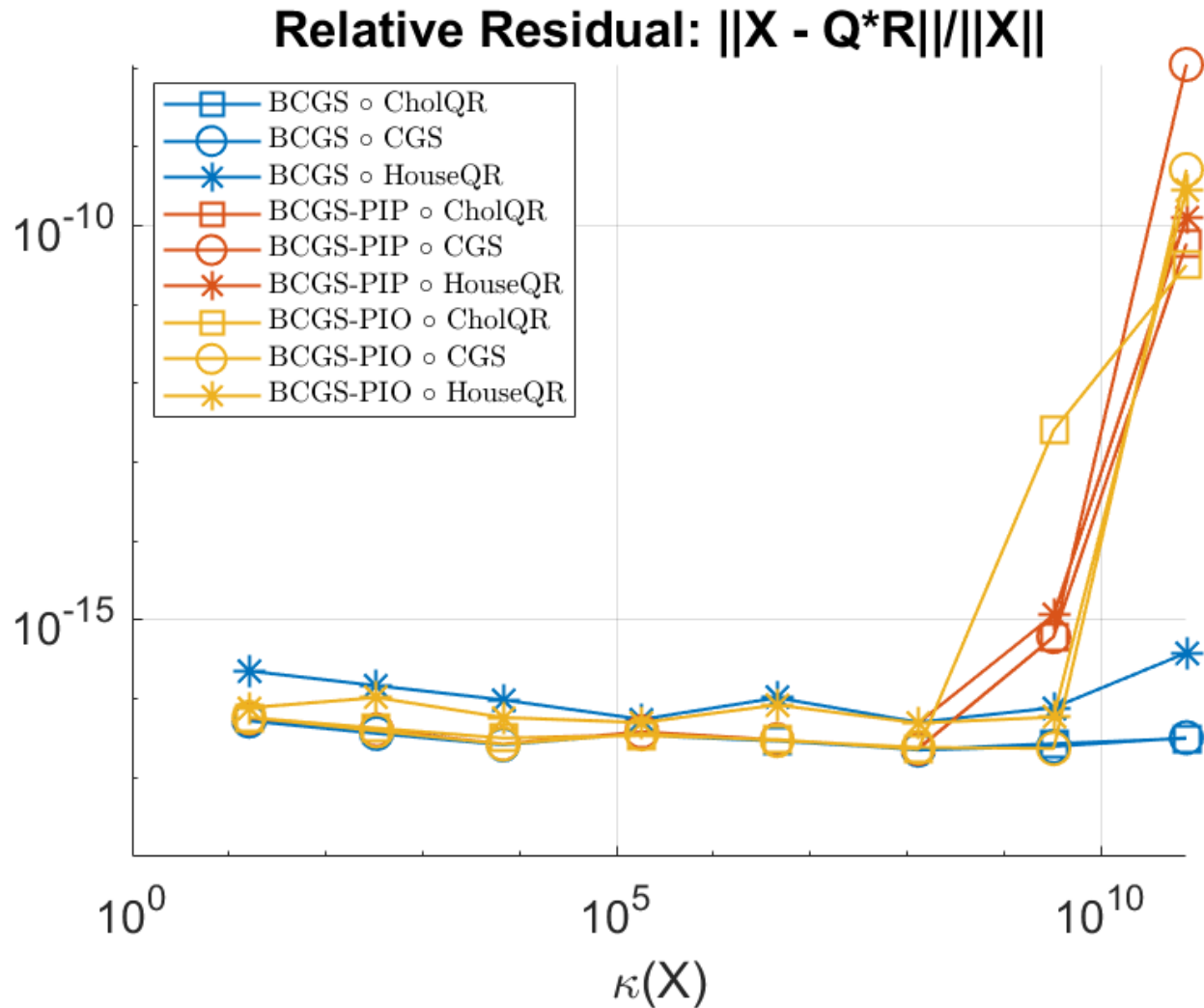
$$\begin{aligned} \|I - \bar{Q}^T \bar{Q}\| &\leq O(\varepsilon)\kappa^2(\mathcal{X}), \quad \text{and} \\ \bar{Q} \bar{R} &= X + \Delta D, \quad \|\Delta D\| \leq O(\varepsilon)\|X\|. \end{aligned}$$

“Glued” matrices from [Smoktunowicz, Barlow, Langou, 2006]

$$m = 1000, p = 50, s = 4$$



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Looking forward...

- Can we loosen the constraint on condition number (e.g., to $O(\varepsilon)\kappa(\mathcal{X}) < 1$)?
 - Need a better Cholesky:
 - [Yamazaki, Tomov, Kurzak, Dongarra, Barlow, 2015]: mixed precision CholeskyQR
 - [Fukaya, Kannan, Nakatsukasa, Yamamoto, Yanagisawa, 2020]: shifted-CholeskyQR3
- Stability for low-sync variants? [Świrydowicz, Langou, Ananthan, Yang, Thomas, 2021]
 - What is the effect of normalization lag?
 - What skeletons work with what muscles?

Thank You!

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BCGS-P preprint: http://www.math.cas.cz/fichier/preprints/IM_20210124200723_43.pdf

BGS survey paper: <https://arxiv.org/pdf/2010.12058.pdf>

BlockStab MATLAB package: <https://github.com/katlund/BlockStab>