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On bifurcations and traction forces on an obstacle in incompressible flow

Jakub Čach

joint work with Jan Blechta, Sebastian Schwarzacher, Karel Tůma

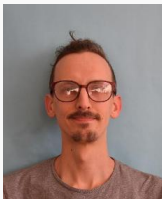
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Jakub Cach, Karel Tůma, Jan Blechta, & Sebastian Schwarzacher, *On bifurcations and traction forces on an obstacle in incompressible flow*, **arXiv:2512.15424 [physics.flu-dyn] (2025)**

Aim

- Traction: transfer of momentum between fluid–obstacle
- **Q:** *Can a steady boundary observable, namely the pointwise traction on the obstacle, indicate bifurcations of the unsteady Navier–Stokes dynamics?*
- Systematically observe all transition in the flow up to $\text{Re} = 500$
- A posteriori connect bifurcations to traction changes
- Critical points in the traction $\partial_{\text{Re}} \mathbf{t} = 0$

Equations and traction

- Unsteady incompressible Navier-Stokes equations

$$\rho(\partial_t \mathbf{v} + \mathbf{v} \cdot \nabla \mathbf{v}) = \operatorname{div} \mathbb{T} \quad \text{in } \Omega,$$

$$\operatorname{div} \mathbf{v} = 0 \quad \text{in } \Omega,$$

$$\mathbb{T} = -p\mathbb{I} + \mu(\nabla \mathbf{v} + (\nabla \mathbf{v})^T),$$

$$\mathbf{v} = \mathbf{v}_D^i \quad \text{on } \Gamma_i \subset \partial\Omega,$$

$$\mathbb{T}\mathbf{n} = 0 \quad \text{on } \partial\Omega \setminus \bigcup \Gamma_i.$$

- Traction

$\mathbf{t}(\theta; \operatorname{Re}) := \mathbb{T}\mathbf{n}.$

- Evaluation of pointwise traction

$$p_h, \mathbf{v}_h \mapsto \int_{\Gamma} \mathbf{t}_{\mathbf{n}}^h \cdot \varphi_h \, dS := \int_{\Omega} \rho \frac{d\mathbf{v}_h}{dt} \cdot \varphi_h + \int_{\Omega} \mathbb{T}_h \cdot \nabla \varphi_h - \int_{\partial\Omega \setminus \Gamma} (\mathbb{T}_h \mathbf{n}_h) \cdot \varphi_h \, dS \quad \forall \varphi_h \in V^h$$

Schäfer–Turek benchmark

- $t_{\text{drag}}(\theta; \text{Re}) := t_x(\theta; \text{Re})$
- $t_{\text{lift}}(\theta; \text{Re}) := t_y(\theta; \text{Re})$

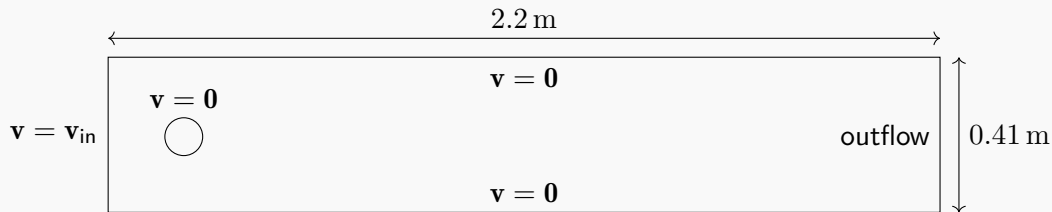


Figure: The Schäfer–Turek benchmark. The lower left corner is at $(0 \text{ m}, 0 \text{ m})$ and the cylinder center is located at $(0.2 \text{ m}, 0.2 \text{ m})$ with radius $R = 0.05 \text{ m}$. The domain is slightly asymmetric. The benchmark does not require use of a specific outflow condition.

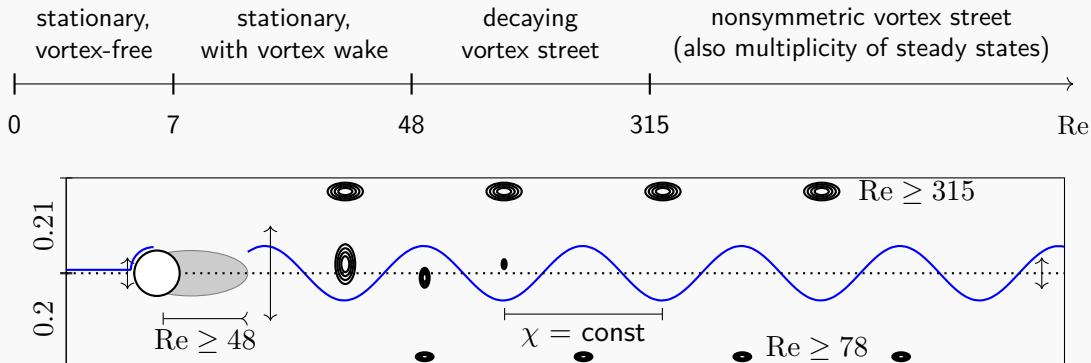
Navier-Stokes theory — What to expect

- steady BVP non-unique in 2D, 3D (except low Re)
- IBVP unique in 2D (Ladyženskaja)
- Uniqueness of time-periodic solutions in 2D, 3D
 - Steady solution only unique time-per. solution in case of a single obstacle flow (low Re)
- Open in rigorous manner:
 - What makes stable solution?
 - Are long-time attractors unique?
 - Are eigenvalues the key?

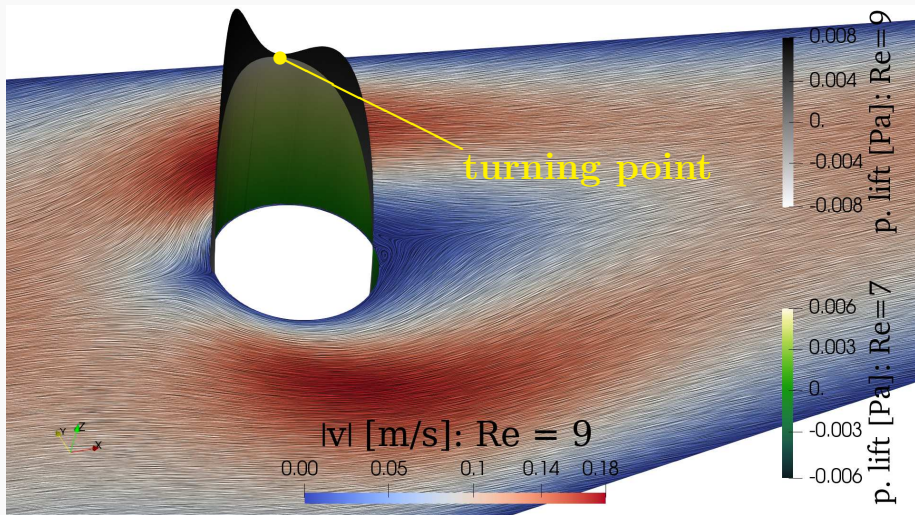
How we numerically analyze

- Discretization: Firedrake; Taylor-Hood CG(2,1); monolithic; Newton+LU; Crank-Nicolson
- global velocity field of the unsteady solution (long-time attractor)
- global velocity field of the steady solution
- traction profile of the steady solution (computed using dual method)
- eigenvalues of the Linear Perturbation Theory (LPT) operator (2D and 3D variant)
- deflated continuation of steady equations

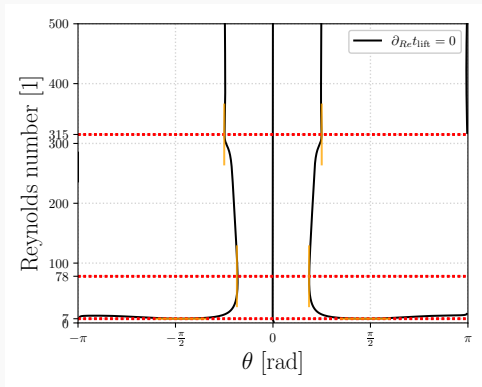
Long-time solutions for $Re \in (0, 500)$



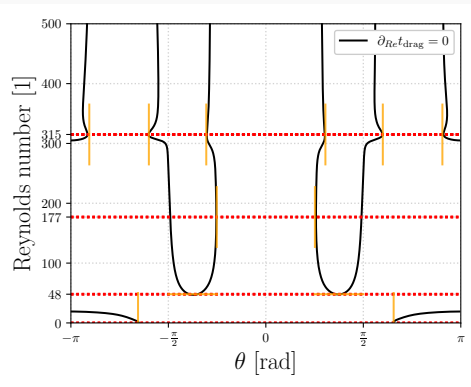
Pointwise traction



Critical curves $\rightarrow$ Turning points: global view



(a) Pointwise lift: $\partial_{Re} t_{\text{lift}}(\theta, Re) = 0$ in black



(b) Pointwise drag: $\partial_{Re} t_{\text{drag}}(\theta, Re) = 0$ in black

Turning points empirical conditions

The neutral traction curves exhibit folds in Reynolds number, reminiscent of degeneracies in bifurcation theory but of derived quantity

$$t_c(\theta, \text{Re}; (\mathbf{v}, p)(\text{Re})),$$

rather than the solution map $(\mathbf{v}, p)(\text{Re})$.

Neutral curve condition: $\partial_{\text{Re}} t(\theta, \text{Re}) = 0$

Turning point types:

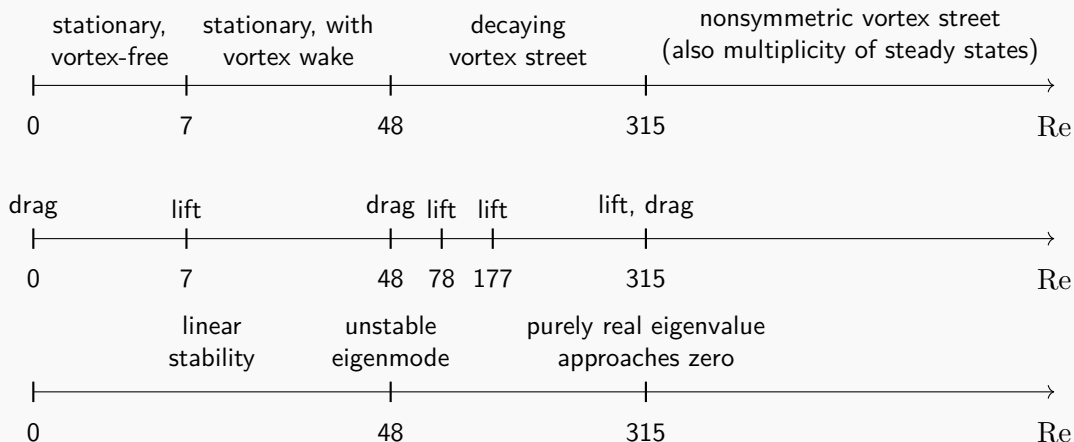
- **(A) Horizontal (simple critical point)**

$$\partial_{\text{Re}} t_c = 0, \quad \partial_{\theta} \partial_{\text{Re}} t_c = 0$$

- **(B) Vertical (higher-order degeneracy)**

$$\partial_{\text{Re}} t_c = 0, \quad \partial_{\text{Re}}^2 t_c = 0$$

Summary: Axis comparison



Summary

We observed:

- An **upstream** footprint of flow dynamics on the obstacle boundary
- Pointwise drag and lift traction as localized **indicators** of flow transitions

References and acknowledgement



1) Turek, Schaefer; *Benchmark computations of laminar flow around cylinder; in Flow Simulation with High-Performance Computers II*, Notes on Numerical Fluid Mechanics 52, 547-566, Vieweg 1996



2) David A. Ham et al. *Firedrake User Manual*. First edition. Imperial College London and University of Oxford and Baylor University and University of Washington. May 2023. DOI: 10.25561/104839.

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Questions?

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Results: All transitions found

- Low Re flow ($Re \lesssim 7$)

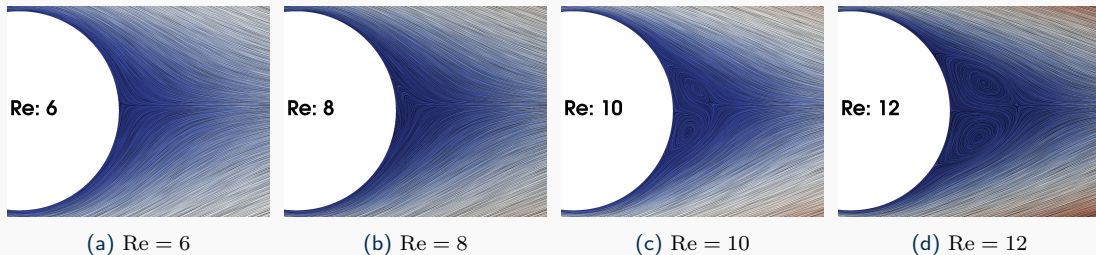


Figure: Velocity field on the downstream side of the cylinder in line integral convolution plot (streamlines). A pair of stationary vortices appears at $Re = 7$ and grows in size with increasing Re .

Results: All transitions found

- Non-trivial long-time solution ($Re \geq 48$)

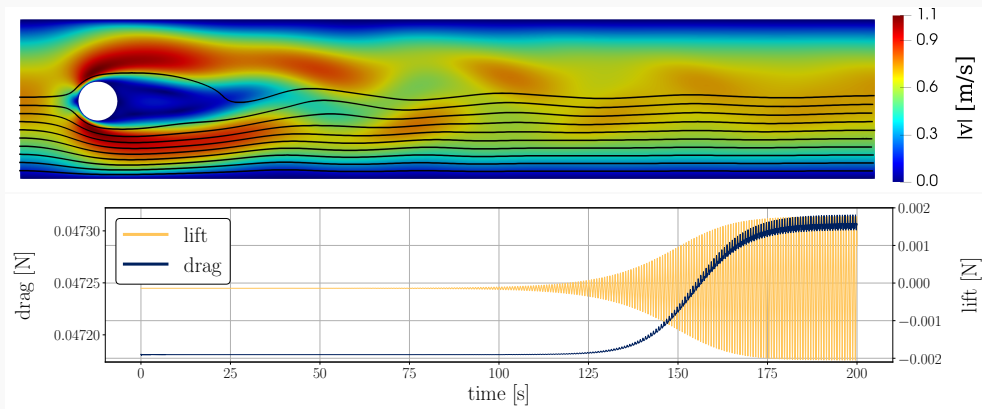
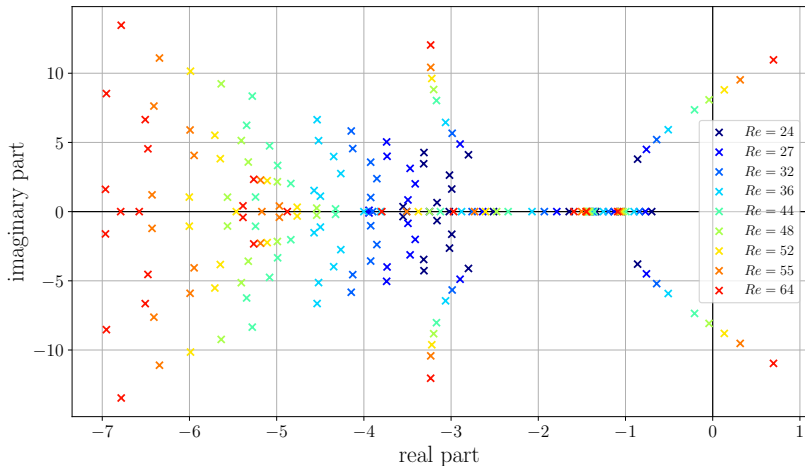


Figure: Numerical simulation of evolution problem at $Re = 50$.

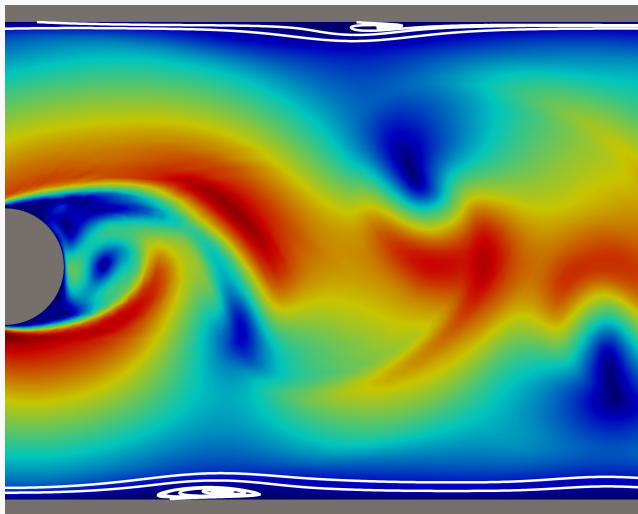
Results: All transitions found

- Hopf bifurcation ($\text{Re} = 48$)



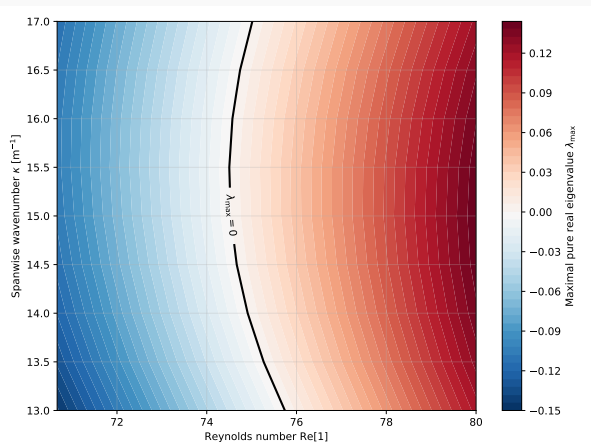
Results: All transitions found

- Wall effect: vortices along boundaries ($\text{Re} \geq 78$)



Results: All transitions found

- Steady 3D bifurcation: Mode E ($Re = 75$)

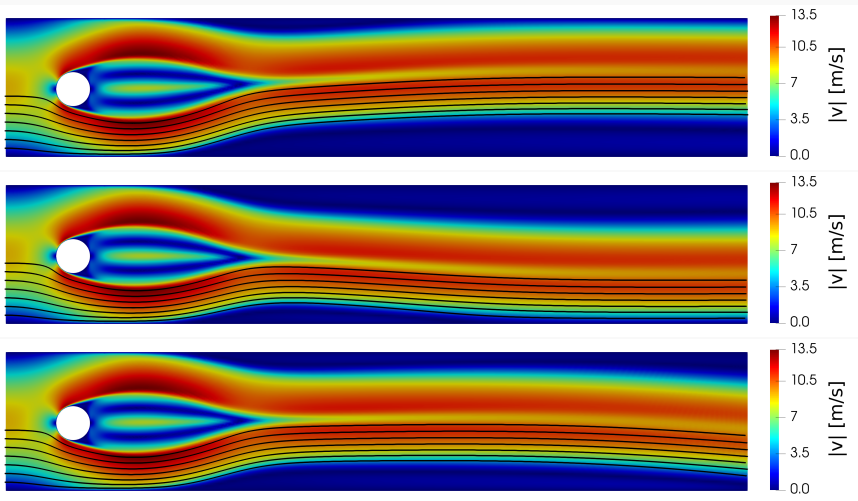


- 3D perturbation of 2D base flow
- spatial wavelength κ in spanwise coord. z must be solved for
- observation: spatial period $\approx$ domain width

$$\begin{aligned} v_x &= v_{st,x}(x, y) + \varepsilon e^{\lambda t} \hat{v}_x(x, y) \cos(\kappa z), \\ v_y &= v_{st,y}(x, y) + \varepsilon e^{\lambda t} \hat{v}_y(x, y) \cos(\kappa z), \\ v_z &= \varepsilon e^{\lambda t} \hat{v}_z(x, y) \sin(\kappa z), \\ p &= p_{st}(x, y) + \varepsilon e^{\lambda t} \hat{p}(x, y) \cos(\kappa z) \end{aligned}$$

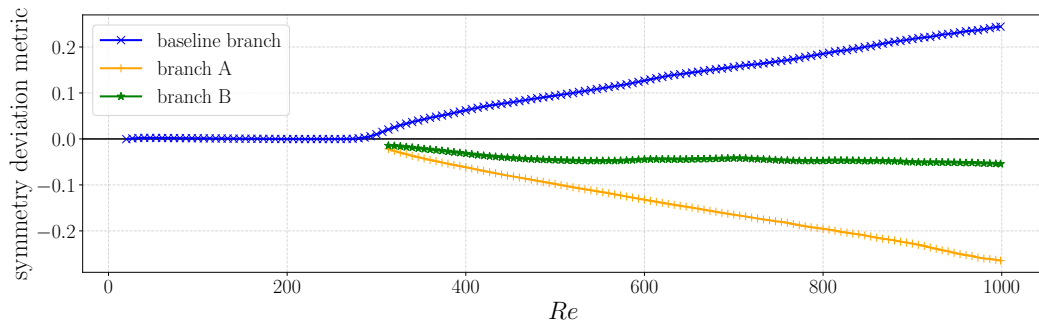
Results: All transitions found

- Multiple steady solutions at $Re \geq 315$



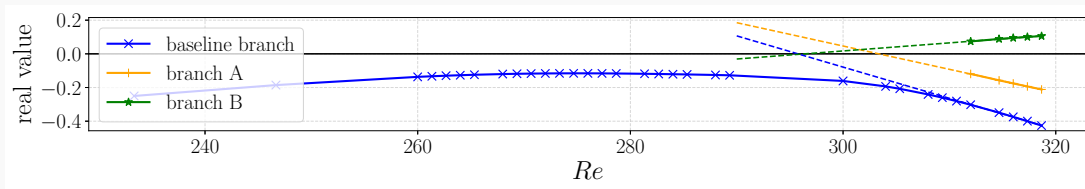
Results: All transitions found

- Bifurcation diagram for steady state multiplicity ($Re = 315$)



Results: All transitions found

- Maximal real eigenvalue behavior



Results: All transitions found

- Asymmetric shedding along top wall $Re \geq 315$

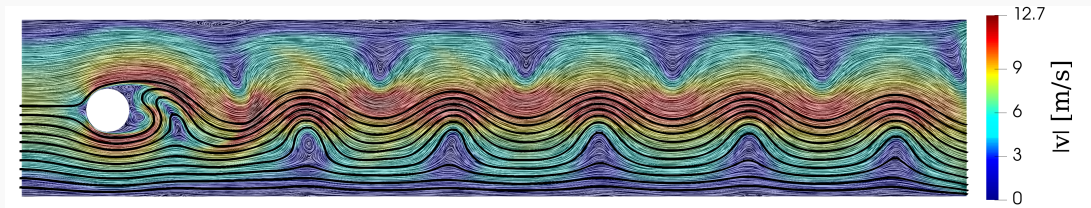


Figure: Non-symmetric decaying vortex street depicted at $Re = 500$.

Notion of a discrete pointwise traction

Direct evaluation

$$p_h, \mathbf{v}_h \mapsto \mathbf{t}_h := \mathbb{T}(p_h, \mathbf{v}_h) \mathbf{n}_h; \mathbb{T}(p, \mathbf{v}) = -p\mathbb{I} + 2\mu\mathbb{D}$$

Direct projection

$$p_h, \mathbf{v}_h \mapsto \int_{\Gamma} \mathbf{t}_h \cdot \boldsymbol{\varphi} \, dS := \int_{\Gamma} \mathbb{T}(p_h, \mathbf{v}_h) \mathbf{n}_h \cdot \boldsymbol{\varphi} \, dS$$

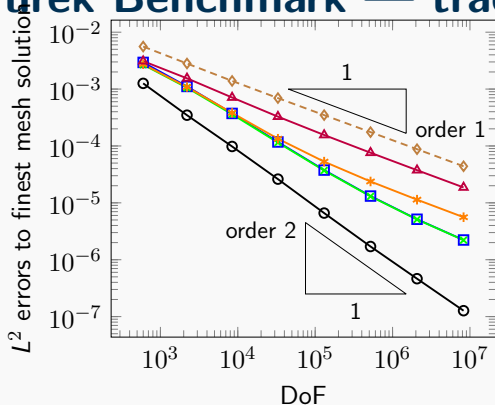
Variational approach

$$p_h, \mathbf{v}_h \mapsto \int_{\Gamma} \mathbf{t}_h^h \cdot \boldsymbol{\varphi}_h \, dS := \int_{\Omega} \rho \frac{d\mathbf{v}_h}{dt} \cdot \boldsymbol{\varphi}_h + \int_{\Omega} \mathbb{T}_h \cdot \nabla \boldsymbol{\varphi}_h - \int_{\partial\Omega \setminus \Gamma} (\mathbb{T}_h \mathbf{n}_h) \cdot \boldsymbol{\varphi}_h \, dS \quad \forall \boldsymbol{\varphi}_h \in \mathbf{V}^h$$

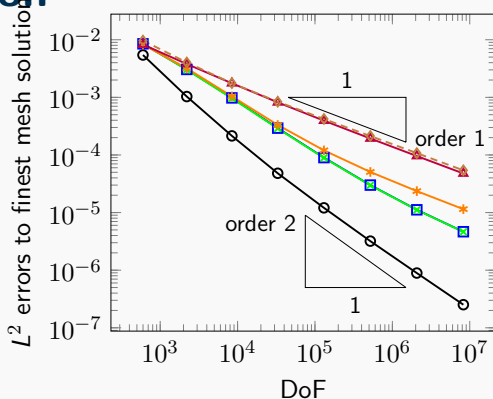
Discrete variational normal derivative ($\Delta u = f, u|_{\partial\Omega} = 0$)

$$u_h \mapsto \int_{\partial\Omega} \partial_{\mathbf{n}}^h u_h v_h \, dS := \int_{\Omega} \nabla u_h \cdot \nabla v_h \, dx - \langle f, v_h \rangle \quad \forall v_h \in V^h, \text{ solve for } \partial_{\mathbf{n}}^h u \in \text{trace } V^h$$

Turek Benchmark — traction



(a) Stokes



(b) Navier-Stokes (original benchmark)

