

# Lagrangian duality in nonlinear programming

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COMPUTATIONAL ASPECTS OF OPTIMIZATION

# Nonlinear Programming Problem (NLP)

**Primal problem (P):**

$$(P) = \min_{x \in X} f(x) \text{ s.t. } g_j(x) \leq 0, j = 1, \dots, m,$$
$$h_i(x) = 0, i = 1, \dots, l.$$

**Lagrangian function**,  $u \in \mathbb{R}_+^m$ ,  $v \in \mathbb{R}^l$ :

$$L(x, u, v) = f(x) + \sum_{j=1}^m u_j g_j(x) + \sum_{i=1}^l v_i h_i(x)$$

# Dual problem

**Dual function:**

$$\theta(u, v) = \inf_{x \in X} L(x, u, v) \quad (1)$$

**Dual problem (D):**

$$(D) = \sup_{u \geq 0, v} \theta(u, v) \quad (2)$$

# Weak Duality Theorem

## Theorem

Let  $x$  be feasible for problem  $(P)$  and  $(u, v)$  be feasible for problem  $(D)$ .  
Then

$$\theta(u, v) \leq f(x).$$

## Proof.

$$\theta(u, v) = \inf_y L(y, u, v) \leq L(x, u, v) \leq f(x),$$

where the last inequality follows from feasibility of  $x$  and  $(u, v)$ , when  $u_j g_j(x) \leq 0$  and  $v_i h_i(x) = 0$ .

## Weak Duality Theorem – Consequences

1. We obtain

$$(P) \geq (D).$$

2. If for some primal feasible  $\bar{x}$  and dual feasible  $(\bar{u}, \bar{v})$  holds

$$f(\bar{x}) = \theta(\bar{u}, \bar{v}),$$

then  $\bar{x}$  is optimal solution of (P) and  $(\bar{u}, \bar{v})$  is optimal solution of (D).

3. If  $(P) = -\infty$  (unbounded primal problem), then  $\theta(u, v) = -\infty$  for all  $(u, v) \in \mathbb{R}_+^m \times \mathbb{R}^l$ .
4. If  $(D) = \infty$ , then (P) is infeasible.

# Strong Duality Theorem

## Theorem

Let

- $X$  be a nonempty convex set
- $f, g_j$  be **convex**
- $h_i$  be **affine**
- **Slater condition** be satisfied, i.e. there is  $\hat{x} \in X$  such that  
 $g_j(\hat{x}) < 0, \forall j$  and  $h_i(\hat{x}) = 0, \forall i$ , and  
 $0 \in \text{int}\{(h_1(x), \dots, h_l(x)) : x \in X\} := h(X)$ .

Then  $(P) = (D)$ .

Moreover, if  $(P)$  is finite, then  $\sup$  in  $(D)$  is achieved at  $(\bar{u}, \bar{v}) \in \mathbb{R}_+^m \times \mathbb{R}^l$ .  
If  $\inf$  in  $(P)$  is achieved at  $\bar{x}$ , then  $\sum_{j=1}^m \bar{u}_j g_j(\bar{x}) = 0$ .

## A counterexample

**Convexity alone is not sufficient.** Consider

$$\begin{aligned} p^* &= \min_{x,y} e^{-x} \\ \text{s.t. } &x^2/y \leq 0, \\ &y > 0 \quad (\text{or } y \geq \varepsilon). \end{aligned}$$

The optimal value is  $p^* = 1$ . The dual function is equal to

$$\theta(u) = \inf_{x,y>0} e^{-x} + ux^2/y = \begin{cases} 0 & u \geq 0, \\ -\infty & u < 0. \end{cases}$$

The dual problem is

$$d^* = \max_{u \geq 0} \theta(u)$$

with optimal value  $d^* = 0$ . Slater condition is not satisfied since  $x = 0$  for any feasible  $(x, y)$ , i.e.  $x^2/y = 0$ .

Bazaraa et al. (2006), Lemma 6.2.3:

## Lemma

Let  $X \subseteq \mathbb{R}^n$  be a convex set,  $f, g_j : \mathbb{R}^n \rightarrow \mathbb{R}$  be convex,  $h_i : \mathbb{R}^n \rightarrow \mathbb{R}$  be affine. If System 1 has no solution, then System 2 has a solution  $(u_0, u, v)$ . The converse holds true if  $u_0 > 0$ .

System 1:  $f(x) < 0, g_j(x) \leq 0, h_i(x) = 0$  for some  $x \in X$ .

System 2:  $u_0 f(x) + \sum_{j=1}^m u_j g_j(x) + \sum_{i=1}^l v_i h_i(x) \geq 0$  for all  $x \in X$ ,  
 $(u_0, u) \geq 0, (u_0, u, v) \neq 0$ .

Let  $\gamma$  be a (finite) optimal value of (P) and consider the following system:

$$f(x) - \gamma < 0, \quad g_j(x) \leq 0, j = 1, \dots, m, \quad h_i(x) = 0, i = 1, \dots, l, \quad x \in X.$$

By the definition of  $\gamma$  the system has no solution. Hence, there exists  $(u_0, u, v) \neq 0$  with  $(u_0, u) \geq 0$  such that

$$u_0(f(x) - \gamma) + \sum_{j=1}^m u_j g_j(x) + \sum_{i=1}^l v_i h_i(x) \geq 0, \quad \forall x \in X.$$

## SDT proof

Suppose that  $u_0 = 0$ . By assumption there is an  $\hat{x} \in X$  such that  $g_j(\hat{x}) < 0, \forall j$  and  $h_i(\hat{x}) = 0, \forall i$ . Substituting into the inequality we obtain  $\sum_{j=1}^m u_j g_j(\hat{x}) \geq 0$ . Since  $g_j(\hat{x}) < 0, \forall j$ , we have  $u_j = 0, \forall j$ , and  $u_0 = 0$ . This implies that  $\sum_{i=1}^I v_i h_i(x) \geq 0$  for all  $x \in X$ . Since  $0 \in h(X)$ , we can pick a  $x \in X$  such that  $h_i(x) = -\lambda v_i$ , where  $\lambda > 0$  (small). Therefore

$$\sum_{i=1}^I v_i h_i(x) = -\lambda \sum_{i=1}^I v_i^2 \geq 0,$$

which implies that  $v_i = 0, \forall i$ . But this is a contradiction with  $(u_0, u, v) \neq 0$ . Hence  $u_0 > 0\dots$

Hence  $u_0 > 0$ . Thus, if we set  $\tilde{u}_j = u_j/u_0$  and  $\tilde{v}_i = v_i/u_0$ , we get

$$f(x) + \sum_{j=1}^m \tilde{u}_j g_j(x) + \sum_{i=1}^l \tilde{v}_i h_i(x) \geq \gamma, \quad \forall x \in X.$$

This shows that

$$\theta(\tilde{u}, \tilde{v}) = \inf_{x \in X} L(x, \tilde{u}, \tilde{v}) \geq \gamma.$$

Together with the Weak Duality Theorem we obtain that

$$\gamma = \theta(\tilde{u}, \tilde{v}) = \sup_{u \geq 0, v} \theta(u, v).$$

## Example: Linear programming duality

$$\begin{aligned} & \min c^T x \\ \text{s.t. } & Ax = b, \\ & x \geq 0. \end{aligned}$$

## Example: Ordinary least squares with equality constraints

$$\begin{aligned} \min \quad & \|Ax - b\|_2^2 \\ \text{s.t. } & Fx = g. \end{aligned}$$

## Example: The support vector classifier

Hastie et al. (2009): Training data:  $N$  pairs  $(x_1, y_1), (x_2, y_2), \dots, (x_N, y_N)$ ,  
 $x_i \in \mathbb{R}^p$ ,  $y_i \in \{-1, 1\}$  (classes).

A linear classification rule with  $\|\beta\| = 1$

$$G(x) = \text{sign}[x^T \beta + \beta_0].$$

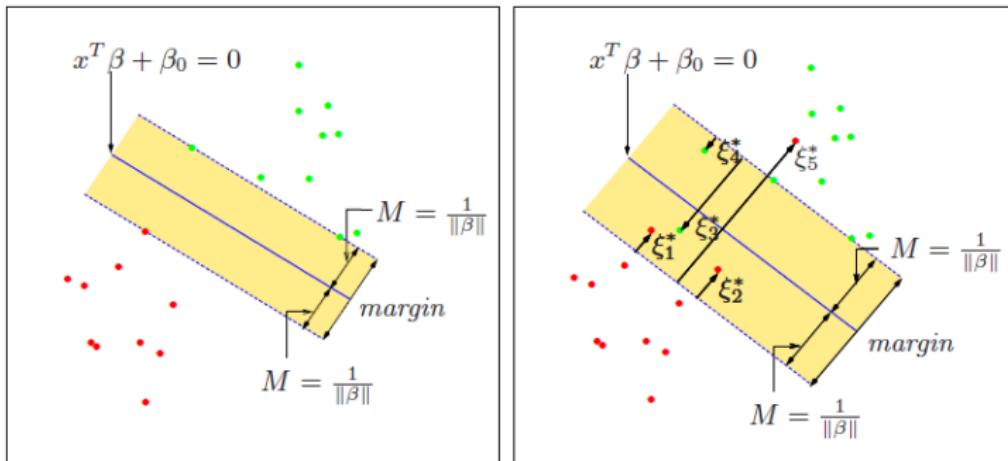
Assume first that the data are separable. We would like to find **the biggest margin** between the training points for class 1 and -1:

$$\max_{\beta_0, \beta} M$$

$$\text{s.t. } y_i(x_i^T \beta + \beta_0) \geq M, \quad i = 1, \dots, N,$$

$$\|\beta\| = 1.$$

## Example: The support vector classifier



Hastie et al. (2009)

## Example: The support vector classifier

By setting  $M = 1/\|\beta\|$ :

$$\min_{\beta_0, \beta} \|\beta\|$$

$$\text{s.t. } y_i(x_i^T \beta + \beta_0) \geq 1, \quad i = 1, \dots, N.$$

If the classes overlap:

$$\min_{\beta_0, \beta, \xi} \frac{1}{2} \|\beta\|^2 + C \sum_{i=1}^N \xi_i$$

$$\text{s.t. } y_i(x_i^T \beta + \beta_0) \geq 1 - \xi_i, \quad i = 1, \dots, N,$$

$$\xi_i \geq 0,$$

where we penalize the overall overlap.

## Example: The support vector classifier

Lagrange function

$$\begin{aligned} L(\beta_0, \beta, \xi, \alpha, \mu) = & \frac{1}{2} \|\beta\|^2 + C \sum_{i=1}^N \xi_i - \sum_{i=1}^N \mu_i \xi_i \\ & - \sum_{i=1}^N \alpha_i (y_i (x_i^T \beta + \beta_0) - 1 + \xi_i), \quad \alpha_i \geq 0, \mu_i \geq 0. \end{aligned}$$

The dual function

$$\theta(\alpha, \mu) = \inf_{\beta_0, \beta, \xi} L(\beta_0, \beta, \xi, \alpha, \mu).$$

## Example: The support vector classifier

$$L(\beta_0, \beta, \xi, \alpha, \mu) = \frac{1}{2} \|\beta\|^2 + C \sum_{i=1}^N \xi_i - \sum_{i=1}^N \mu_i \xi_i$$
$$- \sum_{i=1}^N \alpha_i (y_i(x_i^T \beta + \beta_0) - 1 + \xi_i), \quad \alpha_i \geq 0, \mu_i \geq 0$$

Use the derivatives to obtain the dual function:

$$\frac{\partial L}{\partial \beta_0} = \sum_{i=1}^N \alpha_i y_i = 0,$$

$$\frac{\partial L}{\partial \beta} = \beta - \sum_{i=1}^N \alpha_i y_i x_i = 0,$$

$$\frac{\partial L}{\partial \xi_i} = C - \alpha_i - \mu_i = 0.$$

## Example: The support vector classifier

We can express the dual function

$$\begin{aligned}\theta(\alpha, \mu) &= \frac{1}{2} \sum_{i=1}^N \sum_{i'=1}^N \alpha_i \alpha_{i'} y_i y_{i'} x_i^T x_{i'} + C \sum_{i=1}^N \xi_i - \sum_{i=1}^N \sum_{i'=1}^N \alpha_i \alpha_{i'} y_i y_{i'} x_i^T x_{i'} \\ &\quad - \beta_0 \sum_{i=1}^N \alpha_i y_i + \sum_{i=1}^N \alpha_i - \sum_{i=1}^N \alpha_i \xi_i - \sum_{i=1}^N \mu_i \xi_i \\ &= -\frac{1}{2} \sum_{i=1}^N \sum_{i'=1}^N \alpha_i \alpha_{i'} y_i y_{i'} x_i^T x_{i'} + \sum_{i=1}^N \alpha_i,\end{aligned}$$

subject to  $0 \leq \alpha_i \leq C$ ,  $\sum_{i=1}^N \alpha_i y_i = 0$ .

# Literature

- Bazaraa, M.S., Sherali, H.D., and Shetty, C.M. (2006). **Nonlinear programming: theory and algorithms**, Wiley, Singapore, 3rd edition.
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- Hastie, T., Tibshirani, R., Friedman, J. (2009). **The Elements of Statistical Learning: Data Mining, Inference, and Prediction**. Springer Series in Statistics, 2nd edition.