

LEGENDRE POLYNOMIALS

& THEIR APPLICATION TO APPROXIMATIONS OF

ELIPSOIDAL FIGURES OF EQUILIBRIUM

[10 min] **A** ESSENTIALS

[50 min] **B** LEGENDRE POLYNOMIALS

[35 min] **C** SHAPE DESCRIPTION OF A NEAR-
-SPHERICAL BODY

D CONSTITUTIONAL AND EQUILIBRIUM
BALANCE EQUATIONS

E WORKED EXAMPLES

A

ESSENTIALS

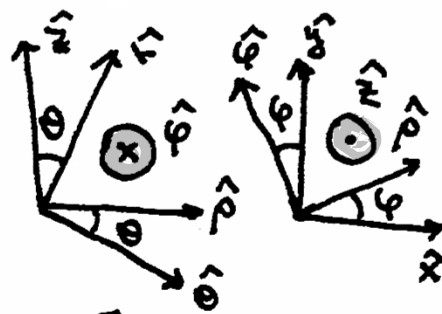
- Newton's approximation: $(1 + \epsilon)^a = 1 + a\epsilon + \frac{a(a-1)}{2}\epsilon^2 + \dots$

- Vector identities

$$\vec{a} \times \vec{b} = -\vec{b} \times \vec{a} \rightarrow \vec{a} \times \vec{a} = 0$$

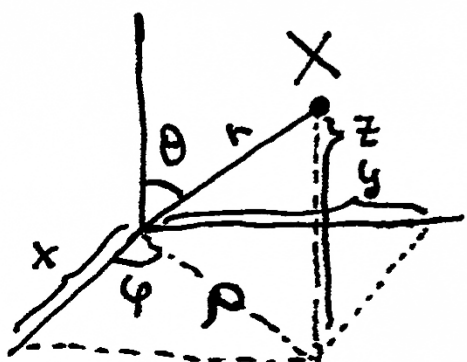
$$\vec{a} \cdot (\vec{b} \times \vec{c}) = \vec{b} \cdot (\vec{c} \times \vec{a}) = \vec{c} \cdot (\vec{a} \times \vec{b})$$

$$\vec{a} \times (\vec{b} \times \vec{c}) = \vec{b}(\vec{a} \cdot \vec{c}) - \vec{c}(\vec{a} \cdot \vec{b})$$



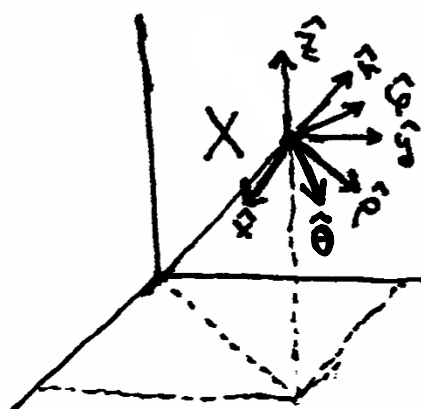
- Coordinate systems

$$(\vec{T} \times \vec{b}) \cdot \vec{c} = \vec{T} \cdot (\vec{b} \times \vec{c})$$



Scalar fields

xyz
 $\rho\phi z$
 $r\theta\phi$



$\hat{x}\hat{y}\hat{z}$
 $\hat{\rho}\hat{\phi}\hat{z}$
 $\hat{r}\hat{\theta}\hat{\phi}$

Unit vector fields

- Differential identities (with coordinate fields)

$$\nabla x = \hat{x}$$

$$\nabla y = \hat{y}$$

$$\nabla z = \hat{z}$$

$$\nabla \rho = \hat{\rho}$$

$$\nabla r = \hat{r}$$

$$\nabla \phi = \frac{1}{\rho} \hat{\phi}$$

$$\nabla \theta = \frac{1}{r} \hat{\theta}$$

$$\nabla \hat{x} = 0$$

$$\nabla \hat{y} = 0$$

$$\nabla \hat{z} = 0$$

$$\nabla \hat{\rho} = \frac{1}{\rho} \hat{\phi} \hat{\phi}$$

$$\nabla \hat{r} = \frac{1}{r} (\mathbf{I} - \hat{r} \hat{r})$$

$$\nabla \hat{\phi} = -\frac{1}{\rho} \hat{\phi} \hat{\rho}$$

$$\nabla \hat{\theta} = \frac{\cot \theta}{r} \hat{\phi} \hat{\phi} - \frac{1}{r} \hat{\theta} \hat{r}$$

$$\nabla \cdot \hat{x} = 0$$

$$\nabla \cdot \hat{y} = 0$$

$$\nabla \cdot \hat{z} = 0$$

$$\nabla \cdot \hat{\rho} = \frac{1}{\rho}$$

$$\nabla \cdot \hat{r} = \frac{2}{r}$$

$$\nabla \cdot \hat{\phi} = 0$$

$$\nabla \cdot \hat{\theta} = \frac{\cot \theta}{r}$$

$$\nabla \times \hat{x} = \nabla \times \hat{y} = \nabla \times \hat{z} = 0$$

$$\nabla \times \hat{\rho} = 0$$

$$\nabla \times \hat{r} = 0$$

$$\nabla \times \hat{\phi} = \frac{1}{\rho} \hat{z}$$

$$\nabla \times \hat{\theta} = \frac{1}{r} \hat{\phi}$$

$$\Delta x = \Delta y = \Delta z = 0$$

$$\Delta \rho = \frac{1}{\rho}$$

$$\Delta r = \frac{2}{r^2}$$

$$\Delta \phi = 0$$

$$\Delta \theta = \frac{1}{r^2} \cot \theta$$

$$\Delta \hat{x} = \Delta \hat{y} = \Delta \hat{z} = 0$$

$$\Delta \hat{\rho} = -\frac{1}{\rho^2} \hat{\rho}$$

$$\Delta \hat{r} = -\frac{2}{r^2} \hat{r}$$

$$\Delta \hat{\phi} = -\frac{1}{\rho^2} \hat{\phi}$$

$$\Delta \hat{\theta} = -\frac{1}{r^2} [2 \cot \theta \hat{r} + \csc^2 \theta \hat{\theta}]$$

- Differential identities (Miscellaneous)

$$\nabla \times (\nabla \times \vec{u}) = \nabla \nabla \cdot \vec{u} - \Delta \vec{u} \quad (\Delta := \nabla \cdot \nabla \text{ Laplacian})$$

$$\nabla \times \nabla T = 0 \quad (T \text{ any tensor})$$

$$\nabla \times (\vec{u} \times \vec{v}) = \vec{u} \nabla \cdot \vec{v} - \vec{v} \nabla \cdot \vec{u} - \vec{u} \cdot \nabla \vec{v} + \vec{v} \cdot \nabla \vec{u}$$

$$\nabla(\phi T) = (\nabla \phi) T + \phi \nabla T \quad (\phi \text{ a scalar field})$$

$$\nabla \cdot (\nabla(\phi T)) = (\Delta \phi) T + 2 \nabla \phi \cdot \nabla T + \phi \Delta T$$

$$\nabla \cdot (\vec{u} T) = (\nabla \cdot \vec{u}) T + \vec{u} \cdot \nabla T$$

$$\nabla \cdot (\phi \vec{u}) = (\nabla \phi) \cdot \vec{u} + \phi \nabla \cdot \vec{u}$$

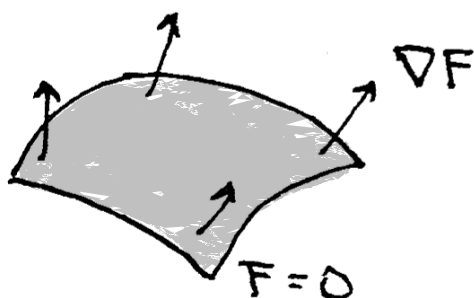
$$\Delta(\vec{F} \times \nabla \phi) = \vec{F} \times \nabla \Delta \phi$$

$$\nabla f(\phi) = f'(\phi) \nabla \phi \Rightarrow \nabla f(r) = f'(r) \hat{r}$$

$$\Delta f(r) = \frac{1}{r} (r f')'' \Rightarrow \Delta r^n = n(n+1) r^{n-2}$$

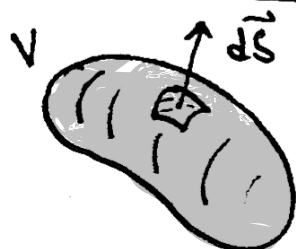
$$\hat{r} \cdot \nabla = \partial_r \quad \frac{1}{r^2} (r^2 f')'$$

- Normal vector field (to a given surface)



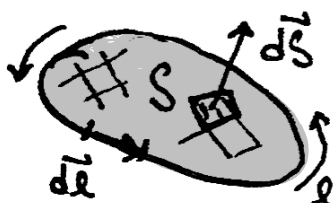
$$\nabla F \perp F=0$$

- Integral theorems



$$\iiint_V dV \nabla T = \oint_{\partial V} d\vec{S} T$$

Gauss'



$$\iint_S d\vec{S} \times \nabla T = \oint_{\partial S} d\vec{l} T$$

Stokes'



LEGENDRE POLYNOMIALS

GENERAL ORTHOGONAL POLYNOMIALS

$$\phi_n(x) = k_n x^n + \tilde{k}_{n-1} x^{n-1} + \dots; \quad \langle \phi_n, \phi_{n'} \rangle := \int_M \phi_n(x) \bar{\phi}_{n'}(x) \rho(x) dx = \|\phi_n\|^2 \delta_{nn'}$$

leading coefficient sub-leading coefficient (interval (a,b)) ρ -norm weight Kronecker δ

orthogonality relation

1 DEFINITIONS

• Fundamental integral : $F = \int_{-1}^1 f(x + \frac{t}{2}(1-x^2)) dx$; $t \in [-1, 1]$
 f analytic on $(-1, 1)$

I. Substitution $y = x + \frac{t}{2}(1-x^2) \Rightarrow dx = \frac{dy}{\sqrt{1-2yt+t^2}}$

$\therefore F = \int_{-1}^1 \frac{f(y)}{\sqrt{1-2yt+t^2}} dy$

II Taylor expansion: $f(x + \frac{t}{2}(1-x^2)) = \sum_{n=0}^{\infty} \frac{f^{(n)}(x)}{n!} \left[\frac{t}{2}(1-x^2) \right]^n$

$\downarrow$
By parts integration: $F = \int_{-1}^1 f(x) \sum_{n=0}^{\infty} t^n \frac{(-1)^n}{2^n n!} [(1-x^2)^n]^{(n)}$

• Rodrigues formula : $P_n(x) := \frac{(-1)^n}{2^n n!} [(1-x^2)^n]^{(n)}$

* Low order polynomials ($x \equiv \hat{r} \cdot \hat{z} = \cos \theta$)



$P_0 = 1$ $P_1 = x$ $P_2 = \frac{1}{2}(3x^2 - 1)$ $P_3 = \frac{1}{2}(5x^3 - 3x)$ $P_4 = \frac{1}{8}(35x^4 - 30x^2 + 3)$

* Leading term : $P_n = \frac{(-1)^n}{2^n n!} [(-1)^n x^{2n} + \dots]^{(n)} = \frac{(2n)!}{2^n n!} x^n + \dots$
 $\underbrace{\hspace{10em}}_{k_n}$

• Generating function (GF):
 By comparing I & II in F: $G(x, t) := \sum_{n=0}^{\infty} P_n(x) t^n = \frac{1}{\sqrt{1-2xt+t^2}}$; $t \in [-1, 1]$

2 BASIC PROPERTIES

$$G(x, t) = \sum_{n=0}^{\infty} t^n P_n(x) = \frac{1}{\sqrt{1-2xt+t^2}}$$

• Special values ($C \rightarrow GF$)

a) $x = 1 : \frac{1}{1-t} = \sum P_n(1) t^n \therefore P_n(1) = 1$

b) $x = -1 : \frac{1}{1+t} = \sum P_n(-1) t^n \therefore P_n(-1) = (-1)^n$

in general $G(-x, -t) = G(x, t) \therefore P_{2n}(-x) = P_{2n}(x) \wedge P_{2n+1}(-x) = -P_{2n+1}(x)$

c) $x = 0 : \frac{1}{\sqrt{1+t^2}} = \sum_{l=0}^{\infty} \frac{(2l-1)!!}{(2l)!!} (-t^2)^l \equiv \sum_{n=0}^{\infty} P_n(0) t^n$

$$\therefore P_{2l+1}(0) = 0 \wedge P_{2l}(0) = (-1)^l \frac{(2l-1)!!}{(2l)!!}$$

Alternatively from Rodrigues: $n = 2l$, so

$$(1-x^2)^n = \dots + (-1)^l \binom{2l}{l} x^{2l} + \dots \quad (\text{when } n \text{ is odd we have no } x^n \text{ term})$$

$$\hookrightarrow [(1-x^2)^n]^{(n)} \Big|_{x=0} = (-1)^l \binom{2l}{l} (2l)! \therefore P_{2l}(0) = (-1)^l \frac{(2l)!}{4^l l!^2} = (-1)^l \frac{(2l-1)!!}{(2l)!!}$$

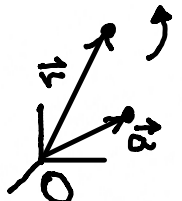
• Polynomial orthogonality relation : WLOG $n \geq n'$:

$$\begin{aligned} * \langle P_n, P_{n'} \rangle &= \int_{-1}^1 P_n P_{n'} dx \stackrel{RG}{=} \frac{(-1)^n}{2^n n!} \int_{-1}^1 [(1-x^2)^n]^{(n)} P_{n'} dx = \int_{-1}^1 P_n P_{n'} dx = \frac{2}{2n+1} \delta_{nn'} \quad (\text{POGR}) \\ &\quad \text{by parts} \\ &\quad k_n x^{n'} + \dots \\ * \sum_{n=0}^{\infty} \|P_n\|^2 t^{2n} &= \int_{-1}^1 \sum_{n,n'} \langle P_n, P_{n'} \rangle t^n t^{n'} dx = \int_{-1}^1 \left(\frac{1}{\sqrt{1-2xt+t^2}} \right)^2 dx = \frac{1}{t} \ln \left(\frac{1+t}{1-t} \right) = \sum_{n=0}^{\infty} \frac{2}{2n+1} t^{2n} \therefore \|P_n\|^2 = \frac{2}{2n+1} \end{aligned}$$

• Coulomb kernel expansion

$$\frac{1}{|\vec{r} - \vec{a}|} = \frac{1}{\sqrt{r^2 - 2\vec{r} \cdot \vec{a} + a^2}} = \frac{1}{r} \frac{1}{\sqrt{1 - 2\frac{a}{r} \hat{r} \cdot \hat{a} + \left(\frac{a}{r}\right)^2}} \stackrel{\text{by GF}}{=} \frac{1}{r} \sum_{n=0}^{\infty} \left(\frac{a}{r}\right)^n P_n(\hat{r} \cdot \hat{a}); r \geq a$$

for $r \leq a$, we replace $r \leftrightarrow a$: $\frac{1}{|\vec{r} - \vec{a}|} = \frac{1}{a} \sum_{n=0}^{\infty} \left(\frac{r}{a}\right)^n P_n(\hat{r} \cdot \hat{a})$

$$\therefore \frac{1}{|\vec{r} - \vec{a}|} = \sum_{n=0}^{\infty} g_n(r, a) P_n(\hat{r} \cdot \hat{a}) \quad \text{where } g_n(r, a) = \begin{cases} \frac{1}{r} \left(\frac{a}{r}\right)^n; & r \geq a \\ \frac{1}{a} \left(\frac{r}{a}\right)^n; & r \leq a \end{cases}$$


• Laplacian

* $\Delta r^n = n(n+1)r^{n-2} \Rightarrow \Delta \frac{1}{r} \stackrel{r \neq 0 \text{ transl.}}{=} 0 \Rightarrow \Delta \frac{1}{|\vec{r} - \vec{a}|} = 0; \vec{r} \neq \vec{a}$

* In Coulomb's expansion, taking Δ and comparing the a^n and a^{n-1} terms, respectively:

$$\Delta(r^n P_n) = 0 \quad \wedge \quad \Delta(r^{n-1} P_n) \stackrel{r \neq 0}{=} 0$$

* On the other hand, by $\Delta(fg) = (\Delta f)g + 2\nabla f \cdot \nabla g + f\Delta g$:

$$\begin{aligned} \Delta(r^n P_n) &= (\Delta r^n) P_n + 2\nabla r^n \cdot \nabla P_n + r^n \Delta P_n = \\ &= n(n+1)r^{n-2} P_n + 2n \underbrace{r^{n-1} \hat{r} \cdot \nabla P_n}_{\frac{\partial P_n}{\partial r}} + r^n \Delta P_n = 0 \end{aligned}$$

$\therefore \Delta P_n = -\frac{1}{r^2} n(n+1) P_n$ for any $\hat{a}$

|| Exercise: Show that $\Delta(r^{n+2} P_n) = 2(2n+3)r^n P_n$

3 ORTHOGONAL FORMULAE

• Two Legendres orthogonality

* Recall $\oint_{\partial V} d\vec{S} \cdot \vec{T} = \int_V \nabla \cdot \vec{T} dV$ Gauss' theorem, put

$$\vec{T} = f \nabla g - g \nabla f \Rightarrow \nabla \cdot \vec{T} = \nabla f \cdot \nabla g + f \Delta g - \nabla g \cdot \nabla f - g \Delta f$$

$$\therefore \text{We get Green's identity } \oint_{\partial V} (f \nabla g - g \nabla f) \cdot d\vec{S} = \int_V f \Delta g - g \Delta f dV$$

* Let $V = B_1(0)$ (unit ball in $\mathbb{E}^3$), $f = r^n P_n(\hat{r} \cdot \hat{a})$; $g = r^m P_m(\hat{r} \cdot \hat{b})$

$$\therefore \text{RHS OF GI: } \int_V f \Delta g - g \Delta f dV = 0$$

* Since $d\vec{S} = \hat{r} r^2 d\Omega = \hat{r} d\Omega$ and $\nabla P_n(\hat{r} \cdot \hat{a}) \perp \hat{r}$,

$$\text{we get } (f \nabla g - g \nabla f) \cdot d\vec{S} = (m-n) P_n(\hat{r} \cdot \hat{a}) P_m(\hat{r} \cdot \hat{b})$$

$$\text{LHS} \stackrel{\text{GI}}{=} \text{RHS} \Rightarrow \oint P_n(\hat{r} \cdot \hat{a}) P_m(\hat{r} \cdot \hat{b}) d\Omega = 0 \text{ for } n \neq m$$

• Dirac kernel expansion ($\delta(\vec{r}-\vec{a})$)

* Recall $\Delta(\frac{1}{r}) = 0$ at $r \neq 0 \Rightarrow$ Ansatz $\Delta \frac{1}{r} = A \delta(\vec{r})$

Integrating over $B_1(0)$: $\int_V A \delta(\vec{r}) dV = A$, on the o.h.

$$\text{LHS} = \int_V \Delta \frac{1}{r} dV = \int_V \nabla \cdot \nabla \frac{1}{r} dV \stackrel{\text{G.T.}}{=} \oint_S (\nabla \frac{1}{r}) \cdot d\vec{S} =$$

$$= - \oint \frac{1}{r^2} \hat{r} \cdot r^2 \hat{r} d\Omega = - \oint d\Omega = -4\pi \quad \therefore A = -4\pi$$

and $\Delta \frac{1}{r} = -4\pi \delta(\vec{r}) \xrightarrow{\text{transl.}} \boxed{\Delta \frac{1}{|\vec{r}-\vec{a}|} = -4\pi \delta(\vec{r}-\vec{a})}$

* Taking Δ of the Coulomb's expansion:

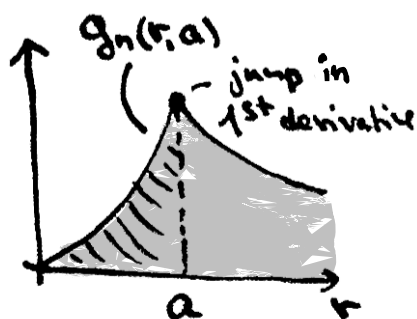
$$-4\pi \delta(\vec{r}-\vec{a}) = \sum_{n=0}^{\infty} \Delta(g_n(r,a) P_n(\hat{r} \cdot \hat{a})) =$$

$$= \sum_{n=0}^{\infty} (\Delta g_n) P_n + 2 \nabla g_n \cdot \nabla P_n + g_n \Delta P_n =$$

$$= \sum_{n=0}^{\infty} \left(\frac{1}{r^2} (r^2 g_n') \right)' - \frac{1}{r^2} g_n n(n+1) P_n$$

$$\Leftrightarrow \text{only possible if } (r^2 g_n')' - g_n n(n+1) = B \delta(r-a)$$

* Integrating over $\int_{a-\epsilon}^{a+\epsilon} dr$: $a^2 (g_n'(a^+) - g_n'(a^-)) = B$



$$\text{But } g_n'(a^-) = \left[\frac{1}{a} \left(\frac{r}{a} \right)^n \right]' \Big|_a = \frac{n}{a^2}$$

$$g_n'(a^+) = \left[\frac{1}{r} \left(\frac{a}{r} \right)^n \right]' \Big|_a = -\frac{n+1}{a^2}$$

$\therefore$ $\boxed{\delta(\vec{r}-\vec{a}) = \frac{1}{a^2} \delta(r-a) \sum_{n=0}^{\infty} \frac{2n+1}{4\pi} P_n(\hat{r} \cdot \hat{a})} \quad (\text{DKE})$

• Master orthogonal formula

* Two ways how to compute $I = \int_{\mathbb{R}^3} P_m(\hat{r} \cdot \hat{b}) \delta(\vec{r} - \vec{a}) dV$

* Either by def of δ : $I \stackrel{\vec{r}=\vec{a}}{=} P_m(\hat{a} \cdot \hat{b})$

* Or by DKE: $I = \oint_{\Omega} d\Omega \int_0^{\infty} dr r^2 P_m(\hat{r} \cdot \hat{b}) \delta(\vec{r} - \vec{a}) =$
 $= \underbrace{\frac{1}{a^2} \int_0^{\infty} r^2 \delta(r-a) dr}_{a^2} \sum_{n=0}^{\infty} \frac{2n+1}{4\pi} \underbrace{\oint d\Omega P_n(\hat{r} \cdot \hat{a}) P_m(\hat{r} \cdot \hat{b})}_{=0 \text{ if } n \neq m}$

$$= \frac{2m+1}{4\pi} \oint P_m(\hat{r} \cdot \hat{a}) P_m(\hat{r} \cdot \hat{b}) d\Omega$$

* $\therefore \oint_{\Omega} P_n(\hat{r} \cdot \hat{a}) P_m(\hat{r} \cdot \hat{b}) d\Omega = \frac{4\pi}{2n+1} \delta_{nm} P_n(\hat{a} \cdot \hat{b}) \quad (OG)$

• Polynomial orthogonal formula

* Spec case $\hat{a} = \hat{b} = \hat{z} \rightarrow \hat{r} \cdot \hat{a} = \hat{r} \cdot \hat{b} = \cos \theta \equiv x$,

* LHS = $\int_0^{2\pi} \int_0^{\pi} P_n(\cos \theta) P_m(\cos \theta) \sin \theta d\theta d\varphi = 2\pi \int_{-1}^1 P_n(x) P_m(x) dx$

* RHS = $\frac{4\pi}{2n+1} \delta_{nm} \underbrace{P_n(1)}_{=1} \therefore \int_{-1}^1 P_n(x) P_m(x) dx = \frac{2}{2n+1} \delta_{nm}$

• φ -orthogonal formula

* let $\delta(x-y) = \sum_{n=0}^{\infty} A_n P_n(x) / \int_{-1}^1 dx P_m(x) : P_n(y) = \frac{2A_n}{2n+1}$

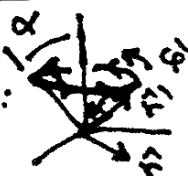
$$\therefore \delta(x-y) = \sum_{n=0}^{\infty} \frac{2n+1}{2} P_n(x) P_n(y)$$

* Put $x = \hat{r}' \cdot \hat{z} = \cos \theta'$, $y = \cos \alpha$ (const.)

$$\delta(\cos \theta' - \cos \alpha) = \sum \frac{2n+1}{2} P_n(\hat{r}' \cdot \hat{z}) P_n(\cos \alpha) / \oint d\hat{r}' P_m(\hat{r}' \cdot \hat{z})$$

$$\int_0^{\pi} \int_0^{2\pi} \delta(\cos \theta' - \cos \alpha) \sin \theta' P_n(\hat{r}' \cdot \hat{r}) d\varphi d\theta' \stackrel{OG}{=} \frac{2n+1}{2} \frac{4\pi}{2n+1} P_n(\hat{r} \cdot \hat{z}) P_n(\cos \alpha)$$

$\therefore \int_0^{2\pi} P_n(\hat{r}' \cdot \hat{r}) d\varphi = 2\pi P_n(\hat{r} \cdot \hat{z}) P_n(\hat{z} \cdot \hat{r}') \quad (\varphi OG)$



4 VECTOR LEGEDRES

• Axial expansion :

* Scalar fields $\phi(r, \theta) = \sum \phi_n(r) P_n$ argument $\hat{r} \cdot \hat{z} = \cos \theta$

* Vector fields $\vec{\psi}(r, \theta) = \sum u_n(r) \underbrace{\hat{r}}_{\vec{P}_n} P_n + v_n(r) \underbrace{r \nabla P_n}_{\vec{Q}_n} + w_n(r) \underbrace{\vec{r} \times \nabla P_n}_{\vec{R}_n}$

vector legedres $\rightarrow \vec{P}_n \quad \vec{Q}_n \quad \vec{R}_n$

• Low order values :

* $P_0 = 1 \Rightarrow \vec{Q}_0 = \vec{R}_0 = 0$

* $\vec{Q}_1 = r \nabla P_1 = r \nabla(\hat{r} \cdot \hat{z}) = r \nabla \hat{r} \cdot \hat{z} = r \frac{1 - \hat{r}^2}{r} \cdot \hat{z} =$
 $= \hat{z} - \hat{r}(\hat{r} \cdot \hat{z}) = (\hat{r}\hat{r} + \hat{\theta}\hat{\theta}) \cdot (\hat{z} - \hat{r}(\hat{r} \cdot \hat{z})) =$
 $= \hat{\theta}(\hat{\theta} \cdot \hat{z}) = -\sin \theta \hat{\theta} \quad + \hat{\phi}\hat{\phi}$

* $\vec{R}_1 = \hat{r} \times \vec{Q}_1 = -\sin \theta \hat{r} \times \hat{\theta} = -\sin \theta \hat{\phi}$



• Basic properties

a) $(\vec{P}_n, \vec{Q}_n, \vec{R}_n)$ forms an orthogonal basis $\Rightarrow \hat{r} \cdot \vec{Q}_n = \hat{r} \cdot \vec{R}_n = 0$

b) Since $\vec{P}_n, \vec{Q}_n, \vec{R}_n$ indep. of $r \Rightarrow \partial_r = \hat{r} \cdot \nabla = 0$

c) Divergence :

* $\nabla \cdot \vec{P}_n = \nabla \cdot (\hat{r} P_n) = \hat{r} \cdot \nabla P_n + \frac{2}{r} P_n = \frac{2}{r} P_n$

* $\nabla \cdot \vec{Q}_n = \nabla \cdot (r \nabla P_n) = \cancel{\nabla r \cdot \nabla P_n} + r \Delta P_n = -\frac{1}{r} n(n+1) P_n$

* $\nabla \cdot \vec{R}_n = \nabla \cdot (\vec{r} \times \nabla P_n) = \nabla P_n \cdot (\nabla \times \vec{r}) - \vec{r} \cdot (\nabla \times \nabla P_n) = 0$
 $[\vec{a} \cdot (\vec{b} \times \vec{c}) = \vec{c} \cdot (\vec{a} \times \vec{b}) = \vec{b} \cdot (\vec{c} \times \vec{a})]$

d) Transposed $\hat{r} \cdot \nabla$:

* $\hat{r} \cdot (\nabla \vec{P}_n)^T = (\nabla \vec{P}_n) \cdot \hat{r} = \nabla(\hat{r} P_n) \cdot \hat{r} = \nabla P_n \cdot \hat{r} \cdot \hat{r} + P_n \nabla \hat{r} \cdot \hat{r} = \frac{2}{r} P_n$

* $\nabla \vec{Q}_n \cdot \hat{r} = \nabla(r \nabla P_n) \cdot \hat{r} = \hat{r} \cdot \nabla P_n \cdot \hat{r} + r \nabla^2 P_n \cdot \hat{r} =$
 $= r \hat{r} \cdot \nabla^2 P_n = r \partial_r \nabla P_n = r \partial_r \frac{\vec{Q}_n}{r} = -\frac{1}{r} \vec{Q}_n$

$$\begin{aligned}
 * \nabla \vec{R}_n \cdot \hat{r} &= \nabla (\hat{r} \times \nabla P_n) \cdot \hat{r} = (\mathbf{I} \times \nabla P_n) \cdot \hat{r} - (\nabla^2 P_n \times \hat{r}) \cdot \hat{r} = \\
 &= \mathbf{I} \cdot (\nabla P_n \times \hat{r}) - \nabla^2 P_n \cdot (\hat{r} \times \hat{r})^0 = \nabla P_n \times \hat{r} = -\frac{1}{r} \vec{R}_n
 \end{aligned}$$

e) $\times$ with $\hat{r}$:

$$* \hat{r} \times \vec{P}_n = \hat{r} \times \hat{r} P_n = \vec{0}$$

$$* \hat{r} \times \vec{Q}_n = \hat{r} \times (r \nabla P_n) = \vec{r} \times \nabla P_n = \vec{R}_n$$

$$* \hat{r} \times \vec{R}_n = \hat{r} \times (\vec{r} \times \nabla P_n) = \hat{r} (\hat{r} \cdot \nabla P_n) - \nabla P_n (\hat{r} \cdot \hat{r}) = -\vec{Q}_n$$

f) Curl:

$$* \nabla \times \vec{P}_n = \nabla \times (\hat{r} P_n) = \nabla P_n \times \hat{r} + (\nabla \times \hat{r}) P_n = -\frac{1}{r} \vec{R}_n$$

$$* \nabla \times \vec{Q}_n = \nabla \times (r \nabla P_n) = \hat{r} \times \nabla P_n + r \nabla \times \nabla P_n = \frac{1}{r} \vec{R}_n$$

$$\begin{aligned}
 * \nabla \times \vec{R}_n &= \nabla \times (\vec{r} \times \nabla P_n) = \vec{r} \Delta P_n + \nabla P_n \cdot \nabla \vec{r} - \nabla P_n \nabla \cdot \vec{r} - \vec{r} \cdot \nabla^2 P_n \\
 &= -\frac{n(n+1)}{r} \vec{P}_n + \nabla P_n - 3 \nabla P_n + \frac{1}{r} \vec{Q}_n = -\frac{1}{r} (\vec{Q}_n + n(n+1) \vec{P}_n)
 \end{aligned}$$

g) Laplacian

$$\begin{aligned}
 * \Delta \vec{P}_n &= \Delta (\hat{r} P_n) = \Delta \hat{r} P_n + 2 \nabla P_n \cdot \nabla \hat{r} + \hat{r} \Delta P_n = \\
 &= -\frac{2}{r^2} \hat{r} P_n + \frac{2}{r} \nabla P_n \cdot (\mathbf{I} - \hat{r} \hat{r}) - \frac{\hat{r}}{r^2} n(n+1) P_n \\
 &= -\frac{2}{r^2} \vec{P}_n + \frac{2}{r^2} (\vec{Q}_n - \vec{0}) - \frac{n(n+1)}{r^2} \vec{P}_n = -\frac{2+n(n+1)}{r^2} \vec{P}_n + \frac{2\vec{Q}_n}{r^2}
 \end{aligned}$$

$$\begin{aligned}
 * \Delta \vec{Q}_n &= \Delta (r \nabla P_n) = \Delta r \nabla P_n + 2 \nabla r \cdot \nabla^2 P_n + r \nabla \Delta P_n = \\
 &= \frac{2}{r} \nabla P_n + 2 \hat{r} \cdot \nabla^2 P_n - n(n+1) r \nabla \left(\frac{1}{r^2} P_n \right) = \\
 &= \frac{n(n+1)}{r^2} [2 \vec{P}_n + \vec{Q}_n]
 \end{aligned}$$

$$\begin{aligned}
 * \Delta \vec{R}_n &= \Delta (\vec{r} \times \nabla P_n) = \vec{r} \times \nabla \Delta P_n = -n(n+1) \vec{r} \times \nabla \left(\frac{1}{r^2} P_n \right) = \\
 &= -\frac{n(n+1)}{r^2} \vec{r} \times \nabla P_n = -\frac{n(n+1)}{r^2} \vec{R}_n
 \end{aligned}$$

|| Exercise: Show $(n+1) \nabla (r^n P_n) + \nabla \times (r^n \vec{R}_n) = 0$.

5 Miscellaneous

a) $P_1^2 \stackrel{\text{even}}{=} AP_0 + BP_2$

$(P_n = P_n(\hat{r} \cdot \hat{z}) = P_n(\cos\theta))$

* $\frac{1}{4\pi} \oint \frac{1}{3} \equiv A$

* $\cos\theta = 1 : 1 \equiv A + B$

$$P_1^2 = \frac{1}{3}P_0 + \frac{2}{3}P_2$$

b) $s^2\theta = 1 - c^2\theta = 1 - P_1^2$

$$\therefore s^2\theta = \frac{2}{3}(P_0 - P_2)$$

c) $\vec{Q}_1 = -s\theta \hat{\theta} \Rightarrow \vec{Q}_1 \cdot \vec{Q}_1 = \frac{2}{3}(P_0 - P_2)$

d) $\underbrace{P_1^2}_{s^2\theta} = \frac{1}{3}P_0 + \frac{2}{3}P_2 \quad / \cdot \nabla : 2P_1 \vec{Q}_1 = \frac{2}{3}\vec{Q}_2 \therefore P_1 \vec{Q}_1 = \frac{1}{3}\vec{Q}_2$

e) $P_1 P_2 \stackrel{\text{odd}}{=} AP_1 + BP_3 \quad / \cdot P_1$

* $\frac{1}{4\pi} \oint \underbrace{P_1^2}_{\frac{1}{3}P_0 + \frac{2}{3}P_2} P_2 d\Omega = \frac{2}{3} \cdot \frac{1}{5} \stackrel{\text{RHS}}{=} \frac{1}{4\pi} \oint P_1 (AP_1 + BP_3) d\Omega = \frac{1}{3}A$

* $\cos\theta = 1 : 1 = A + B$

$\therefore$

$$P_1 P_2 = \frac{2}{5}P_1 + \frac{3}{5}P_3 \quad \leftarrow A = \frac{2}{5}$$

f) $\vec{Q}_1 \cdot \vec{Q}_2 = 3\vec{Q}_1 \cdot (P_1 \vec{Q}_1) = 3P_1 \frac{2}{3}(P_0 - P_2) = 2(P_1 - \frac{2}{5}P_1 - \frac{3}{5}P_3)$

$$\therefore \vec{Q}_1 \cdot \vec{Q}_2 = \frac{6}{5}(P_1 - P_3)$$

g) $P_1^3 \stackrel{\text{odd}}{=} AP_1 + BP_3 \quad / \cdot P_1$

* $\frac{1}{4\pi} \oint \underbrace{P_1^4}_{\frac{1}{3}P_0 + \frac{2}{3}P_2} d\Omega = \frac{1}{4\pi} \oint (\underbrace{P_1^2}_{\frac{1}{3}P_0 + \frac{2}{3}P_2})^2 d\Omega = \left(\frac{1}{3}\right)^2 + \left(\frac{2}{3}\right)^2 \frac{1}{5} \equiv \frac{1}{4\pi} \oint P_1 (AP_1 + BP_3) d\Omega \quad A/3$

* $\cos\theta = 1 : 1 \equiv A + B$

$\therefore$

$$P_1^3 = \frac{3}{5}P_1 + \frac{2}{5}P_3$$

h) Taking ∇ of g): $3P_1^2 \vec{Q}_1 = \frac{3}{5}\vec{Q}_1 + \frac{2}{5}\vec{Q}_2$

$\frac{1}{3}P_0 + \frac{2}{3}P_2$

$\therefore$

$$P_2 \vec{Q}_1 = \frac{1}{5}(\vec{Q}_3 - \vec{Q}_1)$$

i) Since $P_1 P_2 = \frac{2}{5}P_1 + \frac{3}{5}P_3 \xrightarrow{\nabla} P_2 \vec{Q}_1 + P_1 \vec{Q}_2 = \frac{2}{5}\vec{Q}_1 + \frac{3}{5}\vec{Q}_3$

& since $P_2 \vec{Q}_1$ in h):

$$P_1 \vec{Q}_2 = \frac{3}{5}\vec{Q}_1 + \frac{2}{5}\vec{Q}_3$$

$$j) P_1^2 P_2 \stackrel{\text{even}}{=} A P_0 + B P_2 + C P_4$$

$$* \frac{1}{4\pi} \oint \underbrace{P_1^2}_{\frac{1}{3}P_0 + \frac{2}{3}P_2} P_2 d\Omega = \frac{2}{3} \frac{1}{5} \equiv A \quad \therefore A = \frac{2}{15} \quad \cdot P_2$$

$$* \frac{1}{4\pi} \oint P_1^2 P_2^2 d\Omega = \frac{1}{4\pi} \oint \underbrace{(P_1 P_2)^2}_{\frac{2}{5}P_1 + \frac{2}{5}P_3} d\Omega = \left(\frac{2}{5}\right)^2 \frac{1}{3} + \left(\frac{2}{5}\right)^2 \frac{1}{7} \equiv \frac{B}{5}$$

$$* c\theta = 1: 1 \equiv A + B + C \quad \therefore$$

$$P_1^2 P_2 = \frac{2}{15} P_0 + \frac{11}{21} P_2 + \frac{12}{35} P_4$$

$$k) \vec{Q}_2 \cdot \vec{Q}_2 = 3P_1 \vec{Q}_1 \cdot 3P_1 \vec{Q}_1 = 6P_1^2 (P_0 - P_2) = 6(A^2 - P_1^2 P_2) =$$

$$= 6\left(\frac{1}{3}P_0 + \frac{2}{3}P_2 - \frac{2}{15}P_0 - \frac{11}{21}P_2 - \frac{12}{35}P_4\right) \quad \therefore \vec{Q}_2 \cdot \vec{Q}_2 = 6\left(\frac{1}{5}P_0 + \frac{1}{7}P_2 - \frac{12}{35}P_4\right)$$

$$l) c\theta^4 = P_1^4 = P_1^2 P_1^2 = P_1^2 \left(\frac{1}{3}P_0 + \frac{2}{3}P_2\right) = \frac{1}{3}(P_1^2 + 2P_1^2 P_2)$$

$$= \frac{1}{3}\left(\frac{1}{3}P_0 + \frac{2}{3}P_2 + 2\left(\frac{2}{15}P_0 + \frac{11}{21}P_2 + \frac{12}{35}P_4\right)\right) \quad \therefore P_1^4 = \frac{1}{5}P_0 + \frac{4}{7}P_2 + \frac{8}{35}P_4$$

$$m) s^4\theta = (1 - c^2\theta)^2 = (1 - P_1^2)^2 = 1 - 2P_1^2 + P_1^4 = 1 - 2\left(\frac{1}{3}P_0 + \frac{2}{3}P_2\right)$$

$$+ \frac{1}{5}P_0 + \frac{4}{7}P_2 + \frac{8}{35}P_4 \quad \therefore s^4\theta = \frac{8}{15}P_0 - \frac{16}{21}P_2 + \frac{8}{35}P_4$$

$$n) \text{ Since } P_1^2 = \frac{1}{3}P_0 + \frac{2}{3}P_2 \Rightarrow P_2 = \frac{1}{2}(3P_1^2 - 1) \quad (\text{familiar!})$$

$$* P_2^2 = \frac{1}{2}P_2(3P_1^2 - 1) = \frac{1}{2}(3P_1^2 P_2 - P_2) =$$

$$= \frac{1}{2}\left[3\left(\frac{2}{15}P_0 + \frac{11}{21}P_2 + \frac{12}{35}P_4\right) - P_2\right] \quad \therefore P_2^2 = \frac{1}{5}P_0 + \frac{2}{7}P_2 + \frac{18}{35}P_4$$

$$o) \text{ Taking } \nabla: 2P_2 \vec{Q}_2 = \frac{1}{5} \cancel{\vec{Q}_0}^0 + \frac{2}{7} \vec{Q}_2 + \frac{18}{35} \vec{Q}_4$$

$$\therefore P_2 \vec{Q}_2 = \frac{1}{7} \vec{Q}_2 + \frac{9}{35} \vec{Q}_4$$

C SHAPE DESCRIPTION OF A NEAR-SPHERICAL BODY

1 TOPOGRAPHY & ITS TRANSFORMATIONS

• Description



perfect sphere

physics
 $m \dots$ perturb.
 parameter



Topography ($O(m^2)$)
 $T = R(1 + mt + m^2u)$

$$t = \sum_{n=0}^{\infty} t_n P_n$$

$$u = \sum_{n=0}^{\infty} u_n P_n$$

• Normal vector field



$$\hat{n} \perp r - T = 0 \perp \vec{n} := \nabla(r - T) = \hat{r} - Rm\nabla t - Rm^2\nabla u$$

$$\text{so } |\vec{n}| = \sqrt{\vec{n} \cdot \vec{n}} = \sqrt{1 + m^2 R^2 (\nabla t \cdot \nabla t)} =$$

$$= 1 + \frac{1}{2} m^2 R^2 |\nabla t|^2 + O(m^3)$$

$$\therefore \hat{n} = \frac{\vec{n}}{|\vec{n}|} = (\hat{r} - mR\nabla t - m^2 R\nabla u) (1 - \frac{1}{2} R^2 m^2 |\nabla t|^2) =$$

$$= \hat{r} - mR\nabla t - \frac{1}{2} m^2 R^2 \hat{r} |\nabla t|^2 - m^2 R\nabla u + O(m^3)$$

• Fixed-volume topography constraints

$$V = \iiint dV = \oint d\Omega \int_0^T dr r^2 = \frac{R^3}{3} \oint (1 + mt + m^2u)^3 d\Omega =$$

$$= \frac{R^3}{3} \oint (1 + 3mt + 3m^2u + 3m^2t^2) d\Omega =$$

$$= \underbrace{\frac{4\pi R^3}{3}}_{V_0} \left(1 + \underbrace{3m t_0 + 3m^2 u_0}_{\delta} + 3m^2 \sum_{n=0}^{\infty} \frac{t_n^2}{2n+1} \right)$$

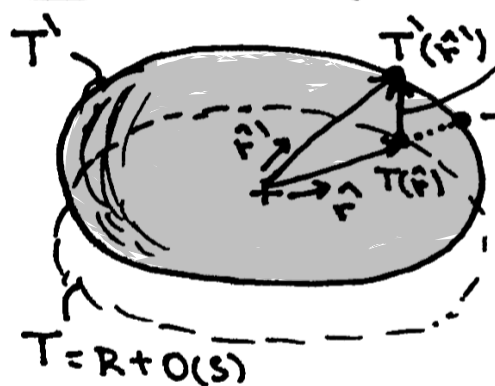
$\delta \sim$ stretch factor $\left[\delta = \frac{V}{V_0} - 1 + O(m^2) \right]$

* Constraints on $V = V_0$

a) $t_0 = 0$

b) $u_0 = - \sum_{n=0}^{\infty} \frac{t_n^2}{2n+1} = -\frac{t_1^2}{3} - \frac{t_2^2}{5} - \frac{t_3^2}{7} - \dots$

• Shifted topography



$\vec{s} = s \hat{z}$ translation ($s = (md + m^2/3R)$) of
old topo $T = T(\hat{r}) = R(1 + mt + m^2u)$ to
new topo $T' = T'(\hat{r}) = R(1 + mt' + m^2u')$

* Note $T'(\hat{r}')\hat{r}' = T(\hat{r})\hat{r} + \vec{s} / 1.1$

$$T'(\hat{r}') = \sqrt{T^2 + 2Ts\hat{r} \cdot \hat{z} + s^2} \Rightarrow$$

$$\begin{aligned} & \Rightarrow T \sqrt{1 + 2\frac{s}{T}P_1 + \frac{s^2}{T^2}} \approx T \left(1 + \frac{s}{T}P_1 + \frac{s^2}{2T^2} - \frac{s^2}{2T^2}P_1^2 \right) = \\ & = T + sP_1 + \frac{s^2}{3R}(1 - P_2) + O(s^3) = \\ & = R \left[1 + m(t + \alpha P_1) + m^2(u + \beta P_1 + \frac{\alpha^2}{3}(1 - P_2)) \right] + O(m^3) \end{aligned}$$

* Transformation of the $\hat{r}$ vector ($O(m)$)

$$\begin{aligned} \hat{r}' &= \frac{T\hat{r} + \vec{s}}{|T\hat{r} + \vec{s}|} = \frac{T\hat{r} + \vec{s}}{T'(\hat{r}')} = (T\hat{r} + \vec{s})(T + sP_1)^{-1} = \\ &= (\hat{r} + \frac{\vec{s}}{T})(1 + \frac{s}{T}P_1)^{-1} = (\hat{r} + \frac{\vec{s}}{R})(1 - \frac{s}{R}P_1) = \\ &= \hat{r} + \frac{s}{R}(\hat{z} - \hat{r}P_1) = \hat{r} + \frac{s}{R}\vec{\Theta}_1 = \hat{r} + m\alpha\vec{\Theta}_1 + O(m^2) \end{aligned}$$

* Transformation $T'(\hat{r}') \rightarrow T'(\hat{r}) \equiv T'$:

$$\begin{aligned} R(1 + mt' + m^2u') &\equiv T' = T'(\hat{r}) = T'(\hat{r}' - \alpha m \vec{\Theta}_1 + O(m^2)) = \\ &= T'(\hat{r}') - (\alpha m \vec{\Theta}_1 + O(m^2)) \cdot \nabla T'(\hat{r}') \end{aligned}$$

$$\begin{aligned} \text{But } (\alpha m \vec{\Theta}_1 + O(m^2)) \cdot \nabla T'(\hat{r}') &= (\alpha m \vec{\Theta}_1 + O(m^2)) \cdot Rm(\nabla t + \alpha \vec{\Theta}_1) \\ &= R\alpha m^2 \vec{\Theta}_1 \cdot \nabla t + R\alpha^2 m^2 \underbrace{\vec{\Theta}_1 \cdot \vec{\Theta}_1}_{\frac{2}{3}(1 - P_2)} \end{aligned}$$

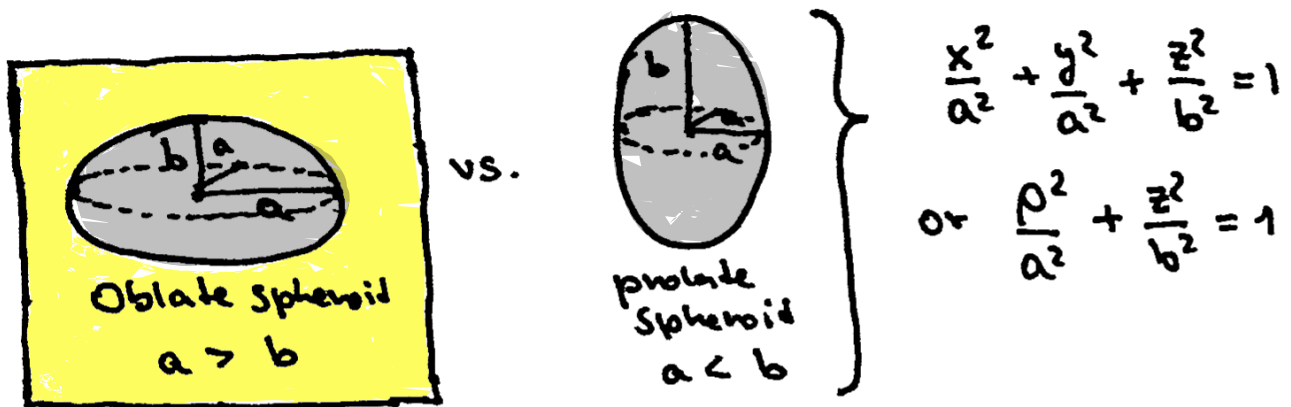
$$\therefore R[1 + mt' + m^2u'] \equiv R \left[1 + m(t + \alpha R) + m^2(u + \beta P_1 - \frac{\alpha^2}{3}(1 - P_2) - \alpha \vec{\Theta}_1 \cdot \nabla t) \right]$$

$$\therefore \boxed{a) t' = t + \alpha R} \quad \boxed{b) u' = u + \beta P_1 - \frac{\alpha^2}{3}(1 - P_2) - \alpha \vec{\Theta}_1 \cdot \nabla t}$$

* Shift degeneracy (in problems with $\hat{z}$ -transl. symmetry)

$\Rightarrow$ we can choose $t_1 = 0, u_1 = 0$ ($\because \alpha, \beta$)

2 BIAXIAL ELLIPSOIDS (SPHEROIDS)



- Topographic expansion (oblate sph. only) ($O(n^2)$)

* Eccentricity $e^2 := 1 - \frac{b^2}{a^2}$

* Volume & axes

$$V = \frac{4}{3}\pi a^2 b \equiv \frac{4}{3}\pi R_E^3 \sim \text{"effective radius"}$$

$$\therefore a = R_E(1 - e^2)^{-1/6} = R_E(1 + \frac{e^2}{6} + \frac{7}{72}e^4)$$

$$\therefore b = R_E(1 - e^2)^{1/3} = R_E(1 - \frac{e^2}{3} - \frac{e^4}{9})$$

* The expansion :

$$\text{Since } 1 = \frac{\rho^2}{a^2} + \frac{z^2}{b^2} = \frac{r^2 s^2 \theta}{a^2} + \frac{r^2 c^2 \theta}{b^2} = \frac{r^2}{b^2} [(1 - e^2) s^2 \theta + c^2 \theta]$$

$$\therefore T = \frac{b}{\sqrt{1 - e^2 s^2 \theta}} = R_E(1 - e^2)^{1/3} (1 - e^2 s^2 \theta)^{-1/2} \approx$$

$$\approx R_E(1 - \frac{e^2}{3} - \frac{e^4}{9})(1 + \frac{1}{2}e^2 s^2 \theta + \frac{3}{8}e^4 c^4 \theta) \equiv$$

$$\equiv R_E \left[1 - \frac{e^2}{3} P_2 + e^4 \left(-\frac{P_0}{45} - \frac{11}{63} P_2 + \frac{3}{35} P_4 \right) \right] \equiv T_{05}$$

Standard second oblate ellipsoid expansion

- Matching conditions

* When is T a spheroid? $\Rightarrow T = R(1 + m_t + m_u^2)$ describes a topography of an oblate spheroid iff $T_{05} \equiv \underbrace{T}_{T_1} (+ \text{shift})$

* Since T_{05} contains P_2 and P_4 only,

$$t = t_0 + t_1 P_1 + t_2 P_2$$

$$u = u_0 + u_1 P_1 + u_2 P_2 + u_3 P_3 + u_4 P_4$$

* Eccentricity expansion : $e^2 = A m + B m^2$

* Volume constrain :

$$V = \underbrace{V_0}_{\frac{4}{3}\pi R^3} (1 + 3m t_0 + 3m^2 (u_0 + t_0^2 + \frac{1}{3} t_1^2 + \frac{1}{5} t_2^2)) \equiv \frac{4\pi}{3} R_E^3$$

$$\therefore R = R_E (1 - m t_0 - m^2 (u_0 - t_0^2 + \frac{1}{3} t_1^2 + \frac{1}{5} t_2^2))$$

* Shift matching : $T \xrightarrow{+\vec{S} = (\alpha m + \beta m^2) \vec{z}^2 R} T' \equiv T_{OS}$ no P_1 s !

a) $t' = t + \alpha P_1 = t_0 + t_1 P_1 + t_2 P_2 + \alpha P_1 \therefore \boxed{\alpha = -t_1}$

b) $u' = u + \beta P_1 - \alpha \vec{Q}_1 \cdot \vec{v} \vec{v} t - \frac{1}{3} \alpha^2 P_0 + \frac{1}{3} \alpha^2 P_2 =$
 $= u + \beta P_1 + t_1 \vec{Q}_1 \cdot (t_1 \vec{Q}_1 + t_2 \vec{Q}_2) - \frac{1}{3} t_1^2 P_0 + \frac{1}{3} t_1^2 P_2$

$$\equiv u_0 P_0 + u_1 P_1 + u_2 P_2 + u_3 P_3 + u_4 P_4 + \beta P_1 + \frac{6}{5} t_1 t_2 (P_1 - P_3) + \frac{1}{3} t_1^2 - \frac{1}{3} t_1^2 P_2 \therefore \boxed{\beta = -u_1 - \frac{6}{5} t_1 t_2}$$

* Final matching

$$T' = R(1 + m t' + m^2 u') = R_E [1 - m t_0 - m^2 (u_0 - t_0^2 + \frac{1}{3} t_1^2 + \frac{1}{5} t_2^2)] \cdot [1 + m(t_0 P_0 + t_2 P_2) + m^2 (u_0 P_0 + u_2 P_2 + u_3 P_3 + u_4 P_4 - \frac{6}{5} t_1 t_2 P_3 + \frac{1}{3} t_1^2 - \frac{1}{3} t_1^2 P_2)] \equiv T_{OS} \Big|_{e^2 = A m + B m^2}$$

$$= R_E [1 - \frac{m}{3} A P_2 + m^2 (-\frac{1}{3} B P_2 + A^2 (-\frac{P_0}{45} - \frac{11}{63} P_2 + \frac{3}{35} P_4))]]$$

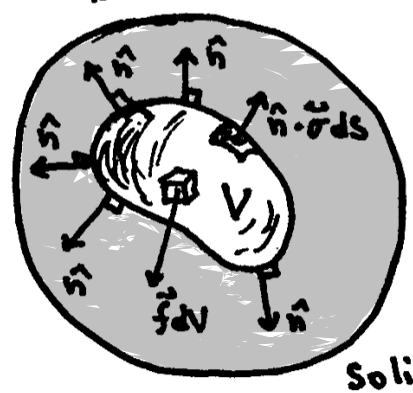
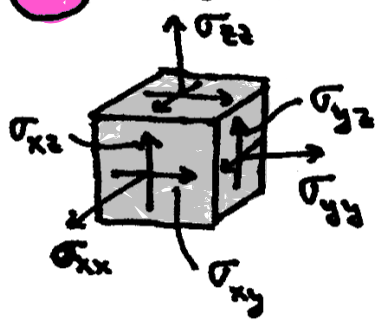
$\therefore$ Comparing the coefficients P_2, P_3, P_4 :

$$u_3 = \frac{6}{5} t_1 t_2 ; \quad u_4 = \frac{27}{35} t_2^2$$

$$e^2 = -3 t_2 m [1 + (\frac{u_2}{t_2} + \frac{11}{7} t_2 - t_0 - \frac{t_1^2}{3 t_2}) m]$$

D CONSTITUTIONAL & EQUILIBRIUM BALANCE EQS.

1 MOMENTUM BALANCE



" $\vec{F} = m\vec{a}$ "

$\rho \vec{a} = \vec{f} + \nabla \cdot \vec{\sigma}$

Solid, liquid ...

$\vec{F} = \vec{F}_V + \vec{F}_S = \iiint_V \vec{f} dV + \oint_S \hat{n} \cdot \vec{\sigma} dS \stackrel{GT}{=} \iiint_V \vec{f} + \nabla \cdot \vec{\sigma} dV$

* Special cases:

a) static case ($\vec{a} = 0$) $\Rightarrow$

$\vec{f} + \nabla \cdot \vec{\sigma} = 0$

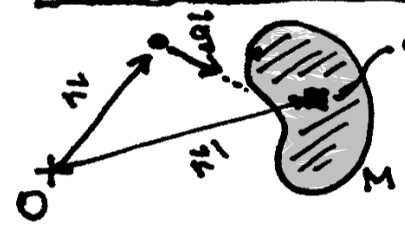
b) Potential volume force $\Rightarrow \vec{f} = -\rho \nabla V$
density potential

2 CONSTITUTIONAL EQUATIONS (OVERVIEW)

- $\vec{\sigma} = 0$... empty space
- $\vec{\sigma} = -p\mathbf{I}$... perfect fluid
- $\vec{\sigma} = -p\mathbf{I} + \eta(\nabla \vec{v} + \nabla \vec{v}^T)$... newtonian fluid
- $\vec{\sigma} = 2\mu \vec{\epsilon} + \lambda \mathbf{I} \text{Tr} \vec{\epsilon}$... elastic solid

3 NEWTONIAN GRAVITY

• Acceleration & potential



$dM(\vec{r}') = \rho(\vec{r}') dV(\vec{r}')$

* Since $\nabla \frac{1}{r} = -\frac{1}{r^2} \hat{r} = -\frac{1}{r^3} \vec{r}$

" $g = \frac{MG}{R^2}$ " $\Rightarrow \vec{g}(\vec{r}) = G \int_V \frac{\vec{r}' - \vec{r}}{|\vec{r}' - \vec{r}|^3} \rho(\vec{r}') dV' = G \int_V \nabla' \frac{\rho(\vec{r}')}{|\vec{r}' - \vec{r}|} dV'$

$\therefore \vec{g} = -\nabla V_G$, where $V_G = -G \int_V \frac{\rho(\vec{r}')}{|\vec{r}' - \vec{r}|} dV'$

• Topography induced potential



M.V

$$T = R(1 + m\epsilon + m^2 u) ; M = \frac{4}{3} \pi R^3 \rho^-$$

$$\epsilon = \sum_{n=0}^{\infty} \epsilon_n P_n(\hat{r} \cdot \hat{z})$$

$$u = \sum_{n=0}^{\infty} u_n P_n(\hat{r} \cdot \hat{z})$$

$$V_G^+; \rho^+ = 0$$

* External potential

$$\begin{aligned} V_G^+ &= -G \int_{r' < T} \frac{\rho^-(\hat{r}') dV'}{|\hat{r} - \hat{r}'|} \stackrel{CE}{=} -G \rho^- \sum_{n=0}^{\infty} \oint d\Omega' \int_0^T dr' r'^2 \frac{1}{r'} \left(\frac{r'}{r}\right)^n P_n(\hat{r} \cdot \hat{r}') \\ &= -G \rho^- \oint d\Omega' \sum_{n=0}^{\infty} \frac{1}{3+n} \frac{T^{3+n}}{r^{1+n}} P_n(\hat{r} \cdot \hat{r}') = \\ &= -G \rho^- R^2 \oint d\Omega' \sum_{n=0}^{\infty} \frac{1}{3+n} \left(\frac{R}{r}\right)^{1+n} (1 + m\epsilon' + m^2 u')^{3+n} P_n(\hat{r} \cdot \hat{r}') \\ &= -G \rho^- R^2 \oint d\Omega' \sum_{n=0}^{\infty} \frac{1}{3+n} \left(\frac{R}{r}\right)^{1+n} (1 + (3+n)m\epsilon' + (3+n)m^2 u' + \frac{1}{2}(3+n)(2+n)\epsilon'^2) P_n(\hat{r} \cdot \hat{r}') \\ &= -G \rho^- R^2 \left[\frac{4\pi}{3} \left(\frac{R}{r}\right) + \sum_{n=0}^{\infty} \frac{1}{3+n} \left(\frac{R}{r}\right)^{3+n} (\dots) P_n(\hat{r} \cdot \hat{r}') \right] = \\ &= -\underbrace{\frac{4\pi G R^2 \rho^-}{3}}_{GM/R} \left[\frac{R}{r} + 3m \sum_{n=0}^{\infty} \frac{\epsilon_n P_n}{2n+1} \left(\frac{R}{r}\right)^{1+n} + 3m^2 \sum_{n=0}^{\infty} \frac{u_n P_n}{2n+1} \left(\frac{R}{r}\right)^{1+n} \right. \\ &\quad \left. + \frac{3m^2}{8\pi} \sum_{n=0}^{\infty} \oint d\Omega' (2+n)\epsilon'^2 P_n(\hat{r} \cdot \hat{r}') \right] \end{aligned}$$

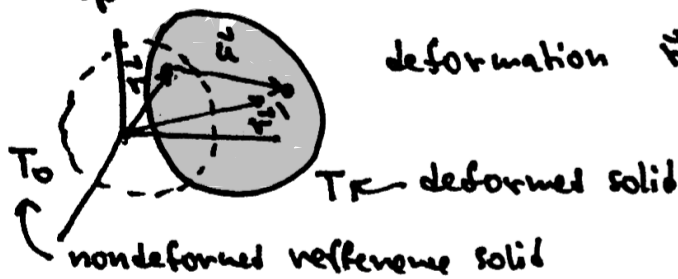
* Internal potential

$$\begin{aligned} V_G^- &= -G \int_{r' < T} \frac{\rho^-(\hat{r}') dV'}{|\hat{r} - \hat{r}'|} = -G \rho^- \sum_{n=0}^{\infty} \oint d\Omega' \left[\int_0^r dr' r'^2 \frac{1}{r'} \left(\frac{r'}{r}\right)^n + \int_r^T dr' r'^2 \frac{1}{r'} \left(\frac{r'}{r}\right)^n \right] P_n(\hat{r} \cdot \hat{r}') \\ &= -G \rho^- \oint d\Omega' \left(\frac{r^2}{6} - \frac{r^2}{3} + \sum_{n=0}^{\infty} \frac{1}{2-n} \frac{r^n}{r^{1+n-2}} \right) P_n(\hat{r} \cdot \hat{r}') = \\ &= -G \rho^- \left[-\frac{4\pi}{6} r^2 + R^2 \sum_{n=0}^{\infty} \frac{1}{2-n} \left(\frac{r}{R}\right)^n \oint d\Omega' P_n(\hat{r} \cdot \hat{r}') (1 + (2-n)m\epsilon' + \right. \\ &\quad \left. + \frac{1}{2}(2-n)(1-n)m^2 \epsilon'^2 + (2-n)m^2 u') \right] = \\ &= -\underbrace{\frac{4\pi G R^2 \rho^-}{3}}_{GM/R} \left[\frac{3}{2} - \frac{1}{2} \left(\frac{r}{R}\right)^2 + 3m \sum_{n=0}^{\infty} \frac{\epsilon_n P_n}{2n+1} \left(\frac{r}{R}\right)^2 + 3m^2 \sum_{n=0}^{\infty} \frac{u_n P_n}{2n+1} \left(\frac{r}{R}\right)^2 \right. \\ &\quad \left. + \frac{3m^2}{8\pi} \sum_{n=0}^{\infty} (1-n) \left(\frac{r}{R}\right)^n \oint d\Omega' \epsilon'^2 P_n(\hat{r} \cdot \hat{r}') \right] \end{aligned}$$

4 LINEAR ELASTICITY

• Deformation

* Displacement vector field $\vec{u}$ describes deformation $\vec{r}' = \vec{r} + \vec{u}(\vec{r})$



* Topography :

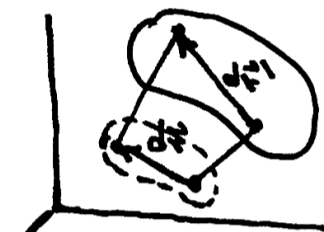


$$\begin{aligned} T(\vec{r}') &= |R\hat{r} + \vec{u}(\vec{r})|_R = \\ &= \sqrt{(R\hat{r} + \vec{u}) \cdot (R\hat{r} + \vec{u})} \Big|_R = \\ &= R \sqrt{1 + \frac{2\hat{r} \cdot \vec{u}}{R}} \Big|_R \approx R + \hat{r} \cdot \vec{u} \Big|_R \end{aligned}$$

and since $\vec{r}' = \vec{r} + O(u)$
and $\vec{u}(\vec{r}) = \vec{u}(\vec{r}') + O(u^2)$

$$T(\vec{r}) = R + \hat{r} \cdot \vec{u} \Big|_R$$

* Strain tensor $\vec{\epsilon}$:



defined by $|d\vec{r}'|^2 - |d\vec{r}|^2 = d\vec{r} \cdot 2\vec{\epsilon} \cdot d\vec{r}$

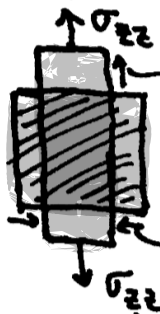
and since $d\vec{r}' = d\vec{r} + d\vec{r} \cdot \nabla \vec{u}$ (Taylor)

$$\begin{aligned} \Rightarrow |d\vec{r}'|^2 &= d\vec{r}' \cdot d\vec{r}' = (d\vec{r} + d\vec{r} \cdot \nabla \vec{u}) \cdot (d\vec{r} + \nabla \vec{u} \cdot d\vec{r}) \\ &= d\vec{r} \cdot d\vec{r} + d\vec{r} \cdot (\nabla \vec{u} + \nabla \vec{u}^T) \cdot d\vec{r} \end{aligned}$$

$$\therefore \vec{\epsilon} = \frac{1}{2} (\nabla \vec{u} + \nabla \vec{u}^T)$$

• Hook's law

* Constitutional equation



$$\epsilon_{zz} = \frac{\sigma_{zz}}{E} \rightarrow \text{Young's modulus} \quad \text{Material constants}$$

$$\epsilon_{xx} = \epsilon_{yy} = -\nu \epsilon_{zz}$$

Via superposition :

$$\epsilon_{xx} = \frac{1}{E} (\sigma_{xx} - \nu \sigma_{yy} - \nu \sigma_{zz})$$

$$\epsilon_{yy} = \frac{1}{E} (\sigma_{yy} - \nu \sigma_{xx} - \nu \sigma_{zz})$$

$$\epsilon_{zz} = \frac{1}{E} (\sigma_{zz} - \nu \sigma_{xx} - \nu \sigma_{yy})$$

$$\begin{aligned} \vec{\epsilon} &= \frac{1+\nu}{E} \vec{\sigma} - \frac{\nu}{E} \text{Tr} \vec{\sigma} \vec{I} \\ \vec{\sigma} &= 2\mu \vec{\epsilon} + \lambda \text{Tr} \vec{\epsilon} \vec{I} \end{aligned}$$

$\mu = \frac{E}{2(1+\nu)} ; \lambda = \frac{\nu E}{(1+\nu)(1-2\nu)}$ Lamé's params.

- Potential decomposition of $\vec{u}$:

$$\vec{u} = \underbrace{\nabla \phi}_{\text{shift potential}} + \underbrace{\nabla \times \vec{\psi}}_{\text{stream potential}}$$

* Since $\text{Tr } \vec{E} = \text{Tr } \frac{1}{2} (\nabla \vec{u} + \nabla \vec{u}^T) = \nabla \cdot \vec{u} = \Delta \phi$

$$\therefore \vec{E} = \frac{1}{2} (\nabla \vec{u} + \nabla \vec{u}^T) = \nabla^2 \phi + \frac{1}{2} (\nabla \nabla \times \vec{\psi} + \nabla \nabla \times \vec{\psi}^T)$$

* $\vec{\sigma} = 2\mu \vec{E} + \lambda I \text{Tr } \vec{E} = \mu (\nabla \vec{u} + \nabla \vec{u}^T) + \lambda I \nabla \cdot \vec{u} =$
 $= 2\mu \nabla^2 \phi + \lambda I \Delta \phi + \mu (\nabla \nabla \times \vec{\psi} + \nabla \nabla \times \vec{\psi}^T)$

* $\nabla \cdot \vec{\sigma} = \mu \Delta \vec{u} + (\mu + \lambda) \nabla \nabla \cdot \vec{u} = (2\mu + \lambda) \nabla \Delta \phi + \mu \nabla \times \Delta \vec{\psi}$

- Free loading & Chree's axisymmetric solution

$$\vec{f} + \nabla \cdot \vec{\sigma} = 0 \quad \vec{f} = 0 \quad \Rightarrow \quad \nabla \cdot \vec{\sigma} = 0 \quad (\text{free loading})$$



i.e. $\nabla \cdot \vec{\sigma} = (2\mu + \lambda) \nabla \Delta \phi + \mu \nabla \times \Delta \vec{\psi} = 0$

$$\begin{cases} \phi = \sum_{n=0}^{\infty} \alpha_n r^n P_n + (n+1)/\beta_n \mu r^{n+2} P_n \\ \vec{\psi} = \sum_{n=0}^{\infty} (2\mu + \lambda)/\beta_n r^{n+2} \vec{R}_n \end{cases}$$

- * Justification :

$$\nabla \cdot \vec{\sigma} = (2\mu + \lambda) \nabla \Delta \phi + \mu \nabla \times \Delta \vec{\psi} =$$

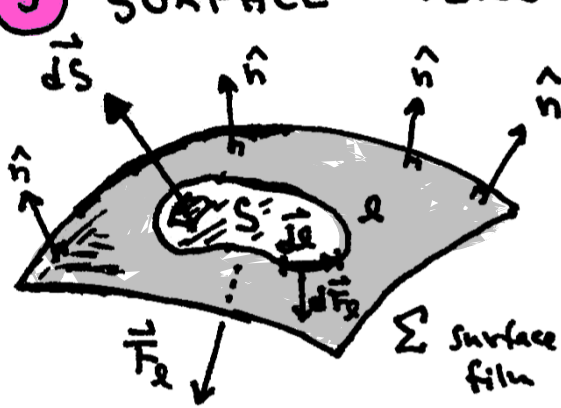
$$= 2\mu (2\mu + \lambda) \sum_{n=0}^{\infty} \beta_n r^n (3+2n) \underbrace{[(n+1) \nabla (r^n P_n) + \nabla \times (r^n \vec{R}_n)]}_0 = 0$$

where we have used

$$\Delta (r^n P_n) = 0$$

$$\Delta (r^n \vec{R}_n) = \vec{0}$$

5 SURFACE TENSION



unit normal vector field $\perp \Sigma$

model: $dF = \gamma dl$; $d\vec{l} \perp d\vec{F} \subset \Sigma$

vectorially: $d\vec{F} = \gamma d\vec{l} \times \hat{n}$

Surface tension coefficient (material!)

• Total force derivation

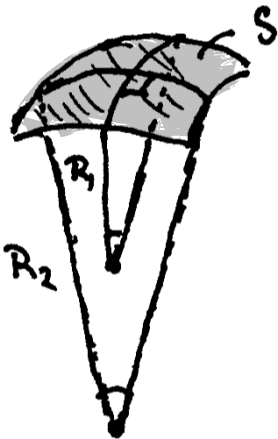
* Recall Stokes then $\iint_S (\hat{n} \times \nabla) T dS = \oint_{\partial S} d\vec{l} T$

for any tensor T , taking $\times$: $\iint_S \underbrace{(\hat{n} \times \nabla) \times T} dS = \oint d\vec{l} \times T$
 $\nabla(\hat{n} \cdot T) - \hat{n} \nabla \cdot T$

* Put $T = \hat{n}$, then $\nabla(\hat{n} \cdot T) = \nabla(\hat{n} \cdot \hat{n}) = \nabla 1 = \vec{0}$, so

$$\vec{F}_Q = \oint_{\partial S} d\vec{F} = \gamma \oint_{\partial S} d\vec{l} \times \hat{n} = -\gamma \iint_S \hat{n} \nabla \cdot \hat{n} dS \approx -\gamma \hat{n} (\nabla \cdot \hat{n}) S$$

* Note that (Landau - Lifshitz): $\nabla \cdot \hat{n} = \frac{1}{R_1} + \frac{1}{R_2}$

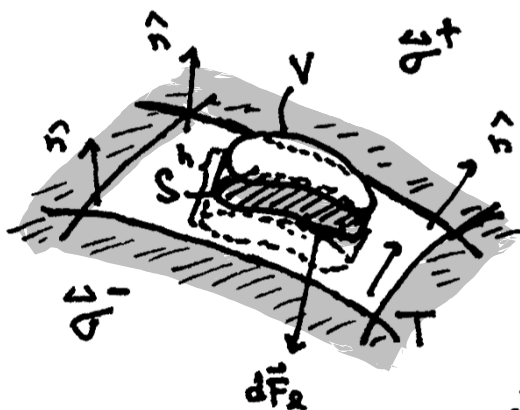


$$\therefore \vec{F}_Q = -\gamma \hat{n} \left(\frac{1}{R_1} + \frac{1}{R_2} \right) S$$

mean curvature
(invariant !!)

[Young-Laplace equation]

6 SURFACE BALANCE



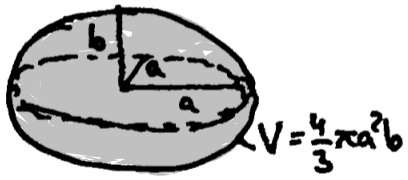
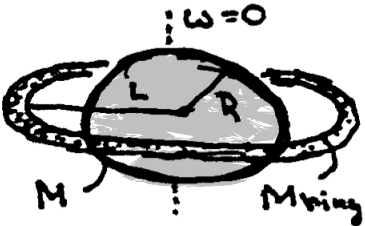
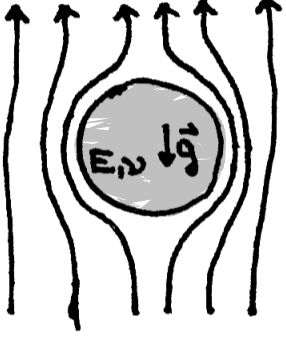
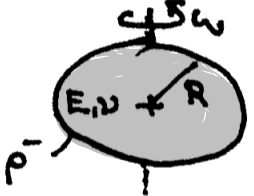
$$\vec{0} = \vec{F} - m\vec{a} = \iiint_V \vec{f} dV + \oint_S \hat{n} \cdot \vec{\sigma} dS + \oint_{\partial S} d\vec{F}_2 - \rho V \vec{a} = \langle h \rightarrow 0 \rangle$$

$$\approx \hat{n} \cdot \vec{\sigma}^+ S - \hat{n} \cdot \vec{\sigma}^- S - \gamma \hat{n} \nabla \cdot \hat{n} S|_T$$

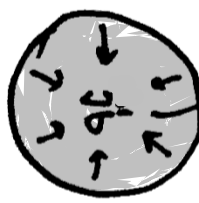
$$\therefore \hat{n} \cdot (\vec{\sigma}^+ - \vec{\sigma}^-) - \gamma \hat{n} \nabla \cdot \hat{n} |_T = \vec{0}$$

WORKED EXAMPLES

TABLE OF HANDY RESULT

Oblate spheroid	Excentricity	Stretch factor
	$e^2 = 1 - \frac{b^2}{a^2}$	$\delta = \frac{V}{V_0} - 1$
	0	$-\frac{3GM\rho^-(1-2\nu)}{2E}$
	$\frac{15M_{ring}}{4M} \left(\frac{R}{L}\right)^3$	0
	$\frac{5\omega^2 R^3}{2GM}$	0
	$\frac{3M\omega^2}{16\pi\delta}$	0
	0	0
	$\frac{2R^2\rho^-\omega^2(1+\nu)(2+\nu)}{E(7+5\nu)}$	$\frac{2R^2\rho^-\omega^2(1-2\nu)}{5E}$

1 STATIC SELF-GRAVITATING ELASTIC PLANET



$\vec{\sigma}^+ = 0; \quad \vec{f}^+ = 0$
 $\vec{\sigma}^- = 2\mu \vec{E} + \lambda \text{Tr} \vec{E} \vec{E} \quad \begin{matrix} \vec{u} = \nabla \phi \\ \vec{E} = \nabla^2 \phi \end{matrix} \quad 2\mu \nabla^2 \phi + \lambda \Delta \phi$
 $\vec{f}^- = -\rho^- \nabla \bar{V}_G; \text{ where } \bar{V}_G = -\frac{GM}{R} \left[\frac{3}{2} - \frac{1}{2} \left(\frac{r}{R} \right)^2 \right]$

• Internal balance

$$\vec{f}^- + \nabla \cdot \vec{\sigma}^- = \vec{0}, \text{ but } \nabla \cdot \vec{\sigma}^- = (2\mu + \lambda) \nabla \Delta \phi$$

$$\therefore \text{sol } (2\mu + \lambda) \Delta \phi - \rho^- \bar{V}_G = \text{const.}$$

* Ansatz $\phi = Ar^4 + Br^2$

a) $\nabla \phi = 4Ar^3 \hat{r} + 2Br \hat{r} \rightarrow \hat{r} \cdot \nabla \phi = 4Ar^3 + 2Br$

b) $\Delta \phi = 20Ar^2 + 6B$

$$\therefore \text{Comparing } r^2: (2\mu + \lambda) 20A - \rho^- \frac{GM}{2R^3} = 0 \Rightarrow A = \frac{GM\rho^-}{40R^3(2\mu + \lambda)}$$

• Surface balance

$$\hat{n} \cdot (\vec{\sigma}^+ - \vec{\sigma}^-)|_T = 0 \rightarrow \hat{r} \cdot \vec{\sigma}^-|_R = 0$$

$$\text{i.e. } \hat{r} \cdot \vec{\sigma}^-|_R = 2\mu \hat{r} \cdot \nabla^2 \phi + \lambda \hat{r} \cdot \text{I} \Delta \phi =$$

$$= [2\mu (12AR^2 + 2B) + \lambda (20AR^2 + 6B)] \hat{r} =$$

$$= 2 [2AR^2 (6\mu + 5\lambda) + B(2\mu + 3\lambda)] \hat{r} \equiv 0$$

$$\therefore B = -2AR^2 \frac{6\mu + 5\lambda}{2\mu + 3\lambda}$$

• In total:

$$\phi = \frac{GM\rho^-}{40(2\mu + \lambda)} \left[\left(\frac{r}{R} \right)^4 - 2 \frac{6\mu + 5\lambda}{2\mu + 3\lambda} \left(\frac{r}{R} \right)^2 \right]$$

$$\vec{u} = \nabla \phi = \frac{GM\rho^-}{40(2\mu + \lambda)} \left[\left(\frac{r}{R} \right)^3 - \frac{6\mu + 5\lambda}{2\mu + 3\lambda} \frac{r}{R} \right]$$

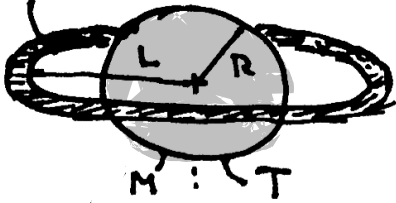
$$\therefore \vec{u}|_R = -\frac{GM\rho^- \hat{r}}{5(2\mu + 3\lambda)} = -\frac{GM\rho^- (1-2\nu)}{5E} \hat{r}$$

$$\text{so } \delta = \frac{V}{V_0} - 1 = \left(\frac{R_E}{R} \right)^3 - 1 = -\frac{3MG\rho^- (1-2\nu)}{2E}$$

2

PLANET TOPOGRAPHY INFLUENCED BY A RING

M_{ring} ; $\omega = 0$ $\vec{\sigma}^+ = 0$ (euph), $\vec{\sigma}^- = -p\vec{I}$ (perfect fluid)



$$m := \frac{M_{ring}}{M} \left(\frac{R}{L}\right)^3$$

$$\vec{f}^+ = 0, \vec{f}^- = -\rho^- \nabla \bar{V}, \text{ where } \bar{V} = \bar{V}_G + \bar{V}_{ring} ; \kappa := \frac{M_{ring}}{2\pi L}$$

self gravity ring-induced grav. potential

$$a) \bar{V}_G = -\frac{GM}{R} \left[\frac{3}{2} - \frac{1}{2} \left(\frac{r}{R}\right)^2 + 3m \sum \frac{t_n P_n}{2n+1} \left(\frac{r}{R}\right)^n \right]$$

$$b) \bar{V}_{ring} = -G \oint_{\mathcal{C}} \frac{\kappa d\ell'}{|\vec{r} - L\hat{\rho}'|} \stackrel{L \gg R}{=} -G\kappa \int_0^{2\pi} \left[1 + \frac{r}{L} P_1(\hat{r} \cdot \hat{\rho}') + \frac{r^2}{L^2} P_2(\hat{r} \cdot \hat{\rho}') + \dots \right] d\ell'$$

$$\varphi_{OG} = -2\pi G\kappa \left[1 + \frac{r}{L} P_1(\hat{r} \cdot \hat{e}) + \frac{r^2}{L^2} P_2(\hat{r} \cdot \hat{e}) + \dots \right]$$

$$= \pi G\kappa \frac{r^2}{L^2} P_2(\hat{r} \cdot \hat{e}) = \frac{GM}{R} \frac{m}{2} P_2 \text{ (up to a constant)}$$

$$\therefore \bar{V} = -\frac{GM}{R} \left[\frac{3}{2} - \frac{1}{2} \left(\frac{r}{R}\right)^2 - \frac{m}{2} \left(\frac{r}{R}\right)^2 P_2 + 3m \sum \frac{t_n P_n}{2n+1} \left(\frac{r}{R}\right)^n \right]$$

Internal Balance

$$\vec{f}^- + \nabla \cdot \vec{\sigma}^- = 0 ; \text{ but } \nabla \cdot \vec{\sigma}^- = -\nabla p^- \text{ and } \vec{f}^- = -\rho^- \nabla \bar{V}$$

$$\hookrightarrow -\rho^- \nabla \bar{V} - \nabla p^- = 0 \therefore \text{solution } \rho^- \bar{V} + p^- = \bar{p}_0$$

Surface Balance

$$\hat{n} \cdot (\vec{\sigma}^+ - \vec{\sigma}^-)|_T = 0 \Rightarrow 0 + p^- \hat{n}|_T = 0 \Rightarrow p^-|_T = 0,$$

$$\therefore \text{e. const.} = \frac{\bar{p}_0}{\rho^-} = \bar{V}|_T = -\frac{GM}{R} \left[\frac{3}{2} - \frac{1}{2} (1+m) - \frac{m}{2} P_2 + 3m \sum_{n=0}^{\infty} \frac{t_n P_n}{2n+1} \right]$$

$$= -\frac{GM}{R} \left[1 - m + \frac{m}{2} P_2 + 3m \sum_{n=0}^{\infty} \frac{t_n P_n}{2n+1} \right]$$

* By comparison of P_n : a) $t_0 = 0$ (fixed volume) $\Rightarrow \frac{\bar{p}_0}{\rho^-} = -\frac{GM}{R}$

b) $t_1 \equiv 0$ (shif degenerag); c) $t_2 = -\frac{5}{4}$; d) $t_n = 0$; $n \geq 3$

• In total: $T = R(1 - \frac{5}{4} m P_2) \Rightarrow e^2 = -3m t_2 = \frac{15}{4} m = \frac{15 M_{ring}}{4 M} \left(\frac{R}{L}\right)^3$

$$* \bar{V} = -\frac{GM}{R} \left[\frac{3}{2} - \frac{1}{2} \left(\frac{r}{R}\right)^2 - \frac{5}{4} m P_2 \left(\frac{r}{R}\right)^2 \right] \therefore p = \rho^- \frac{GM}{R} \left[\frac{1}{2} - \frac{1}{2} \left(\frac{r}{R}\right)^2 - \frac{5}{4} m P_2 \left(\frac{r}{R}\right)^2 \right]$$

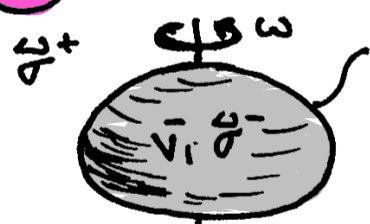
$$* \vec{\sigma}^- = -\nabla \bar{V} = \frac{GM}{R} \left[-\frac{r}{R^2} \hat{r} - \frac{5}{4} m (\nabla P_2) \left(\frac{r}{R}\right)^2 - \frac{5}{4} m P_2 \frac{r}{R^2} \hat{r} \right] = \frac{GM}{R^2} \left[-\hat{r} - \frac{5}{4} m \vec{\Theta}_2 - \frac{5}{4} m \vec{P}_2 \right] \frac{r}{R}$$

$$\hookrightarrow \vec{\sigma}^-|_T = \frac{GM}{R^2} [\dots] (1 - \frac{5}{4} m P_2) = \frac{GM}{R^2} \left[\hat{r} - \frac{5}{4} m \vec{\Theta}_2 \right]$$

planet	$\frac{2}{L}$	$\frac{r}{L}$	$\frac{\Theta}{L}$	$\frac{\Psi}{L}$
e	10^{-7}	10^{-4}	10^{-5}	10^{-5}

PLANET UNDER SELF-GRAVITY

3 ROTATING



$$m := \frac{\omega^2 R^3}{GM}$$

$$T = R(1 + m\epsilon + m^2 u) ; \quad \sigma^+ = 0 \text{ (empty space);}$$

$$\sigma^- = -\bar{p} I \text{ (perfect fluid), } \bar{\rho} = \text{const. (incompress.);}$$

$$\bar{V} = \bar{V}_G + \bar{V}_{\text{rot}} \text{ (in a co-rotating frame)}$$

$$a) \quad \bar{a}_{\text{rot}} = \frac{v^2}{\rho} \hat{\rho} = \omega^2 \rho \hat{\rho} = \nabla \frac{1}{2} \omega^2 \rho^2 = -\nabla V_{\text{rot}}$$

$$\therefore \bar{V}_{\text{rot}} = -\frac{1}{2} \omega^2 \rho^2 = -\frac{R^2 \omega^2}{2} \left(\frac{r}{R}\right)^2 \hat{\theta} = -\frac{GM}{R} \frac{m}{3} \left(\frac{r}{R}\right)^2 (P_0 - P_2)$$

$$b) \quad \therefore \bar{V} = -\frac{GM}{R} \left[\frac{3}{2} - \frac{1}{2} \left(\frac{r}{R}\right)^2 + \frac{m}{3} \left(\frac{r}{R}\right)^2 (P_0 - P_2) + 3m \sum_{n=0}^{\infty} \frac{t_n P_n}{2n+1} \left(\frac{r}{R}\right)^2 + \right.$$

$$\left. + 3m^2 \sum_{n=0}^{\infty} \frac{u_n P_n}{2n+1} \left(\frac{r}{R}\right)^2 + \frac{3m^2}{8\pi} \sum_{n=0}^{\infty} (1-n) \left(\frac{r}{R}\right)^n \int \hat{\rho}^2 P_n(\hat{r} \cdot \hat{r}) d\hat{r} \right]$$

Internal Balance

$$\bar{f}^- + \nabla \cdot \bar{\sigma}^- = 0 \Rightarrow -\bar{\rho} \nabla \bar{V} - \nabla \bar{p} = 0 \therefore \text{sol } \bar{\rho} \bar{V} + \bar{p} = \bar{p}_0 \text{ (const.)}$$

Surface Balance

$$\hat{n} \cdot (\bar{\sigma}^+ - \bar{\sigma}^-)|_T = 0 \Rightarrow \bar{p}|_T = 0 \therefore \frac{\bar{p}_0}{\bar{\rho}^-} = \bar{V}|_T$$

* First order :

$$\frac{\bar{p}_0}{\bar{\rho}^-} = \bar{V}|_T \stackrel{O(m^1)}{=} -\frac{GM}{R} \left[1 - m\epsilon + \frac{m}{3} (P_0 - P_2) + 3m \sum_{n=0}^{\infty} \frac{t_n P_n}{2n+1} \right]$$

$$a) t_0 = 0 \text{ (vol. fix.) ; } b) t_1 \equiv 0 \text{ (shift degeneracy)}$$

$$c) t_2 = -\frac{5}{6} ; d) t_n = 0 ; n \geq 3 \therefore t = -\frac{5}{6} P_2$$

* Second order :

$$\text{Recall } P_2^2 = \frac{1}{3} P_0 + \frac{2}{7} P_2 + \frac{12}{35} P_4, \text{ hence}$$

$$\bar{V} = -\frac{GM}{R} \left[\frac{3}{2} - \frac{1}{2} \left(\frac{r}{R}\right)^2 + \frac{m}{3} \left(\frac{r}{R}\right)^2 (P_0 - P_2) - \frac{m}{2} \left(\frac{r}{R}\right)^2 P_2 + \right.$$

$$\left. + 3m^2 \sum_{n=0}^{\infty} \frac{u_n P_n}{2n+1} \left(\frac{r}{R}\right)^n + \frac{3m^2}{2} t_2^2 \left(\frac{1}{5} P_0 - \frac{2}{7} \frac{1}{5} \left(\frac{r}{R}\right)^2 P_2 - 3 \cdot \frac{12}{35} \frac{1}{9} \left(\frac{r}{R}\right)^2 P_4 \right) \right]$$

$$= -\frac{GM}{R} \left[\frac{3}{2} - \frac{1}{2} \left(\frac{r}{R}\right)^2 + \frac{m}{3} \left(\frac{r}{R}\right)^2 - \frac{5m}{6} \left(\frac{r}{R}\right)^2 P_2 + \frac{5m^2}{24} - \frac{5}{84} m^2 \left(\frac{r}{R}\right)^2 P_2 - \right.$$

$$\left. - \frac{5}{28} m^2 \left(\frac{r}{R}\right)^4 P_4 + 3m^2 \sum_{n=0}^{\infty} \frac{u_n P_n}{2n+1} \left(\frac{r}{R}\right)^n \right]$$

$$\therefore \frac{\bar{p}_0}{\bar{\rho}^-} = \bar{V}|_T \stackrel{O(m^2)}{=} -\frac{GM}{R} \left[\frac{3}{2} - \frac{1}{2} (1 + m\epsilon + m^2 u)^2 + \frac{m}{3} (1 + m\epsilon)^2 - \frac{5m}{6} (1 + m\epsilon)^2 P_2 + \right.$$

$$\left. + \frac{5m^2}{24} - \frac{5}{84} m^2 P_2 - \frac{5}{28} m^2 P_4 + 3m^2 \sum_{n=0}^{\infty} \frac{u_n P_n}{2n+1} \left(\frac{r}{R}\right)^n \right] =$$

$$= -\frac{GM}{R} \left[1 + \frac{m}{3} + m^2 \left(-u - \frac{t^2}{2} + \frac{2}{3}t - \frac{5}{3}tP_2 + \frac{5}{24} - \frac{5}{84}P_2 - \frac{5}{28}P_4 + 3 \sum_{n=0}^{\infty} \frac{u_n P_n}{2n+1} \right) \right] =$$

$$= -\frac{GM}{R} \left[1 + \frac{m}{3} + m^2 \left(-u + \frac{5}{24} - \frac{155}{252}P_2 - \frac{5}{28}P_4 + \frac{25}{24}P_2^2 + 3 \sum_{n=0}^{\infty} \frac{u_n P_n}{2n+1} \right) \right] =$$

$$= -\frac{GM}{R} \left[1 + \frac{m}{3} + m^2 \left(\frac{5}{12} - \frac{20}{63}P_2 + \frac{5}{14}P_4 - u + 3 \sum_{n=0}^{\infty} \frac{u_n P_n}{2n+1} \right) \right]$$

* By comparison of coefficients

a) (vol. fix.): $u_0 = -\frac{1}{5}t^2 = -\frac{5}{36} \therefore \frac{p_0^-}{\rho^-} = -\frac{GM}{R} \left[1 + \frac{m}{3} + \frac{5m^2}{36} \right]$

b) $u_1 = 0$ (shift degeneracy)

c) $u_2 = -\frac{50}{63}$; d) $u_3 = 0$; e) $u_4 = \frac{15}{28}$; f) $u_n = 0; n \geq 5$

$$\therefore u = -\frac{5}{36} - \frac{50}{63}P_2 + \frac{15}{28}P_4$$

• In total:

$$T = R \left[1 - \frac{5}{6}mP_2 + m^2 \left(-\frac{5}{36} - \frac{50}{63}P_2 + \frac{15}{28}P_4 \right) \right]$$

* Ellipsoid matching conditions:

a) $\frac{6}{5}t_1t_2 = \frac{6}{5} \cdot 0 \cdot \left(-\frac{5}{6}\right) = 0 \equiv u_3 \checkmark$

b) $\frac{27}{35}t_2^2 = \frac{27}{35} \left(-\frac{5}{6}\right)^2 = \frac{15}{28} \equiv u_4 \checkmark$

$$\therefore e^2 = -3t_2m \left[1 + \left(\frac{u_2}{t_2} + \frac{11}{7}t_2 \right)m \right] = \frac{5}{2}m \left(1 - \frac{5}{14}m \right)$$

$$\Rightarrow \text{OR } m = \frac{2}{5}e^2 \left(1 + \frac{e^2}{7} \right)$$

[NOTE: exact $m = \frac{1}{2e^3} [9e(e^2-1) - 3\sqrt{1-e^2}(2e^2-3)\arcsin e]$]

• Internal variables

$$* \bar{V} = -\frac{GM}{R} \left[\frac{3}{2} - \frac{1}{2} \left(\frac{r}{R} \right)^2 + \frac{m}{3} \left(\frac{r}{R} \right)^2 - \frac{5m}{6} \left(\frac{r}{R} \right)^2 P_2 - \frac{5}{24}m^2 - \frac{15}{28}m^2 \left(\frac{r}{R} \right)^2 P_2 \right]$$

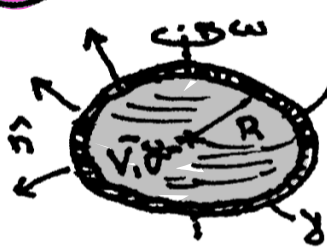
$$* \bar{p}^- = -\rho^- \frac{GM}{R} \left[\frac{1}{2} - \frac{1}{2} \left(\frac{r}{R} \right)^2 - \frac{m}{3} + \frac{m}{3} \left(\frac{r}{R} \right)^2 - \frac{5m}{6} \left(\frac{r}{R} \right)^2 P_2 - \frac{25}{72}m^2 - \frac{15}{28}m^2 \left(\frac{r}{R} \right)^2 P_2 \right]$$

$$* \vec{a}^- = -\nabla \bar{V} = \frac{GM}{R^2} \frac{r}{R} \left[-\vec{r} + \frac{2}{3}m\vec{r} - \frac{5m}{3}\vec{P}_2 - \frac{5m}{6}\vec{Q}_2 - \frac{15}{14}m^2\vec{P}_2 - \frac{15}{28}m^2\vec{Q}_2 \right]$$

$$* \vec{a}|_T = \frac{GM}{R^2} \left[-\vec{r} + \frac{2}{3}m\vec{r} - \frac{5}{6}m(\vec{P}_2 + \vec{Q}_2) + \frac{5}{12}m^2\vec{r} - \frac{55}{126}m^2(\vec{P}_2 + \vec{Q}_2) + \frac{5}{28}m^2(\vec{P}_4 + \vec{Q}_4) \right]$$

	♂	♀	♂	♀	♂	♀	♂	♀	♂	♀
predicted eccentricities	0.0068	0.0011	0.0004	0.0093	0.0044	0.11	0.45	0.57	0.27	0.25

4 ROTATING DROPLET UNDER SURFACE TENSION



$$T = R(1 + m\epsilon + m^2 u); \quad \vec{\sigma}^- = -\bar{p} \mathbf{I} \text{ (perf. fluid)}$$

$$V = \frac{4}{3}\pi R^3$$

$$\vec{\sigma}^+ = 0 \text{ (empty space)}$$

$$M = V\bar{\rho}; \quad \bar{\rho} = \text{const.}$$

$$m := \frac{\bar{\rho} R^3 \omega^2}{12\gamma}$$

$$\begin{aligned} \bar{V} &= \bar{V}_{\text{rot}} = -\frac{1}{2} \omega^2 \rho^2 = -\frac{6\gamma m}{\bar{\rho} R} \left(\frac{r}{R}\right)^2 \sin^2 \theta = \\ &= -\frac{4\gamma}{\bar{\rho} R} m \left(\frac{r}{R}\right)^2 (P_0 - P_2) \text{ (co-rotating r.f.)} \end{aligned}$$

$$\hat{n} = \hat{r} - mR \nabla \epsilon - \frac{m^2}{2} R^2 \hat{r} |\nabla \epsilon|^2 - m^2 R \nabla u$$

• Internal balance

$$\vec{f} + \nabla \cdot \vec{\sigma}^- = 0, \text{ i.e. } \bar{\rho} \nabla \bar{V} - \nabla \bar{p} = 0 \therefore \text{sol } \bar{\rho} \bar{V} + \bar{p} = \bar{p}_0 \text{ (const.)}$$

• Surface balance

$$\hat{n} \cdot (\vec{\sigma}^+ - \vec{\sigma}^-) - \gamma \hat{n} \cdot \nabla \hat{n} |_T = 0 \Rightarrow \hat{n} \bar{p} - \gamma \hat{n} \cdot \nabla \hat{n} |_T = 0,$$

$$\text{so } \bar{p} - \gamma \nabla \cdot \hat{n} |_T = 0 \therefore \text{sol const.} = \bar{p}_0 = \gamma \nabla \cdot \hat{n} + \bar{\rho} \bar{V} |_T$$

* First order :

$$a) \hat{n} = \hat{r} - mR \nabla \epsilon + O(m^2)$$

$$\nabla \cdot \hat{n} = \nabla \cdot \hat{r} - mR \Delta \epsilon = \frac{2}{r} - mR \sum_{n=0}^{\infty} t_n \Delta P_n = \frac{2}{r} + \frac{mR}{r^2} \sum_{n=0}^{\infty} t_n n(n+1) P_n$$

$$\nabla \cdot \hat{n} |_T = \frac{2}{R(1+m\epsilon)} + \frac{m}{R} \sum_{n=0}^{\infty} n(n+1) t_n P_n = \frac{2}{R} - \frac{2m}{R} \epsilon + \frac{m}{R} \sum_{n=0}^{\infty} n(n+1) t_n P_n$$

$$b) \bar{\rho} \bar{V} |_T = -\frac{4\gamma}{R} m (P_0 - P_2)$$

$$c) \therefore \bar{p}_0 = \gamma \nabla \cdot \hat{n} + \bar{\rho} \bar{V} |_T = \frac{\gamma}{R} \left[2 - 2m\epsilon - 4m(P_0 - P_2) + m \sum_{n=0}^{\infty} n(n+1) t_n P_n \right]$$

$$\text{Comparing : } t_0 = 0 \text{ (vol. fix.)}; t_1 = 0 \text{ (shift fix.)}; t_2 = -1$$

$$\text{so } \epsilon = -P_2 \Rightarrow T = R(1 - mP_2) \therefore e^2 = -3t_2 m = \frac{\bar{\rho} R^3 \omega^2}{4\gamma} = \frac{3M\omega^2}{16\pi\gamma}$$

* Second order :

$$a) |\nabla \epsilon|^2 = \frac{1}{r} \vec{Q}_2 \cdot \vec{Q}_2 = \frac{1}{r^2} \left(\frac{6}{5} P_0 + \frac{6}{7} P_2 - \frac{72}{35} P_4 \right)$$

$$\therefore \hat{n} = \hat{r} - mR \nabla \epsilon - m^2 \left(\frac{R}{r}\right)^2 \hat{r} \left(\frac{3}{5} P_0 + \frac{3}{7} P_2 - \frac{36}{35} P_4 \right) - m^2 R \nabla u$$

$$\text{Since } \nabla \cdot \frac{\hat{r}}{r^2} = \frac{2}{r} \frac{1}{r^2} - \frac{2}{r^2} \hat{r} \cdot \hat{r} = 0 \quad (r \neq 0)$$

$$\therefore \nabla \cdot \hat{n} = \frac{2}{r} - mR \Delta \epsilon - m^2 R \Delta u = \frac{2}{r} - \frac{6mR}{r^2} P_2 + \frac{m^2 R}{r^2} \sum_{n=0}^{\infty} n(n+1) t_n P_n$$

$$\begin{aligned}\therefore \nabla \cdot \hat{n}|_T &= \frac{2}{R}(1+mt+m^2u)^{-1} - \frac{6}{R}m(1+mb)^{-2}P_2 + \frac{m^2}{R} \sum_{n=0}^{\infty} n(n+1)u_n P_n = \\ &= \frac{1}{R} [2 - 2mt - 2m^2u + 2m^2t^2 - 6mP_2 + 12m^2tP_2 + m^2 \sum \dots] \\ &= \frac{1}{R} [2 - 4mP_2 - 2m^2u - 10m^2P_2^2 + m^2 \sum_{n=0}^{\infty} n(n+1)u_n P_n]\end{aligned}$$

$$b) \bar{V}|_T = -\frac{4\gamma m}{\rho - R}(1+mt)^2(P_0 - P_2) = -\frac{4\gamma}{\rho - R} [m - mP_2 + 2m^2t - 2m^2tP_2]$$

$$\begin{aligned}c) \therefore \bar{p}_0 &= \gamma \nabla \cdot \hat{n} + \rho \bar{V}|_T = \frac{\gamma}{R} [2 - 4m + 8m^2P_2 - 18m^2P_2^2 - 2m^2u + m^2 \sum \dots] \\ &= \frac{\gamma}{R} [2 - 4m - \frac{18}{5}m^2 + \frac{20}{7}m^2P_2 - \frac{324}{35}m^2P_4 - 2m^2u + m^2 \sum_{n=0}^{\infty} n(n+1)u_n P_n]\end{aligned}$$

Comparing:

$$u_0 = -\frac{1}{8}t^2 = -\frac{1}{5} \quad (\because \text{vol. fix.}) \Rightarrow \bar{p}_0 = \frac{\gamma}{R} [2 - 4m - \frac{16}{5}m^2]$$

$$u_1 \equiv 0 \quad (\text{shift degeneracy})$$

$$u_2 = -5/7; \quad u_3 = 0; \quad u_4 = \frac{18}{35}; \quad u_n = 0 \quad n \geq 5$$

$$\text{so } u = -\frac{1}{5} - \frac{5}{7}P_2 + \frac{18}{35}P_4$$

• In total

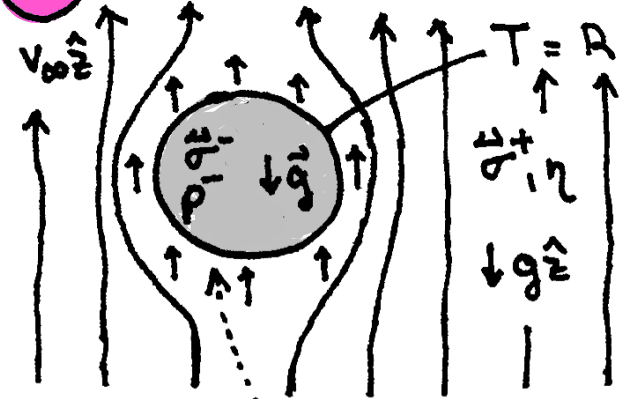
$$\text{* Topography } T = R [1 - mP_2 + m^2(-\frac{1}{5}P_0 - \frac{5}{7}P_2 + \frac{18}{35}P_4)]$$

$$\text{* Pressure } \bar{p} = \frac{\gamma}{R} [2 - 4m - \frac{16}{5}m^2 + 4m(\frac{\gamma}{R})^2(P_0 - P_2)]$$

* Oblate spheroid matching condition?

$$\left. \begin{aligned}a) \frac{6}{5}t_1t_2 &= \frac{6}{5} \cdot 0 \cdot (-1) = 0 \equiv u_3 \quad \checkmark \\ b) \frac{27}{35}t_2^2 &= \frac{27}{35} \neq \frac{18}{35} \equiv u_4 \quad \times\end{aligned} \right\} \begin{array}{l} \text{NOT an} \\ \text{oblate} \\ \text{spheroid!} \end{array}$$

5 FALLING ELASTIC BALL



$$T = R + \hat{r} \cdot \vec{\sigma} |_R ; \quad \vec{\sigma} = 2\mu \vec{E} + \lambda \text{Tr} \vec{E} \hat{I}$$

$$\hat{r} \cdot \vec{\sigma} |_R = \frac{3v_{\infty} \eta}{2R} \hat{z} \quad (\text{Stokes flow})$$

$$(\vec{F} = \oint \hat{n} \cdot \vec{\sigma} dS = 6\pi R v_{\infty} \eta \hat{z})$$

~ co-falling frame

undeformed state: $g=0$; Global balance: $Mg = 6\pi R v_{\infty} \eta \therefore \hat{r} \cdot \vec{\sigma} |_R = \frac{1}{3} R \rho g \hat{z}$
 $T_0 = R$; $V_0 = \frac{4}{3} \pi R^3$

Internal Balance:

$$\vec{f} + \nabla \cdot \vec{\sigma} = \vec{0} ; \quad \vec{f} = -\rho g \hat{z} = -\nabla(\rho g z)$$

* Displacement vector decomposition: $\vec{u} = \nabla \phi + \nabla \times \vec{\psi}$

a) $\vec{\sigma} = 2\mu \nabla^2 \phi + \lambda \text{Tr} \nabla^2 \phi \hat{I} + \mu (\nabla \nabla \times \vec{\psi} + \nabla \nabla \times \vec{\psi}^T)$

b) $\nabla \cdot \vec{\sigma} = (2\mu + \lambda) \nabla \Delta \phi + \mu \nabla \times \Delta \vec{\psi} = -\vec{f} = \nabla(\rho g z)$

* Split of solutions: $\phi = \phi_p + \phi^*$; $\vec{\psi} = \vec{\psi}_p + \vec{\psi}^*$

$\therefore \vec{u} = \vec{u}_p + \vec{u}^* ; \quad \vec{\sigma} = \vec{\sigma}_p + \vec{\sigma}^* ; \dots$

* Particular (p) solution: We can choose $\vec{\psi}_p = 0$ and ϕ_p such that it satisfies $(2\mu + \lambda) \Delta \phi_p = \rho g z$

a) Ansatz $\tilde{\phi}_p = \alpha z^3 \Rightarrow \Delta \tilde{\phi}_p = 6\alpha z$, comparing: $\alpha = \frac{\rho g}{6(2\mu + \lambda)}$

b) However $\tilde{\phi}_p = \alpha z^3 = \alpha r^3 \cos^2 \theta = \alpha r^3 P_2 = \alpha r^3 (\frac{3}{5} P_1 + \frac{2}{5} P_3)$,

and since $\Delta r^3 P_3 \Rightarrow \phi_p = \frac{3}{5} \alpha r^3 P_1$

c) Note that $z^3 = r^3 (\frac{3}{5} P_1 + \frac{2}{5} P_3)$, so taking Δ :

$6z = \frac{3}{5} \Delta(r^3 P_1)$, from which $\Delta(r^3 P_1) = 10 r P_1$.

d) Also $\vec{r} \times \nabla z^3 = \vec{r} \times \nabla(r^3 (\frac{3}{5} P_1 + \frac{2}{5} P_3)) = r^3 (\frac{3}{5} \vec{R}_1 + \frac{2}{5} \vec{R}_3) / \Delta$

$\Delta(\vec{r} \times \nabla z^3) = \vec{r} \times \nabla \Delta z^3 = \vec{r} \times \nabla 6z = 6 r \vec{R}_1 = \frac{3}{5} \Delta(r^3 \vec{R}_1) \therefore \Delta(r^3 \vec{R}_1) = 10 r \vec{R}_1$

* Internal balance is therefore achieved when (*): $\nabla \cdot \vec{\sigma}^* = 0$

$\therefore$ Gen. sol. $\phi^* = \sum_n \alpha_n r^n P_n + \beta_n r^{n+2} P_n$ free loading

[Chnee] $\vec{\psi}^* = \sum_n (2\mu + \lambda) \beta_n r^{n+2} \vec{R}_n$

• Surface balance:

$$\hat{n} \cdot (\vec{\sigma}^+ - \vec{\sigma}^-)|_T = 0 \xrightarrow{O(u)} \hat{r} \cdot (\vec{\sigma}^+ - \vec{\sigma}_p - \vec{\sigma}^*)|_R = 0$$

$$\therefore \hat{r} \cdot \vec{\sigma}^*|_R = \hat{r} \cdot \vec{\sigma}^+|_R - \hat{r} \cdot \vec{\sigma}_p|_R \quad (\text{boundary condition on } \vec{\sigma}^*)$$

$$* \vec{\sigma}_p = 2\mu \nabla^2 \phi_p + \lambda I \Delta \phi_p, \text{ so}$$

$$a) \nabla \phi_p = \frac{3}{5} \alpha r^2 (3\vec{P}_1 + \vec{Q}_1)$$

$$b) \hat{r} \cdot \nabla^2 \phi_p = \partial_r \nabla \phi_p = \frac{6}{5} \alpha r (3\vec{P}_1 + \vec{Q}_1)$$

$$c) \therefore \hat{r} \cdot \vec{\sigma}_p|_R = \frac{12}{5} \alpha \mu R (3\vec{P}_1 + \vec{Q}_1) + 6\lambda \alpha R \vec{P}_1$$

$$* \text{ Since } \hat{z} = \nabla z = \nabla(rP_1) = \vec{P}_1 + \vec{Q}_1$$

$$\therefore \hat{r} \cdot \vec{\sigma}^+|_R = \frac{1}{3} R \rho \bar{g} \hat{z} = 2R\alpha(2\mu + \lambda)(\vec{P}_1 + \vec{Q}_1)$$

$$* \text{ Overall } \hat{r} \cdot \vec{\sigma}^*|_R \equiv \frac{2}{5} R\alpha(4\mu + 5\lambda)(\vec{Q}_1 - 2\vec{P}_1)$$

• Internal balance again

$$* \vec{\sigma}^* = 2\mu \nabla^2 \phi^* + \lambda I \Delta \phi^* + \mu (\nabla \nabla \times \vec{\psi}^* + \nabla \nabla \times \vec{\psi}^{*T})$$

$$a) \text{ based on BC's, we choose } \phi^* = 2A\mu r^3 \vec{P}_1; \vec{\psi}^* = A(2\mu + \lambda) r^3 \vec{R}_1$$

$$b) \nabla \phi^* = 2A\mu r^2 (3\vec{P}_1 + \vec{Q}_1) \therefore \hat{r} \cdot \nabla^2 \phi^*|_R = 4A\mu R (3\vec{P}_1 + \vec{Q}_1)$$

$$\text{and } \Delta \phi^*|_R = 20A\mu R \vec{P}_1$$

$$c) \nabla \times \vec{\psi}^* = 2A(2\mu + \lambda) r^2 (-2\vec{Q}_1 - \vec{P}_1)$$

$$\therefore \hat{r} \cdot \nabla \nabla \times \vec{\psi}^*|_R = 4A(2\mu + \lambda) R (-2\vec{Q}_1 - \vec{P}_1)$$

$$\text{and } \hat{r} \cdot (\nabla \nabla \times \vec{\psi}^*)^T|_R = 2A(2\mu + \lambda)(\vec{Q}_1 - 2\vec{P}_1)$$

$$* \text{ Overall } \hat{r} \cdot \vec{\sigma}^*|_R \equiv 2A\mu(2\mu + 3\lambda)R(2\vec{P}_1 - \vec{Q}_1) \equiv \hat{r} \cdot (\vec{\sigma}^+ - \vec{\sigma}_p)|_R$$

$$\therefore \text{Comparing, we get } A = - \frac{\alpha}{5} \frac{4\mu + 5\lambda}{\mu(2\mu + 3\lambda)} = - \frac{\rho \bar{g} (4\mu + 5\lambda)}{30\mu(2\mu + \lambda)(2\mu + 3\lambda)}$$

• In total:

$$* \vec{u} = \nabla \phi_p + \nabla \phi^* + \nabla \times \vec{\psi}^* \equiv \frac{\rho \bar{g} r^2}{6\mu(2\mu + 3\lambda)} [(\mu + 2\lambda)\vec{P}_1 + (3\mu + 4\lambda)\vec{Q}_1]$$

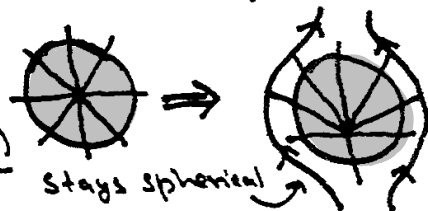
* Note that if $\vec{u}$ is a solution, then $\vec{u} + d\hat{z} = \vec{u} + d(\vec{P}_1 + \vec{Q}_1)$ is also

$$\text{a sol. } (\hat{z}\text{-shift}) \therefore \vec{u} = \frac{\rho \bar{g} R^2}{6\mu(2\mu + 3\lambda)} \left[(\mu + 2\lambda) \left(\frac{r^2}{R^2} - 1 \right) \vec{P}_1 + \left(\frac{r^2}{R^2} (3\mu + 4\lambda) - (\mu + 2\lambda) \right) \vec{Q}_1 \right]$$

$$a) \therefore \vec{u}|_R = \frac{\rho \bar{g} R^2 (\mu + \lambda)}{3\mu(2\mu + 3\lambda)} \vec{Q}_1 = \frac{\rho \bar{g} R^2 (1 - \nu)}{3E} \vec{Q}_1 \therefore T = R + \hat{r} \cdot \vec{u}|_R = R \quad (\nabla)$$

$$b) \vec{u}|_{r=0} = - \frac{\rho \bar{g} R^2 (\mu + 2\lambda)}{6\mu(2\mu + 3\lambda)} \hat{z} = - \frac{\rho \bar{g} R^2 (1 + 2\nu)}{6E} \hat{z}$$

$$c) \text{ Stored energy: } E_{\text{ela}} = \int_V \frac{1}{2} \vec{\sigma} : \vec{\epsilon} dV \equiv \frac{3\pi R V \bar{g}^2 \mu^2 (10\lambda + 7\mu)}{10\mu(3\lambda + 2\mu)}$$



6 ROTATING ELASTIC BALL

$\vec{u}^+ = \vec{u}^- + \vec{\omega} \times \vec{r}$ $T = R + \hat{r} \cdot \vec{u}|_R$; $\vec{\sigma}^- = 2\mu \vec{E} + \lambda \text{Tr} \vec{E} \hat{r}$;
 $\vec{u}^+ = 0$ (empty space) ; $\vec{\sigma}^+ = 0$ (empty space) ;
 $\vec{V} = \vec{V}_{\text{rot}} = -\frac{1}{2} \omega^2 \rho^2$.


• Internal balance :

$$\vec{f}^- + \nabla \cdot \vec{\sigma}^- = \vec{0} ; \quad \vec{f} = -\rho^- \nabla \bar{V} = \nabla \left(\frac{1}{2} \omega^2 \rho^2 \rho^- \right)$$

* Displacement decomposition $\vec{u} = \nabla \phi + \nabla \times \vec{\psi}$, so again

$$a) \vec{\sigma}^- = 2\mu \nabla^2 \phi + \lambda \text{Tr} \Delta \phi \hat{r} + \mu (\nabla \nabla \times \vec{\psi} + \nabla \nabla \times \vec{\psi}^T)$$

$$b) \nabla \cdot \vec{\sigma}^- = (2\mu + \lambda) \nabla \Delta \phi + \mu \nabla \times \Delta \vec{\psi} \equiv -\vec{f} = -\nabla \left(\frac{1}{2} \omega^2 \rho^2 \rho^- \right)$$

* Split of the solution : $\phi = \phi_p + \phi^*$; $\vec{\psi} = \vec{\psi}_p + \vec{\psi}^*$; $\vec{u} = \dots, \vec{\sigma} = \dots$

* Particular (p) solution : $\vec{\psi}_p = 0$ & ϕ_p so $(2\mu + \lambda) \Delta \phi_p = -\frac{1}{2} \omega^2 \rho^2 \rho^-$

$$a) \text{ Ansatz } \tilde{\phi}_p = \alpha \rho^4 \Rightarrow \nabla \tilde{\phi} = 4\alpha \rho^3 \hat{\rho} \quad , \quad \text{taking } \nabla \cdot :$$

$$\Delta \tilde{\phi}_p = \nabla \cdot \nabla \tilde{\phi}_p = 4\alpha (3\rho^2 \hat{\rho} \cdot \hat{\rho} + \rho^3 \underbrace{\nabla \cdot \hat{\rho}}_{1/\rho}) = 16\alpha \rho^2 ;$$

$$\text{Comparing : } \boxed{\alpha = -\frac{\rho^- \omega^2}{32(2\mu + \lambda)}} \quad 1/\rho$$

$$b) \text{ However } \tilde{\phi}_p = \alpha \rho^4 = \alpha r^4 \sin^4 \theta = \alpha r^4 \left(\frac{8}{15} P_0 - \frac{16}{21} P_2 + \frac{8}{35} P_4 \right)$$

$$\text{and since } \Delta(r^4 P_n) = 0 \Rightarrow \phi_p = \alpha r^4 \left(\frac{8}{15} P_0 - \frac{16}{21} P_2 \right)$$

$$c) \text{ Note that taking } \Delta \text{ of } \rho^4 = r^4 \left(\frac{8}{15} P_0 - \frac{16}{21} P_2 + \frac{8}{35} P_4 \right), \text{ we get}$$

$$16\rho^2 = \frac{8}{15} \Delta \cdot 4r^2 - \frac{16}{21} \Delta(r^4 P_2) \therefore \Delta(r^4 P_2) = 14r^2 P_2$$

$$d) \text{ Also since } \vec{r} \times \nabla \rho^4 = \vec{r} \times \nabla (r^4 (\frac{8}{15} - \frac{16}{21} P_2 + \frac{8}{35} P_4)) = r^4 (-\frac{16}{21} \vec{R}_2 + \frac{8}{35} \vec{R}_4)$$

$$\text{but } \Delta(\vec{r} \times \nabla \rho^4) = \vec{r} \times \nabla \Delta \rho^4 = 16 \vec{r} \times \nabla \rho^2 = 16 \vec{r} \times \nabla (r^2 (\frac{2}{3} (P_0 - P_2))) = -\frac{2}{3} r^2 16 \vec{R}_2$$

$$\equiv \Delta \left(r^4 (-\frac{16}{21} \vec{R}_2 + \frac{8}{35} \vec{R}_4) \right) = -\frac{16}{21} \Delta(r^4 \vec{R}_2) \therefore \Delta(r^4 \vec{R}_2) = 14r^2 \vec{R}_2$$

* Internal balance is then achieved when $\nabla \cdot \vec{\sigma}^* = 0 \Rightarrow$ [Chue's sol.]

• Surface balance

$$\hat{n} \cdot (\vec{\sigma}^+ - \vec{\sigma}^-)|_T = 0 \quad O(\vec{u}) \Rightarrow \hat{r} \cdot \vec{\sigma}^*|_R = -\hat{r} \cdot \vec{\sigma}_p|_R \quad (\text{BC for } \vec{\sigma}^*)$$

$$* \vec{\sigma}_p = 2\mu \nabla^2 \phi_p + \lambda \text{Tr} \Delta \phi_p \hat{r}, \text{ so}$$

$$a) \nabla \phi_p = \nabla 8\alpha r^4 \left(\frac{1}{15} P_0 - \frac{2}{21} P_2 \right) = 8\alpha r^3 \left(\frac{4}{15} \vec{P}_0 - \frac{8}{21} \vec{P}_2 - \frac{2}{21} \vec{R}_2 \right)$$

$$b) \hat{r} \cdot \nabla^2 \phi_p = \partial_r \nabla \phi_p = 24\alpha r^2 \left(\frac{4}{15} \vec{P}_0 - \frac{8}{21} \vec{P}_2 - \frac{2}{21} \vec{R}_2 \right)$$

c) and since $\Delta\phi_p = 16\alpha\rho^2 = 16\alpha r^2 s^2 \theta = \frac{32}{3}\alpha r^2 (P_0 - P_2)$, we get

$$* \therefore \hat{r} \cdot \vec{\sigma}_p|_R = 96\alpha\mu R^2 \left(\frac{2}{15} \vec{P}_0 - \frac{4}{21} \vec{P}_2 - \frac{1}{21} \vec{Q}_2 \right) + \frac{32\alpha}{3} \lambda R^2 (\vec{P}_0 - \vec{P}_2)$$

$$* \text{Overall } \hat{r} \cdot \vec{\sigma}^*|_R = -\hat{r} \cdot \vec{\sigma}_p|_R = 32\alpha R^2 \left[-\frac{2\mu}{5} \vec{P}_0 + \frac{4\mu}{7} \vec{P}_2 + \frac{\mu}{7} \vec{Q}_2 - \frac{\lambda}{5} \vec{P}_0 + \frac{\lambda}{5} \vec{P}_2 \right]$$

• Internal balance again

$$* \vec{\sigma}^* = 2\mu \nabla^2 \phi^* + \lambda I \Delta \phi^* + \mu (\nabla \nabla \times \vec{\psi}^* + \nabla \nabla \times \vec{\psi}^{*T})$$

a) Based on BC's, we choose (Chee's sol. ansatz):

$$\phi^* = A\mu r^2 P_0 + B r^2 P_2 + 3C\mu r^4 P_2$$

$$\vec{\psi}^* = A(2\mu + \lambda) R_0^0 + C(2\mu + \lambda) r^4 \vec{Q}_2$$

$$b) \nabla \phi^* = 2A\mu r \vec{P}_0 + B r (2\vec{P}_2 + \vec{Q}_2) + 3C\mu r^3 (4\vec{P}_2 + \vec{Q}_2)$$

$$\therefore \hat{r} \cdot \nabla^2 \phi^*|_R = 2A\mu \vec{P}_0 + B(2\vec{P}_2 + \vec{Q}_2) + 9C\mu R^2 (4\vec{P}_2 + \vec{Q}_2)$$

$$\text{and } \Delta \phi^*|_R = 6A\mu P_0 + 42C\mu R^2 P_2$$

$$c) \nabla \times \vec{\psi}^* = C(2\mu + \lambda) r^3 (-5\vec{Q}_2 - 6\vec{P}_2)$$

$$\therefore \hat{r} \cdot \nabla \nabla \times \vec{\psi}^*|_R = \partial_r \nabla \times \vec{\psi}|_R = 3C(2\mu + \lambda) R^2 (-5\vec{Q}_2 - 6\vec{P}_2)$$

$$\text{and } \hat{r} \cdot (\nabla \nabla \times \vec{\psi}^*)^T|_R = (\nabla \nabla \times \vec{\psi}^*) \cdot \hat{r}|_R \equiv C(2\mu + \lambda) R^2 (-18\vec{P}_2 - \vec{Q}_2);$$

$$\text{so adding these two: } \hat{r} \cdot (\nabla \nabla \times \vec{\psi}^* + \nabla \nabla \times \vec{\psi}^{*T})|_R = C(2\mu + \lambda) R^2 (-36\vec{P}_2 - 16\vec{Q}_2)$$

$$* \text{Overall } \hat{r} \cdot \vec{\sigma}^*|_R = \hat{r} \cdot [2\mu \nabla^2 \phi^* + \lambda I \Delta \phi^* + \mu (\nabla \nabla \times \vec{\psi}^* + \nabla \nabla \times \vec{\psi}^{*T})]|_R \equiv \\ = 2\mu [2A\mu \vec{P}_0 + B(2\vec{P}_2 + \vec{Q}_2) + 9C\mu R^2 (4\vec{P}_2 + \vec{Q}_2)] + \lambda [6A\mu \vec{P}_0 + 42C\mu R^2 \vec{P}_2] + \\ + C\mu(2\mu + \lambda) R^2 (-36\vec{P}_2 - 16\vec{Q}_2) \stackrel{BC}{=} 32\alpha R^2 \left[-\frac{2\mu}{5} \vec{P}_0 + \frac{4\mu}{7} \vec{P}_2 + \frac{\mu}{7} \vec{Q}_2 - \frac{\lambda}{5} \vec{P}_0 + \frac{\lambda}{5} \vec{P}_2 \right]$$

$\therefore$ Comparing, we get (solving linear system of eqs.):

$$A = -\frac{16\alpha R^2 (6\mu + 5\lambda)}{15\mu(2\mu + 3\lambda)}; B = \frac{32\alpha R^2 (2\mu + \lambda)(3\mu + 4\lambda)}{3\mu(14\mu + 19\lambda)}; C = \frac{16\alpha(6\mu + 7\lambda)}{21\mu(14\mu + 19\lambda)}$$

• In total:

$$* \vec{u} = \nabla \phi_p + \nabla \phi^* + \nabla \times \vec{\psi}^* = 16\alpha r^3 \left(\frac{2}{15} \vec{P}_0 - \frac{4}{21} \vec{P}_2 - \frac{1}{21} \vec{Q}_2 \right) + 2A\mu r \vec{P}_0 + \\ + B r (2\vec{P}_2 + \vec{Q}_2) + 3C\mu r^3 (4\vec{P}_2 + \vec{Q}_2) + C(2\mu + \lambda) r^3 (-5\vec{Q}_2 - 6\vec{P}_2)$$

$$a) \vec{u}|_R \equiv -\frac{64\alpha R^3 (2\mu + \lambda)}{15(2\mu + 3\lambda)} \vec{P}_0 + \frac{32\alpha R^3 (2\mu + \lambda)(4\mu + 5\lambda)}{3\mu(14\mu + 19\lambda)} \vec{P}_2 + \frac{16\alpha R^3 (2\mu + \lambda)(2\mu + 3\lambda)}{3\mu(14\mu + 19\lambda)} \vec{Q}_2$$

$$b) \therefore T = R + \hat{r} \cdot \vec{u}|_R \equiv R + R^3 \rho \omega^2 \left[\frac{2}{15(2\mu + 3\lambda)} - \frac{4\mu + 5\lambda}{3\mu(14\mu + 19\lambda)} P_2 \right] \equiv$$

$$\equiv T_{0s} = RE \left(1 - \frac{1}{3} e^2 P_2 \right) = R \left(1 + \frac{1}{3} \delta - \frac{1}{3} e^2 P_2 \right) \text{ (oblate spheroid topography)}$$

$$\therefore \text{Comparing: } \delta = \frac{V}{V_0} - 1 = \frac{2R^2 \rho \omega^2}{5(2\mu + 3\lambda)} = \frac{2R^2 \rho \omega^2 (1 - 2e^2)}{5E}; e^2 = R^2 \rho \omega^2 \frac{4\mu + 5\lambda}{\mu(14\mu + 19\lambda)} = \frac{2R^2 \rho \omega^2 (1 + \lambda)(2\mu)}{E(7 + 5\lambda)}$$