

UA2

2.1

Recap

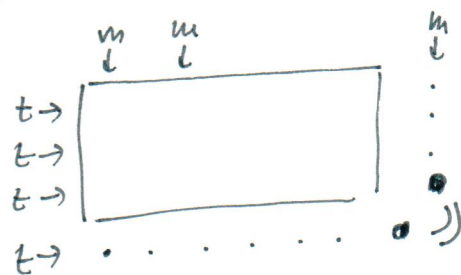
affine = polynomially equivalent to a module

abelian =  $\forall t \in \text{Clo}(A) \quad \forall \bar{x}, \bar{y} \in A^k \quad \forall \bar{u}, \bar{v} \in A^l$   
 $t(\bar{x}, \bar{u}) = t(\bar{x}, \bar{v}) \Rightarrow t(\bar{y}, \bar{u}) = t(\bar{y}, \bar{v})$

- Ex.
- affine
  - unary

Equivalent def. :  $k=1$

$\star$  affine  $\Rightarrow$  abelian and has Mal'cev polynomial, which is central exactly one



abelian + Mal'cev  $\Rightarrow$  affine

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When abelian  $\Rightarrow$  affine?

✓ if  $\text{HSP}(\underline{A})$  congruence permutable  
 $\Leftrightarrow \underline{A}$  has a Mal'cev term operation

✓ if  $\text{HSP}(\underline{A})$  congruence distributive  
 $\Leftrightarrow \underline{A}$  has a majority term operation

— only singleton algebras are abelian

✓ if  $\text{HSP}(\underline{A})$  congruence modular (generalizes both  $\uparrow$ )  
[Herrmann '77]

✓ if  $\underline{A}$  is finite and satisfies any nontrivial  
Mal'cev condition

(generalizes all above for finite algebras)

[Hobby, McKenzie '80s - Tame congruence theory  
easy proof via absorption]

Example  $(\mathbb{Q}; \frac{x+y}{2})$

• abelian

• satisfies a nontrivial idempotent  
Mal'cev condition  $(\begin{matrix} x*y = y*x \\ x*x = x \end{matrix})$

• no Mal'cev polynomial operation  
(use  $\leq$ )

## Relational characterization of abelianess

Proposition  $\underline{A}$  algebra. @

(i)  $\underline{A}$  is abelian

(ii)  $\Delta (= \{(a, a); a \in A\})$  is a block of a congruence of  $\underline{A}^2$

Proof: Note: (ii)  $\Leftrightarrow$

$\Delta$  is a block of  $Cg_{\underline{A}^2}(\Delta^2)$

Recall (?)  $\underline{B}$  algebra,  $X \subseteq B \times B$

$Cg_{\underline{B}}(X) = \text{transitive symmetric closure of } \{(p(a), p(b)); (a, b) \in X, p \text{ unary polynomial op.}\}$

$Cg_{\underline{A}^2}(\Delta^2) = \text{trans. sym. cl. of } \{(p(a), p(b)); a, b \in A, p \text{ unary polynomial op. of } \underline{A}^2\}$

$= \text{---} \{ (t(\begin{pmatrix} a \\ a \end{pmatrix}, \begin{pmatrix} c_1 \\ d_1 \end{pmatrix}, \dots, \begin{pmatrix} c_n \\ d_n \end{pmatrix}), t(\begin{pmatrix} b \\ b \end{pmatrix}, \begin{pmatrix} c_1 \\ d_1 \end{pmatrix}, \dots, \begin{pmatrix} c_n \\ d_n \end{pmatrix}); a, b, c_i, d_i \in A, t \in \text{Clo}(\underline{A}) \}$

$\Delta$  is a block of  $\uparrow$  iff

$t(\begin{pmatrix} a \\ a \end{pmatrix}, \begin{pmatrix} c_1 \\ d_1 \end{pmatrix}, \dots) \in \Delta \Leftrightarrow t(\begin{pmatrix} b \\ b \end{pmatrix}, \begin{pmatrix} c_1 \\ d_1 \end{pmatrix}, \dots)$

iff (i) (def. of abelianess with  $k=1$ )

## Example

Let  $\underline{A} = (\{0, 1\}; \dots)$ ,  $\underline{A}$  has a Mal'cev polynomial operation (or  $\dots$ ),  $R := \{000, 011, 101, 110\} \subseteq \underline{A}^3$ .

Claim:  $\underline{A}$  is affine (ie  $\underline{A}$  poly. eq. to  $(\mathbb{Z}_2, +)$ )

• Note:  $R(xyz)$  iff  $x+y+z = 0 \pmod{2}$

• By proposition, enough to find congruence  $\sim$  of  $\underline{A}^2$  whose block is  $\{(0,0), (1,1)\} = \Delta$

→ Find  $\sim \subseteq (\underline{A}^2)^2 \cong \underline{A}^4$  whose block is  $\Delta$

• How to produce subpowers (= compatible rel's)?

→ PP-definitions

→ PP-define from  $R$  a relation  $S \subseteq \underline{A}^4$

so that when viewed as  $\sim \subseteq (\underline{A}^2)^2$  it is an equivalence whose one block is  $\Delta$

$S(x, y, x', y') \stackrel{\text{def}}{=} \dots$

A taste of Commutator Theory

Def.  $\alpha, \beta, \gamma \in \text{Con } \underline{A}$ ,  $\alpha$  centralizes  $\beta$  modulo  $\delta$ , written  $C(\alpha, \beta; \delta)$  if  $(x_1 \alpha y_1, x_2 \alpha y_2) \dots$

$$\forall t \in \text{Clo}(\underline{A}) \quad \forall \bar{x}, \bar{y} \in A^k \quad \bar{x} \alpha \bar{y}$$

$$\forall \bar{u}, \bar{v} \in A^l \quad \bar{u} \beta \bar{v}$$

$$t(\bar{x}, \bar{u}) \delta t(\bar{x}, \bar{v}) \Rightarrow t(\bar{y}, \bar{u}) \delta t(\bar{y}, \bar{v})$$

Remarks

- $\underline{A}$  abelian if  $C(\underline{1}_A, \underline{1}_A, \underline{0}_A)$

- def:  $\alpha \leq \beta$  in  $\text{Con } \underline{A}$ .  $\beta$  abelian over  $\alpha$  if  $C(\beta, \beta; \alpha)$

- def  $\alpha, \beta \in \text{Con } \underline{A}$ . commutator of  $\alpha, \beta$  is the smallest  $\delta$  such that  $C(\alpha, \beta; \delta)$

- well defined
- $[\alpha, \beta] \leq \alpha \wedge \beta$
- in general  $[\alpha, \beta] \neq [\beta, \alpha]$  (but = in CM)

- def.  $\underline{A}$  solvable if ...

nilpotent if .....

.... in groups it matches the standard concepts

no need to memorize

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Proposition  $G$  group,  $\alpha, \beta, \delta \in \text{Con } G$ ,

$A, B, D$  the corresponding normal subgroups  
(ie  $A = 1/\alpha, B = 1/\beta, D = 1/\delta$ )

Then  $C(\alpha, \beta; \delta)$  iff  $\forall a \in A \forall b \in B \quad ab \delta ba$   
 $(\Leftrightarrow aba^{-1}b^{-1} \in D)$

Proof: • WLOG  $\delta = 1$  (as  $C(\alpha, \beta; \delta)$  in  $A$  iff  $C(\alpha/\delta, \beta/\delta; 1)$  in  $A/\delta$ )

$\Rightarrow$  
$$\begin{matrix} 1 & b & 1^{-1} & b^{-1} \\ x_1 & u_1 & x_2 & u_2 \end{matrix} = \begin{matrix} 1 & 1 & 1^{-1} & 1^{-1} \\ y_1 & v_1 & y_2 & v_2 \end{matrix}$$
 Note  $\begin{matrix} \bar{u} & \beta & \bar{v} \\ \bar{x} & \alpha & \bar{y} \end{matrix}$

$\Rightarrow a \cdot b \cdot a^{-1} \cdot b^{-1} = a \cdot 1 \cdot a^{-1} \cdot 1^{-1} = 1$

$\Leftarrow$  we assume  $\forall a \in A \forall b \in B \quad ab = ba \quad (aba^{-1}b^{-1} = 1)$

①  $\forall \bar{w}_1, \bar{w}_2 \quad \bar{w}_1 \in B \quad \bar{w}_2 \in \text{cl}(A) \quad r(\bar{w}_1) r(\bar{w}_2)^{-1} \in B$

②  $\forall w_1, w_2 \quad w_1 \in A \quad w_2 \in B \quad \forall b \in B \quad w_1^{-1} b w_1 = w_2^{-1} b w_2$

Prf: 
$$\underbrace{w_2 w_1^{-1}}_{\in A} b \underbrace{w_1 w_2^{-1}}_{\in B} \stackrel{?}{=} b$$
  
$$\parallel b w_2 w_1^{-1} w_1 w_2^{-1}$$

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- $x \simeq y, \bar{u} \beta \bar{v}, t \in \text{Clo}(A)$

want  $t(x, \bar{u}) = t(x, \bar{v}) \Rightarrow t(y, \bar{u}) = t(y, \bar{v})$

will prove  $t(x, \bar{u}) t(x, \bar{v})^{-1} = t(y, \bar{u}) t(y, \bar{v})^{-1}$

- $t(x_1, \dots, x_n) = z_1 \cdot z_2 \cdot \dots \cdot z_m$  where each  $z_i$  is  $x_i^{\pm 1}, x_2^{\pm 1}, \dots$ , or,  $x_n^{\pm 1}$

induction on  $m$

$m=1$

- $t(x_1, \dots, x_n) = x_1$        $xx^{-1} \stackrel{?}{=} yy^{-1} \checkmark$
- $t(x_1, \dots, x_n) = x_2$        $u, v_i^{-1} \stackrel{?}{=} u, v_i^{-1} \checkmark$

similarly  $x_i^{-1}$

$x_2^{-1}, x_3^{\pm 1}, \dots$

ind. step: •  $t(x_1, \dots, x_n) = x_1 s(x_1, \dots, x_n)$

similarly  $x_i^{-1}$

$$\begin{aligned} \text{LHS} &= x_1 s(x, \bar{u}) (x_1 s(x, \bar{v}))^{-1} = \\ &= x_1 s(x, \bar{u}) s(x, \bar{v})^{-1} x_1^{-1} = \end{aligned}$$

$$\stackrel{IH}{=} x_1 s(y, \bar{u}) s(y, \bar{v})^{-1} x_1^{-1} =$$

$$\stackrel{\textcircled{2}}{=} y_1 s(y, \bar{u}) s(y, \bar{v})^{-1} y_1^{-1} = \text{RHS}$$

$\rightarrow$  in B by  $\textcircled{1}$

- $t(x_1, \dots, x_n) = x_2 s(x_1, \dots, x_n)$

similarly  $x_2^{-1}, x_3^{\pm 1}, \dots$

$$\text{LHS} = u_1 s(x, \bar{u}) s(x, \bar{v})^{-1} v_i^{-1}$$

$$\stackrel{IH}{=} u_1 s(y, \bar{u}) s(y, \bar{v})^{-1} v_i^{-1}$$

$$= \text{RHS}$$