

Sensitive instances of the Constraint Satisfaction Problem

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Constraint Satisfaction Problem (CSP)

Is it possible to assign domain elements to variables so that given local constraints are satisfied?

Strategy: $(k, k + 1)$ -consistency algorithm

Derive the strongest possible constraint on each set of k variables by considering $k + 1$ variables at a time

How good is the algorithm?

“so so” no contradiction found \Rightarrow solution exists

“great” every partial solution on $\geq k$ variables extends to a solution

“good” every partial solution on k variables extends to a solution
= every sharpening of a constraint invalidates some solution

sensitivity

Instance of the CSP is a list of constraints $R(\mathbf{x})$

- ▶ \mathbf{x} is a list of variables, called the **scope**
- ▶ R is a relation on a fixed domain A of appropriate arity

Example: $R(x_1, x_2), S(x_2, x_4, x_2), R(x_3, x_4)$, where
 $R \subseteq \{0, 1, 2\}^2, S \subseteq \{0, 1, 2\}^3$

Solution: mapping variables \rightarrow domain
that satisfies every constraint

Partial solution: partial mapping variables \rightarrow domain
that satisfies every constraint with fully evaluated scope

Sensitive instance: every sharpening of a constraint
invalidates some solution

Fix: $k \geq 1$

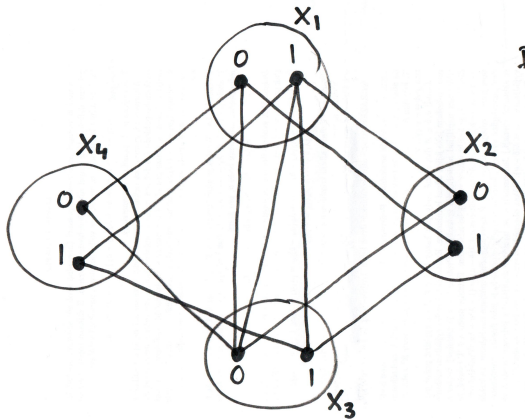
Assume: all constraint relations have arity $\leq k$

$(k, k + 1)$ -consistency algorithm produces a $(k, k + 1)$ -instance

- ▶ every k -element set of variables is constraint by a single constraint (and there are no other constraints)
- ▶ each partial solution on k variables can be extended to any additional variable

and

- ▶ the algorithm is polynomial
- ▶ the $(k, k + 1)$ -instance has the same solution set as the original one



Domain $\{0, 1\}$

$R(x_1, x_2),$

$S(x_1, x_3),$

$T(x_1, x_4),$

$T(x_2, x_3),$

$T(x_3, x_4)$

Template is

- ▶ **relational structure** $\mathbb{A} = (A; R_1, R_2, \dots)$, each $R_i \subseteq A^{k_i}$
- ▶ or **algebra** $\mathbf{A} = (A; f_1, f_2, \dots)$, each $f_i : A^{k_i} \rightarrow A$

CSP over \mathbb{A} : constraint relations are from \mathbb{A}

Examples: 3-SAT, 3-LIN_p, HORN-3-SAT, 2-SAT

CSP over \mathbf{A} : constraint rel's are compatible with operations in \mathbf{A}

Examples:

CSP over $(\{0, 1\}; (x, y, z) \mapsto x + y + z \pmod{2})$ is \sim LIN₂

CSP over $(\{0, 1\}; (x, y) \mapsto \min(x, y))$ is \sim HORN-SAT

CSP over $(\{0, 1\}; (x, y, z) \mapsto \text{majority of } x, y, z)$ is \sim 2-SAT

Operation $t : A^m \rightarrow A$ is

- ▶ **idempotent** if $(\forall a \in A) t(a, a, \dots, a) = a$
- ▶ **near unanimity of arity m , or $NU(m)$** if $(\forall a, b \in A)$
 $t(b, a, \dots, a) = t(a, b, a, \dots, a) = \dots = t(a, \dots, a, b)$

Theorem ([BKTV])

Let $k \geq 2$ and \mathbf{A} a finite idempotent algebra. TFAE

- (i) \mathbf{A} has an $NU(k+2)$ term operation.
- (ii) Every $(k, k+1)$ -instance of CSP over \mathbf{A}^2 is sensitive.

- ▶ idempotency and square in \mathbf{A}^2 necessary for (ii) \Rightarrow (i)
- ▶ not necessary for (i) \Rightarrow (ii)
- ▶ more general version for infinite idempotent algebras

Consider $k \geq 2$, \mathbb{A} a finite structure with relations of arity $\leq k$

If \mathbb{A} has a compatible $\text{NU}(m)$ (for some m), the alg. is “so so”
for any instance of CSP over \mathbb{A}
if the associated $(k, k + 1)$ -instance is non-trivial,
then there exists a solution [B., Kozik'09, B.'16]

If \mathbb{A} has a compatible $\text{NU}(k + 1)$, then the algorithm is “great”
for any instance of CSP over \mathbb{A}
in the associated $(k, k + 1)$ -instance
every partial solution on $\geq k$ variables extends to a solution
[Bergman'77, Feder, Vardi'99]

If \mathbb{A} has a compatible $\text{NU}(k + 2)$, then the algorithm is “good”
for any instance of CSP over \mathbb{A}
the associated $(k, k + 1)$ -instance is sensitive [BKTV]

Note: $\text{NU}(3) \Rightarrow \text{NU}(4) \Rightarrow \text{NU}(5) \Rightarrow \dots$

- ▶ 3-LIN_p tractable, but not “so so” for any k
- ▶ HORN-3-SAT is “so so” but not “good” (for any k)
- ▶ 2-SAT is “great” ($k \geq 2$)
- ▶ the following structure is “good” but not “great” for $k = 2$

$\mathbb{A} = (\{0, 1\}^2; R_1, R_2, R_3)$, where $((a, b), (c, d)) \in R_i$ iff

$$(i=1) \quad a + b + c + d \geq 2$$

$$(i=2) \quad a = c$$

$$(i=3) \quad a = d$$

Theorem ([BKTV])

Let $k \geq 2$ and \mathbf{A} a finite idempotent algebra. TFAE

- (i) \mathbf{A} has an $NU(k+2)$ term operation.
- (ii) Every $(k, k+1)$ -instance of $CSP(\mathbf{A}^2)$ is sensitive.

(ii) \Rightarrow (i):

- ▶ careful choices of $(k, k+1)$ -instances give “very local” $NU(k+2)$'s
- ▶ $NU(k+2)$ can be assembled from these [Horowitz'13]

(i) \Rightarrow (ii): we apply a new loop lemma, improvement of [Olšák'17]

Theorem ([BKTV]): If $S \subseteq A^2$ contains a directed closed walk and absorbs all the loops, then S has a loop.

For \mathbb{A} with \leq 2-ary relations compatible with $\text{NU}(k+2)$, $k \geq 2$

“so so” after enforcing (2, 3)-consistency, no contradiction found \Rightarrow solution

“good” after enforcing $(k, k+1)$ -consistency, every partial solution on k variables extends to a solution

“great” after enforcing $(k+1, k+2)$ -consistency, every partial solution on $\geq k$ variables extends to a solution

Questions:

- ▶ gap between “so so” and “good” – \exists natural conditions in between?
- ▶ “so so” and “great” (holding for every instance) can be characterized by compatible operations, what about “good”?
- ▶ “so so” and “great” have natural versions for higher arity relations, is there such for “good”?
- ▶ characterization of “great” has a generalization to a class of infinite domain structures (by means of **oligopotent quasi-NUs**), is it possible to generalize our result to oligopotent quasi-NUs?