

Behaviour of the smallest singular value while appending a column of a matrix

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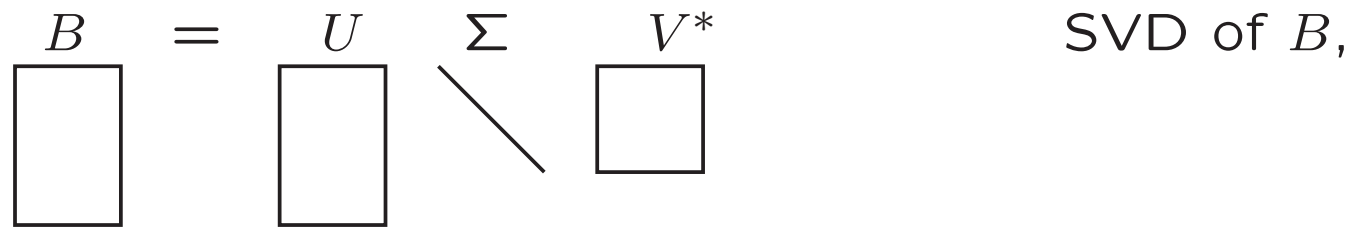
Question

When appending a column to a matrix cause no change of the smallest singular value;
and, if it cause a change, when the change is small?

Solution

Paige, S. Numerische Mathematik (2002) 91: 117–146,
Paige, S. Numerische Mathematik (2002) 91: 91–115,
Wilkinson, Algebraic Eigenvalue Problem, (1965) §39,
Golub, Bunch, Nielsen, Elsner, Mehrmann, He, . . .

B an n by k matrix, c an n -vector, $n > k$, $\text{rank}(B) = k$, $\gamma > 0$

$$B = U \Sigma V^* \quad \text{SVD of } B,$$


$\delta(\gamma) = \sigma_{\min}([c\gamma, B]) / \sigma_{\min}(B)$. When $\delta(\gamma) = 1$ ($\delta(\gamma) \rightarrow 1$) ?

$$\left[\begin{array}{c|c} \gamma^2 \|c\|^2 & \gamma(B^*c)^T \\ \hline \gamma B^*c & B^*B \end{array} \right] \approx \left[\begin{array}{c|c} \gamma^2 \|c\|^2 & \gamma(\Sigma U^*c)^T \\ \hline \gamma \Sigma U^*c & \Sigma^2 \end{array} \right]$$

A zero entry in U^*c indicates trivial preserving of the corresponding singular value.

Denote by

$$\sigma_1(B) > \cdots > \sigma_{t-1}(B) > \sigma_t(B) \equiv \sigma_{\min}(B)$$

the distinct singular values of B with multiplicities r_1, \dots, r_t . Then the s. v. of $[c\gamma, B]$ must solve the characteristic equation

$$\begin{aligned} & (\gamma^2 \|c\|^2 - \sigma^2) \prod_{i=1}^t (\sigma_i^2 - \sigma^2)^{r_i} \\ & - \gamma^2 \sum_{i=1}^t \sigma_i^2 \|c_i\|^2 (\sigma_i^2 - \sigma^2)^{r_i-1} \prod_{\substack{j=1 \\ j \neq i}}^t (\sigma_j^2 - \sigma^2)^{r_j} = 0 \end{aligned}$$

where $\|c_i\|$ denotes the size of the component of the vector c in the subspace generated by the left singular vectors of B corresponding to σ_i .

Each singular value of B with $r_i > 1$ must be at least $r_i - 1$ multiple singular value of $[c\gamma, B]$. Singular values of $[c\gamma, B]$ different from the singular values of B must solve the **deflated secular equation**

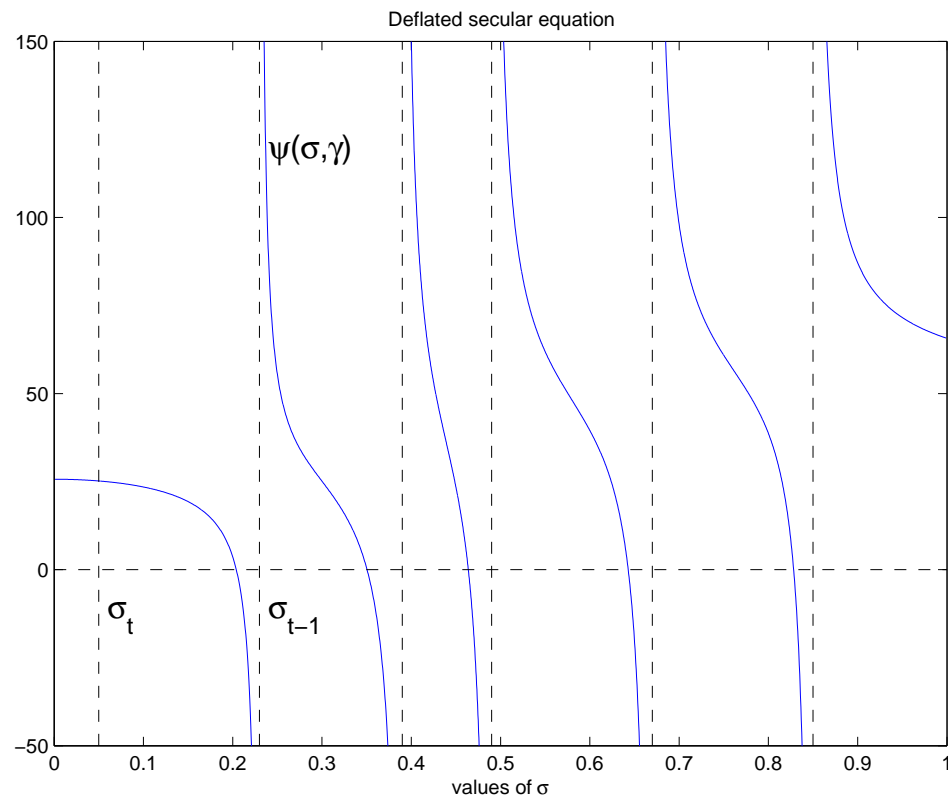
$$\gamma^2 \|c\|^2 - \sigma^2 - \gamma^2 \sum_{i=1}^t \|c_i\|^2 \frac{\sigma_i^2}{\sigma_i^2 - \sigma^2} = 0.$$

Denoting by r the residual of the LS problem for $Bx \approx c$,

$$\|r\|^2 = \|c\|^2 - \sum_{i=1}^t \|c_i\|^2,$$

the deflated secular equation gets the form

$$\psi(\sigma, \gamma) \equiv \gamma^2 \|r\|^2 - \sigma^2 - \gamma^2 \sigma^2 \sum_{i=1}^t \frac{\|c_i\|^2}{\sigma_i^2 - \sigma^2} = 0.$$



Recall the notation

$$\sigma_1(B) > \cdots > \sigma_{t-1}(B) > \sigma_t(B) \equiv \sigma_{\min}(B)$$

Theorem 1: Necessary and sufficient condition

$$\sigma_{\min}([c\gamma, B]) = \sigma_{\min}(B) \quad (\delta(\gamma) = 1)$$

if and only if

$$\|c_t\| = 0 \quad \text{and} \quad \psi(\sigma_{\min}(B), \gamma) \geq 0.$$

Assume $c_t \neq 0$. Then

$$\sigma_{\min}([c\gamma, B]) \equiv \sigma_{t+1}([c\gamma, B]) < \sigma_{\min}(B), \quad \delta(\gamma) < 1.$$

Theorem 2: Bounds

$$\delta(\gamma) \leq \frac{\|r\|}{(\|c_t\|^2 + \|r\|^2)^{1/2}} < 1, \quad \delta(\gamma) \leq \frac{\gamma\|r\|}{\sigma_t([c\gamma, B])}.$$

Theorem 3: Dependence on γ in $([c\gamma, B])$

For $\gamma < \sigma_{\min}(B)/\|c\|$ we get $\delta(\gamma) < 1$.

For $\gamma = \hat{\gamma} \equiv \sigma_{\min}(B)/\|c\|$

$\delta(\hat{\gamma}) = 1$ if and only if $\|r\| = \|c\|$ ($\|c_i\| = 0, i = 1, \dots, t$).

Moreover, with $\hat{\gamma}$ we have the following bound for the LS residual

$$\delta(\hat{\gamma}) \|c\| \leq \|r\| \leq \delta(\hat{\gamma}) \|c\| \{2 - \delta(\hat{\gamma})^2\}^{1/2}.$$

Liesen, Rozložník, S, SISC (2002), 23: 1503–1525

What is it good for?

I. Basic solution of the (Scaled) Total Least Squares

II. Fundamentals of (Scaled) Total Least Squares:

- A consistent theory ($c_t = 0 \Rightarrow \sigma_{\min}(B)$ should play no role!)
- A new approach to single right hand side problems based on the bidiagonalization of $[c, B]$

III. Rounding error analysis of MGS GMRES:

$\delta \rightarrow 1$ disturbs the bounds. However, small residual norm cause $\delta \ll 1$.

Sherman2, b MM, $x_0 = 0$

