On Generalized Spectrum of Second Order Elliptic Differential Operators

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Problem with bounded invertible operator $\,\mathcal{G}\,\,$ on the infinite dimensional Hilbert space $\,S\,\,$

$$\mathcal{G} u = f$$

is approximated on a finite dimensional subspace $S_h \subset S$ by a problem with the finite dimensional operator

$$\mathcal{G}_h u_h = f_h ,$$

represented, using an appropriate basis of S_h , by the (sparse?) matrix problem

$$\mathbf{A}\mathbf{x} = \mathbf{b}$$
.

(Infinite dimensional) Krylov subspace methods at the step n implicitly construct the finite dimensional approximation \mathcal{G}_n of \mathcal{G} which determines the desired approximate solution $u_n \in u_0 + \mathcal{K}_n(\mathcal{G}, r), \quad r = f - \mathcal{G}u_0$

$$u_n := u_0 + p_{n-1}(\mathcal{G}) r \approx u = \mathcal{G}^{-1} f.$$

Here $p_{n-1}(\lambda)$ is the associated polynomial of degree at most n-1 and \mathcal{G}_n is obtained by restricting and projecting \mathcal{G} onto the *n*th Krylov subspace

$$\mathcal{K}_n(\mathcal{G}, r) := \operatorname{span}\left\{r, \mathcal{G}r, \dots, \mathcal{G}^{n-1}r\right\}.$$

A.N. Krylov (1931), Gantmakher (1934), Hestenes and Stiefel (1952), Lanczos (1952-53); Karush (1952), Hayes (1954), Stesin (1954), Vorobyev (1958) From

$$r_n^{\mathrm{M}} = f - \mathcal{G} u_n^{\mathrm{M}} = r - \mathcal{G} p_{n-1}^{\mathrm{M}}(\mathcal{G}) r =: \varphi_n^{\mathrm{M}}(\mathcal{G}) r$$

we get the approximation polynomial

$$\varphi_n^{\mathrm{M}}(\lambda) = 1 - \lambda p_{n-1}^{\mathrm{M}}(\lambda),$$

which is nonlinear both in \mathcal{G} (obvious) and f (through the orthogonality/optimality property defining the particular method M). Clearly

$$\varphi_n^{\mathrm{M}}(0) = 1.$$

Motivation: Class of elliptic PDEs, frequently used example



 $- \, \nabla \cdot \left(\, k(x) \, \nabla u \, \right) \; = \; 0 \, ,$

Morin, Nocheto, Siebert, SIREV (2002), linear FE, standard uniform triangulation, N = 3969 DOF.

ICHOL PCG (drop-off tolerance 1e-02), $\kappa \approx 16$; Laplace operator PCG, $\kappa \approx 160$.

- Spectral information and convergence of the conjugate gradient method
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1 Predicting the computational cost?



Here we will not deal with the algorithmic and computational issues related to preconditioning. Therefore in the description of convergence we will consider a preconditioned system of equations.

$$r_0 = b - Ax_0, \ p_0 = r_0$$
. For $n = 1, \dots, n_{\text{max}}$:

$$\begin{aligned} \alpha_{n-1} &= \frac{r_{n-1}^* r_{n-1}}{p_{n-1}^* A p_{n-1}} \\ x_n &= x_{n-1} + \alpha_{n-1} p_{n-1} , \text{ stop when the stopping criterion is satisfied} \\ r_n &= r_{n-1} - \alpha_{n-1} A p_{n-1} \\ \beta_n &= \frac{r_n^* r_n}{r_{n-1}^* r_{n-1}} \\ p_n &= r_n + \beta_n p_{n-1} \end{aligned}$$

Here α_{n-1} ensures the minimization of the energy norm $\|x - x_n\|_A$ along the line

$$z(\alpha) = x_{n-1} + \alpha p_{n-1} \,.$$

Provided that

$$p_i \perp_A p_j, \quad i \neq j,$$

the one-dimensional line minimizations at the individual steps 1 to n result in the n-dimensional minimization over the whole shifted Krylov subspace

$$x_0 + \mathcal{K}_n(A, r_0) = x_0 + \operatorname{span}\{p_0, p_1, \dots, p_{n-1}\}.$$

Indeed,

$$x - x_0 = \sum_{\ell=0}^{N-1} \alpha_\ell p_\ell = \sum_{\ell=0}^{n-1} \alpha_\ell p_\ell + x - x_n \,,$$

where

 $x - x_n \perp_A K_n(A, r_0)$, or, equivalently, $r_n \perp K_n(A, r_0)$.

1 Optimality seen through the CG polynomial $\varphi_n^{\rm CG}(\lambda)$

$$\begin{aligned} \|\mathbf{x} - \mathbf{x}_n\|_{\mathbf{A}}^2 &= \min_{\varphi \in \Pi_n} \|\varphi(\mathbf{A})(\mathbf{x} - \mathbf{x}_0)\|_{\mathbf{A}}^2 \\ &= \sum_{j=1}^N \lambda_j \, \zeta_j^2 \, \varphi_n^{\mathrm{CG}}(\lambda_j)^2 \,, \quad j = 1, 2, \dots \end{aligned}$$

Here

$$\varphi_n^{\rm CG}(\lambda) = \frac{(\lambda - \theta_1^{(n)}) \cdots (\lambda - \theta_n^{(n)})}{(-1)^n \, \theta_1^{(n)} \cdots \theta_n^{(n)}}$$

is determined by the eigenvalues of the orthogonally restricted operator, i.e., by the eigenvalues $\theta_1^{(n)}, \ldots, \theta_n^{(n)}$ of \mathbf{T}_n (Ritz values).

1 CG (Lanczos) and Gauss quadrature

Let $\omega^{(n)}(\lambda)$ be the distribution function determined by the *n*-node Gauss quadrature approximation of the Riemann-Stieltjes integral with the distribution function $\omega(\lambda)$ determined by the SPD matrix A and r_0 . Then



The quadrature nodes $\lambda_j^{(n)}$ are the eigenvalues $\theta_j^{(n)}$ of \mathbf{T}_n and the weights $\omega_j^{(n)}$ are the squared first components of the associated normalized eigenvectors.

At any iteration step n, CG represents the matrix formulation of the *n*-point Gauss quadrature of the Riemann-Stieljes integral determined by **A** and \mathbf{r}_0 ,

$$\int_0^\infty \phi(\lambda) \, d\omega(\lambda) = \sum_{i=1}^n \omega_i^{(n)} \phi(\theta_i^{(n)}) + R_n(\phi) \, .$$

For the function $\phi(\lambda) \equiv \lambda^{-1}$,

$$\frac{\|\mathbf{x} - \mathbf{x}_0\|_{\mathbf{A}}^2}{\|\mathbf{r}_0\|^2} = n \text{-th Gauss quadrature} + \frac{\|\mathbf{x} - \mathbf{x}_n\|_{\mathbf{A}}^2}{\|\mathbf{r}_0\|^2}.$$

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This has become the basis for CG error estimation; see Golub, 1994; and, e.g., the surveys in S and Tichý, 2002; Meurant and S, 2006; Golub and Meurant, 2010; Liesen and S, 2013.

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Paige (1971-80), Greenbaum (1989), Parlett (1990), S (1991), Greenbaum and S (1992), Notay (1993), ..., Druskin, Kniznermann, Zemke, Wülling, Meurant,

Recent reviews and updates in Meurant and S, Acta Numerica (2006); Meurant (2006); Liesen and S (2013).

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Now back to our motivating example.



1 Linear "description" of the nonlinear CG method

• The CG optimality property

$$\|\mathbf{x} - \mathbf{x}_n\|_{\mathbf{A}} = \min_{\mathbf{z} \in \mathbf{x}_0 + \mathcal{K}_n(\mathbf{A}, \mathbf{r}_0)} \|\mathbf{x} - \mathbf{z}\|_{\mathbf{A}} = \min_{\varphi \in \Pi_n} \|\varphi(\mathbf{A})(\mathbf{x} - \mathbf{x}_0)\|_{\mathbf{A}}$$

yields in two derivation steps the (worst case) linear convergence bound valid and relevant for the Chebyshev method

$$\frac{\|\mathbf{x} - \mathbf{x}_n\|_{\mathbf{A}}}{\|\mathbf{x} - \mathbf{x}_0\|_{\mathbf{A}}} \le \min_{\varphi \in \Pi_n} \max_{1 \le j \le N} |\varphi(\lambda_j)| \le \min_{p \in \Pi} \max_{\lambda \in [\lambda_1, \lambda_N]} |p(\lambda)|$$
$$\le 2 \left(\frac{\sqrt{\kappa(\mathbf{A})} - 1}{\sqrt{\kappa(\mathbf{A})} + 1}\right)^n, \quad \kappa(\mathbf{A}) = \frac{\lambda_N}{\lambda_1}.$$

• The worst-case nonlinear bound is completely determined by the distribution of the eigenvalues of **A**.

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$$\begin{aligned} \frac{\|\mathbf{x} - \mathbf{x}_n\|_{\mathbf{A}}}{\|\mathbf{x} - \mathbf{x}_0\|_{\mathbf{A}}} &\leq \min_{\varphi \in \Pi_n} \max_{1 \leq j \leq N} |\varphi(\lambda_j)| \leq \min_{p \in \Pi} \max_{\lambda \in [\lambda_1, \lambda_N]} |p(\lambda)| \\ &\leq 2 \left(\frac{\sqrt{\kappa(\mathbf{A})} - 1}{\sqrt{\kappa(\mathbf{A})} + 1}\right)^n, \quad \kappa(\mathbf{A}) = \frac{\lambda_N}{\lambda_1}. \end{aligned}$$

• The worst-case nonlinear bound is completely determined by the distribution of the eigenvalues of **A**.

1 Spectra and distribution functions for preconditioned systems



1 Various parts of the spectra and convergence behavior





Index	1 - 1922	1923	1924	1925	1926
Eigenvalues	1	28.508	61.384	75.324	$\lambda_{1926}^{\mathbf{L}} = 79.699$
Total weight	9×10^{-6}	$\approx 10^{-3}$	$\approx 10^{-3}$	$\approx 10^{-3}$	$\approx 10^{-3}$
Index	1927 - 1930	1931 - 2039	2040 - 2047		2048 - 3969
Eigenvalues	80.875 - 81.222	$\lambda_{2039}^{\mathbf{L}} = 81.224$	81.226 - 133.94		161.45
Total weight	$\approx 10^{-3}$	1.8×10^{-2}	8×10^{-10}		0.96



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Consider the scalar real valued bounded and uniformly positive function $k(x): \mathbb{R}^d \to \mathbb{R}$ and the generalized eigenvalue problem

$$\nabla \cdot (k(x)\nabla u) = \lambda \,\Delta u \quad \text{in } \Omega \subset \mathbb{R}^d,$$
$$u = 0 \qquad \text{on } \partial\Omega.$$

Then

 $k(x) \in \operatorname{sp}(\mathcal{L}^{-1}\mathcal{A})$

for all $x \in \Omega$ at which k(x) is continuous, where

$$\begin{aligned} \mathcal{A} &: H_0^1(\Omega) \mapsto H^{-1}(\Omega), \quad \langle \mathcal{A}u, v \rangle = \int_{\Omega} k \nabla u \cdot \nabla v, \quad u, v \in H_0^1(\Omega), \\ \mathcal{L} &: H_0^1(\Omega) \mapsto H^{-1}(\Omega), \quad \langle \mathcal{L}u, v \rangle = \int_{\Omega} \nabla u \cdot \nabla v, \quad u, v \in H_0^1(\Omega). \end{aligned}$$

Consider a standard conforming FE discretization (d = 1, 2 or 3), which yields the generalized eigenvalue problem in the form

$$\mathbf{A}\mathbf{v} = \lambda \mathbf{L}\mathbf{v}.$$

Based on numerical observations, the authors conjecture that the spectrum of the discretized preconditioned algebraic operator

$\mathbf{L}^{-1}\mathbf{A}$

can be approximated by the nodal values of k(x).

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Pairing the eigenvalues and the intervals $k(\mathcal{T}_j), j = 1, ..., N$.

Let $0 < \lambda_1 \leq \lambda_2 \leq \ldots \leq \lambda_N$ be the eigenvalues of $\mathbf{L}^{-1}\mathbf{A}$. Let k(x) be bounded and piecewise continuous. Then there exists a (possibly non-unique) permutation π such that the eigenvalues of the matrix $\mathbf{L}^{-1}\mathbf{A}$ satisfy

$$\lambda_{\pi(j)} \in k(\mathcal{T}_j), \quad j = 1, \dots, N,$$

where

$$k(\mathcal{T}_j) \equiv \left[\inf_{x \in \mathcal{T}_j} k(x), \sup_{x \in \mathcal{T}_j} k(x)\right], \quad \mathcal{T}_j = \operatorname{supp}(\phi_j), \quad j = 1, \dots, N.$$

Pairing the eigenvalues and the nodal values

Consider any point \hat{x}_j such that $\hat{x}_j \in \mathcal{T}_j$. Then the associated eigenvalue $\lambda_{\pi(j)}$ of the matrix $\mathbf{L}^{-1}\mathbf{A}$ satisfies

$$|\lambda_{\pi(j)} - k(\hat{x}_j)| \leq \sup_{x \in \mathcal{T}_j} |k(x) - k(\hat{x}_j)|, \quad j = 1, \dots, N.$$

If, in addition, $k(x) \in C^2(\mathcal{T}_j)$, then

$$\begin{aligned} |\lambda_{\pi(j)} - k(\hat{x}_j)| &\leq \sup_{x \in \mathcal{T}_j} |k(x) - k(\hat{x}_j)| \\ &\leq \hat{h} \|\nabla k(\hat{x}_j)\| + \frac{1}{2} \hat{h}^2 \sup_{x \in \mathcal{T}_j} \|D^2 k(x)\|, \quad j = 1, \dots, N, \end{aligned}$$
(1)

where $\hat{h} = \operatorname{diam}(\mathcal{T}_j)$ and $D^2k(x)$ is the second order derivative of k(x).

3 Numerical illustration, 4 problems, nodal values, N = 81





3 Correct pairing illustrating proved results



Here we use discontinuous function k(x, y), (problem P4 in the paper).

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Consider the generalized eigenvalue problem

$$\nabla \cdot (K\nabla u) = \lambda \Delta u \quad \text{in } \Omega,$$
$$u = 0 \qquad \text{on } \partial \Omega.$$

Here the real valued tensor function $K(x,y): \Omega \to \mathbb{R}^{2 \times 2}$ is symmetric with its entries being bounded Lebesgue integrable functions and with the spectral decomposition

$$K(x,y) = Q(x,y) \Lambda(x,y) Q^{T}(x,y), \quad (x,y) \in \Omega,$$

where

$$\Lambda(x,y) = \begin{bmatrix} \kappa_1(x,y) & 0\\ 0 & \kappa_2(x,y) \end{bmatrix}, \quad QQ^T = Q^TQ = I.$$

Spectrum of the infinite dimensional preconditioned operator

Consider an open and bounded Lipschitz domain $\Omega \subset \mathbb{R}^2$. Assume that the tensor K(x, y) is symmetric and continuous throughout the closure $\overline{\Omega}$. Then the spectrum of the operator $\mathcal{L}^{-1}\mathcal{A}$ equals

$$\operatorname{sp}(\mathcal{L}^{-1}\mathcal{A}) = \operatorname{Conv}(\kappa_1(\overline{\Omega}) \cup \kappa_2(\overline{\Omega})),$$

where

$$\operatorname{Conv}(\kappa_1(\overline{\Omega}) \cup \kappa_2(\overline{\Omega})) = \left[\inf_{(x,y)\in\overline{\Omega}} \min_{i=1,2} \kappa_i(x,y)\right], \sup_{(x,y)\in\overline{\Omega}} \max_{i=1,2} \kappa_i(x,y)\right].$$

4 Eigenvalues of the discretized problems P1 - P3 in the paper



P1: constant $\kappa_1 \neq \kappa_1$ P2: non overlapping $\kappa_1(\overline{\Omega}), \kappa_2(\overline{\Omega})$ P3: overlapping $\kappa_1(\overline{\Omega}), \kappa_2(\overline{\Omega})$

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- Eigenvalues in the spectrum of the infinite dimensional operator?
- Discretized tensor case?
- Extension to 3D?
- Generalizations and preconditioning for practical problems?

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Faber, Manteuffel and Parter, On the theory of equivalent operators and application to the numerical solution of uniformly elliptic partial differential equations, Advances in Applied Mathematics 11, 109–163 (1990):

"This work is motivated by the desire to construct a preconditioning strategy that yields bounds independent of the mesh parameter h. This leads to the conclusion that while equivalence [of operators] may be necessary to yield bounds independent of h, it is by no means sufficient to produce a good preconditioning strategy."

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Málek, S, Preconditioning and the Conjugate Gradient Method in the Context of Solving PDEs, SIAM Spotlights, SIAM (2015), Chapter 13:

"Here we do not argue against using condition numbers ... where appropriate. We argue against using them as general unquestioned tools which are considered fully descriptive ... as arguments closing the door for further investigation." "We will go on pondering and meditating, the great mysteries still ahead of us, we will err and stumble on the way, and if we win a little victory, we will be jubilant and thankful, without claiming, however, that we have done something that can eliminate the contribution of all the millenia before us." "There remains this: we beech the skilled in these things, that we thought worth showing, they will think openly receiving, an whatever it hides, worth imparting more properly by themselves to the wider mathematical community."

Thank you very much for your kind patience!

