

Data Depth

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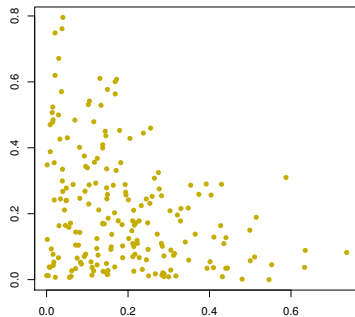
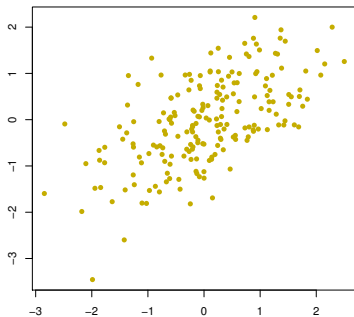
- 1 Depth Measure and its Smoothness for Multivariate Data
 - Smoothness of Halfspace Depth Contours
- 2 Functional Data Depth: Theory
 - Functional Band Depths
 - Consistency
 - Counterexample
 - Fixing the Continuousness
 - Integral and Vector Depths
- 3 Functional Data Depth: Practice
 - Problem of Functional Data Classification
 - Using Depth for Classification
 - Simulation Study
- 4 Conclusions

Outline

- 1 **Depth Measure and its Smoothness for Multivariate Data**
 - Smoothness of Halfspace Depth Contours
- 2 **Functional Data Depth: Theory**
 - Functional Band Depths
 - Consistency
 - Counterexample
 - Fixing the Continuousness
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- 3 **Functional Data Depth: Practice**
 - Problem of Functional Data Classification
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 - Simulation Study
- 4 **Conclusions**

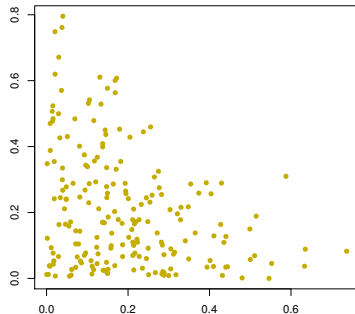
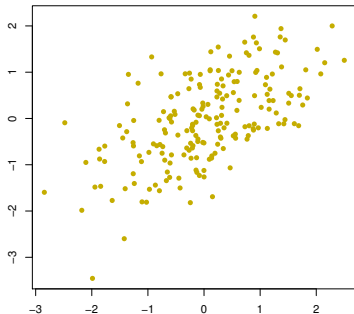
Data Depth

Consider a random variable $X \sim P \in \mathcal{P}(\mathbb{R}^d)$.



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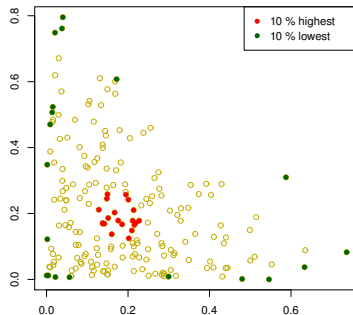
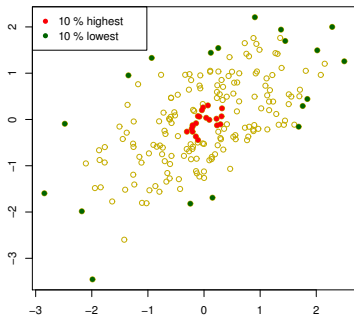
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How to **define ordering** of these data?

Data Depth

Consider a random variable $X \sim P \in \mathcal{P}(\mathbb{R}^d)$.



Using **data depth**!

Depth Generally

According to Zuo and Serfling [13], **Statistical depth** is a function possessing:

- affine transformation **invariance**
- **maximality at the center of symmetry** of the distribution for the class of symmetric distributions
- **monotonicity** relative to the point with the highest depth
- **vanishing** at infinity

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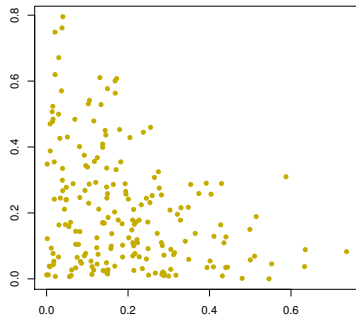
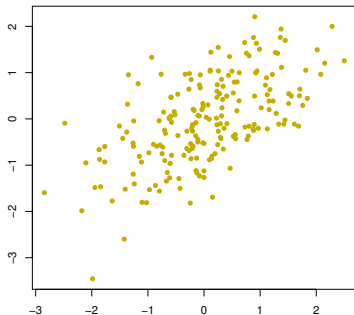
- affine transformation **invariance**
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We obtain a function recognizing “typical” and “outlier” observations, a **generalization of quantiles** for multivariate data.

Halfspace Depth

Halfspace depth (Tukey [11]) HD of an observation from \mathbb{R}^d

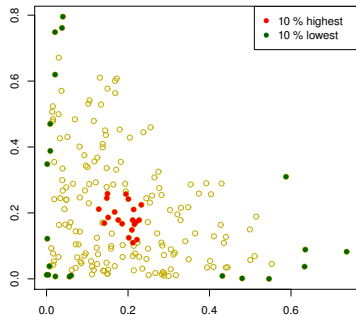
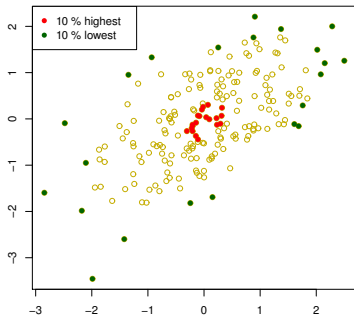
$$HD(x; P) = \inf_{H \in \mathcal{H}(x)} P(X \in H)$$



Halfspace Depth

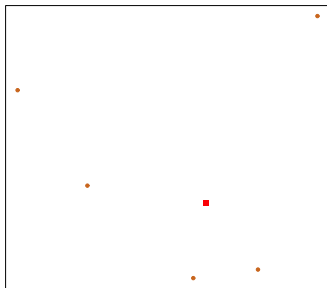
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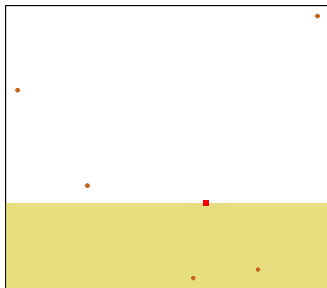
Halfspace Depth

$HD(x; X_1, \dots, X_n) =$ least ratio of observations in a halfspace containing x



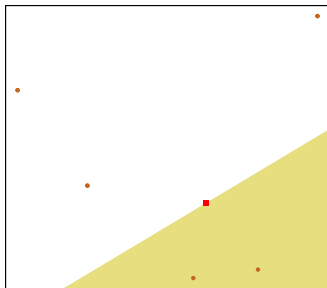
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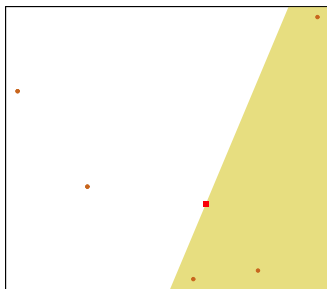
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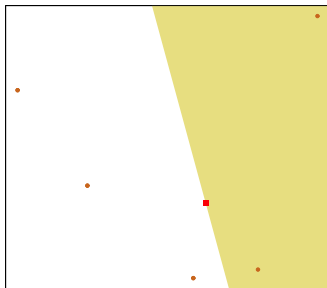
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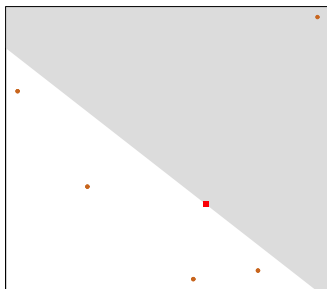
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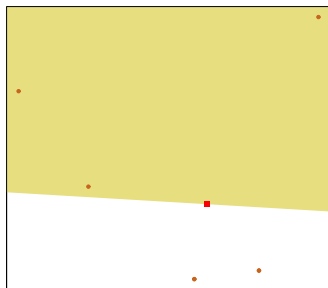
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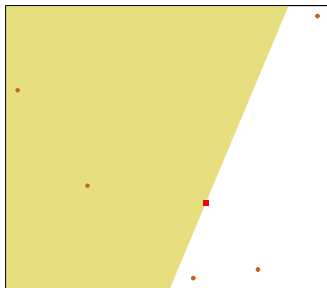
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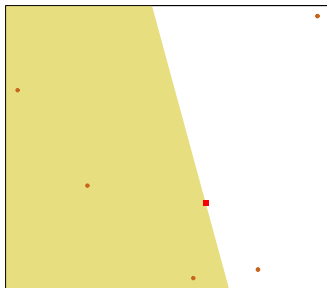
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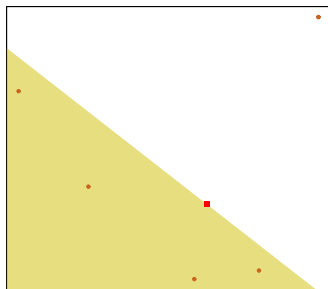
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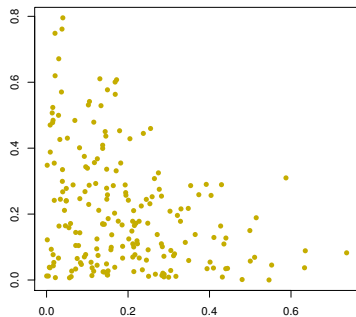
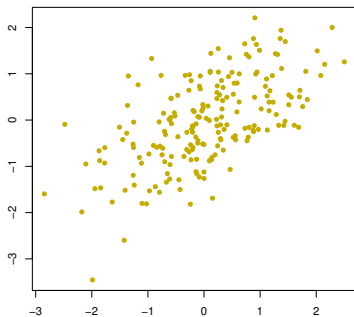
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Simplicial Depth

Simplicial depth (Liu [7]) SD of an observation from \mathbb{R}^d

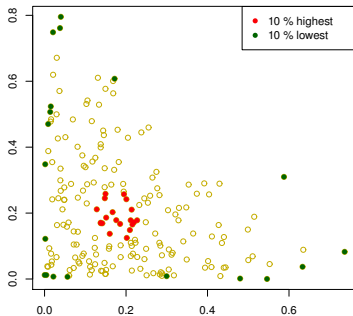
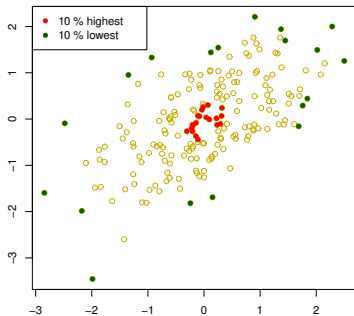
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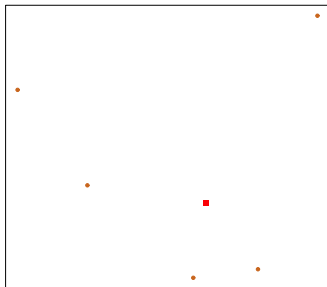
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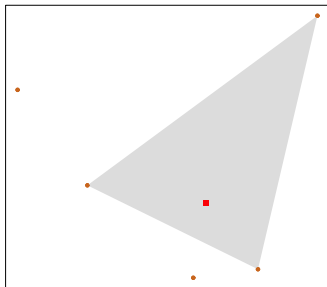
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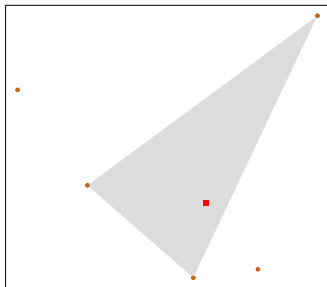
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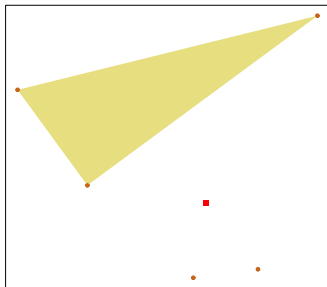
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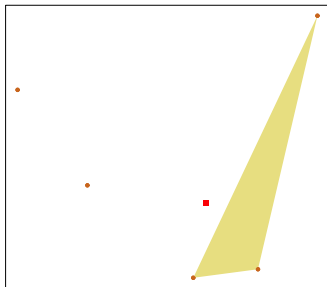
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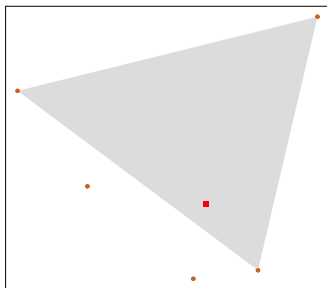
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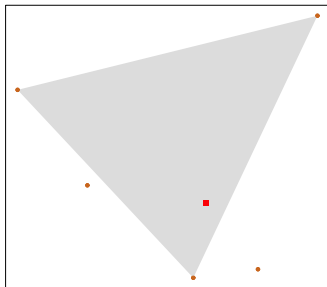
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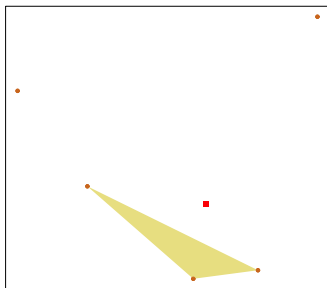
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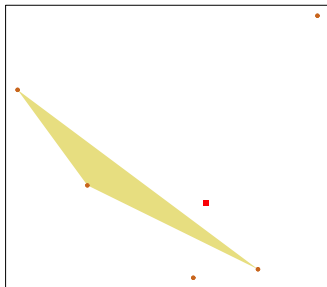
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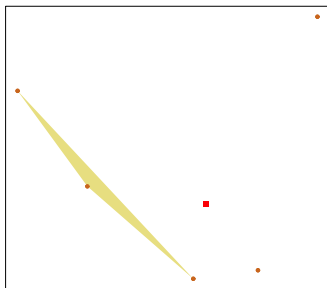
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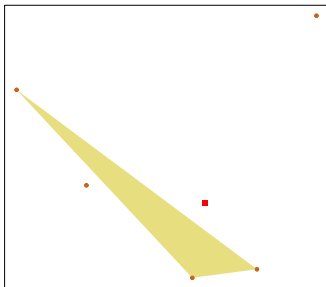
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Characterization of Distribution

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Yes, if

- P is an **empirical measure** (Struyf and Rousseeuw 1999),
- P is **a.c. with a compact support** (Koshevoy 2001),
- P is **atomic** (Koshevoy 2002)
- P has a $C^{(2)}$ **density** (Hassairi and Regaieg 2008),
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When are HD contours smooth?

When are Halfspace Depth Contours Smooth?

Theorem:

Let $P \in \mathcal{P}(\mathbb{R}^d)$ be contiguous and $x \in \mathbb{R}^d$. Then the halfspace depth contours are smooth at x if and only if there exists a unique halfspace $H \in \mathcal{H}(x)$ such that

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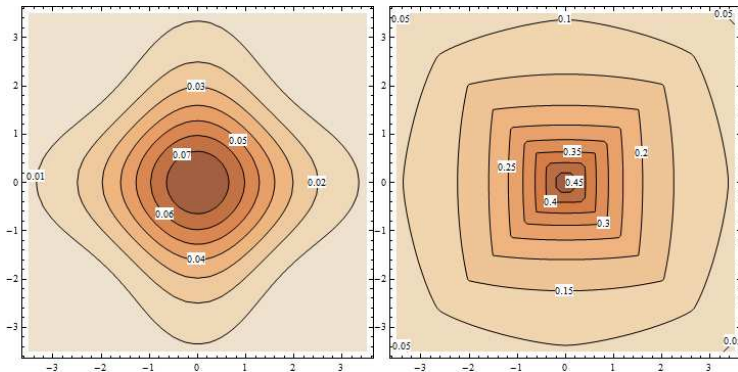
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As a corollary, a point x from the hyperspace of reflectional symmetry R of P is depth regular (depth contours at x are smooth) if and only if **HD is attained only at a halfspace orthogonal to R .**

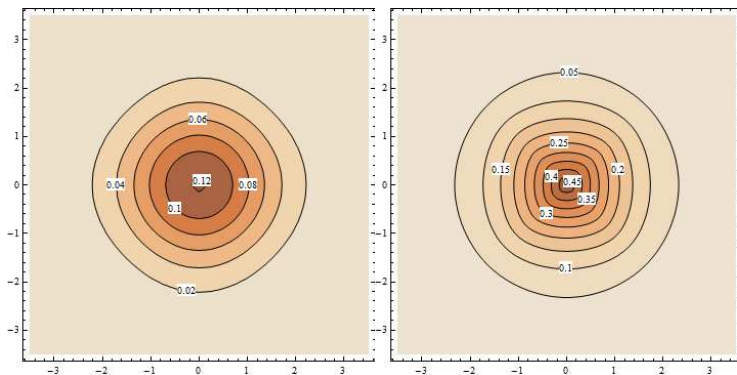
Example 1: Gaussian Distributions Mixture

A **strictly unimodal** distribution and non-smooth *HD* contours.



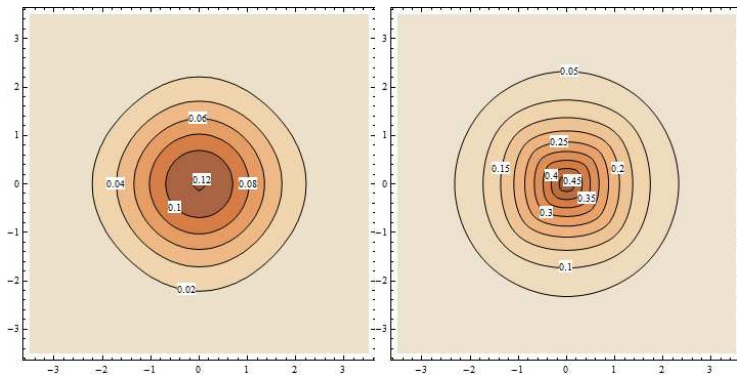
Example 2: Gaussian Distributions Mixture

Another **strictly unimodal** distribution.



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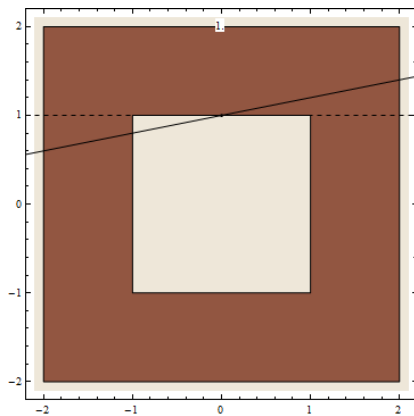
Another **strictly unimodal** distribution.



Is non-smooth **only for $\sigma_1^2 > \sigma_2^2(2 + \sqrt{3})$** .

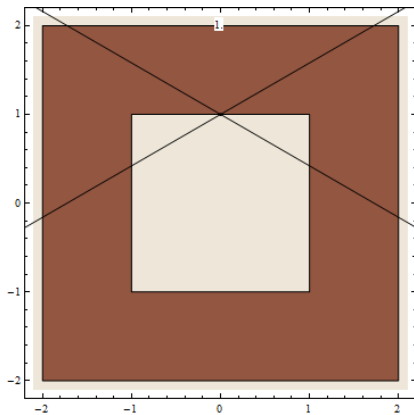
Example 3: Rectangle

A distribution with non-smooth HD contours.



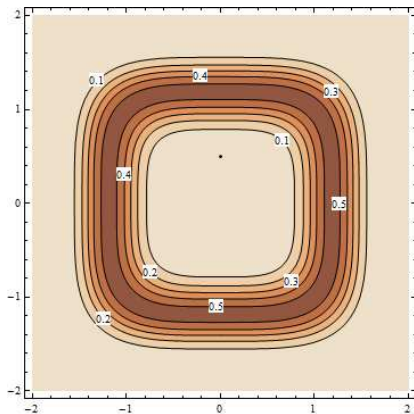
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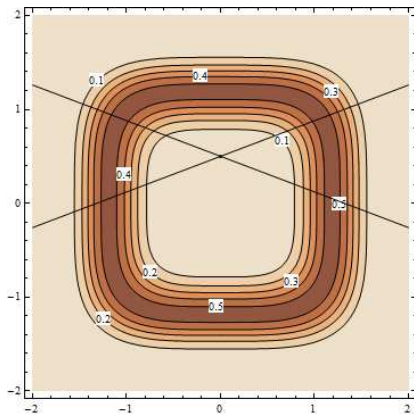
Example 4: L^4 symmetrical distribution

An L^4 **symmetrical** distribution with non-smooth HD contours.



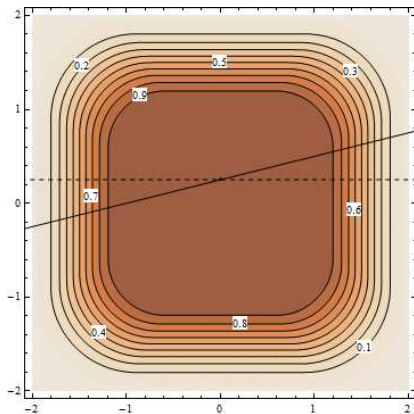
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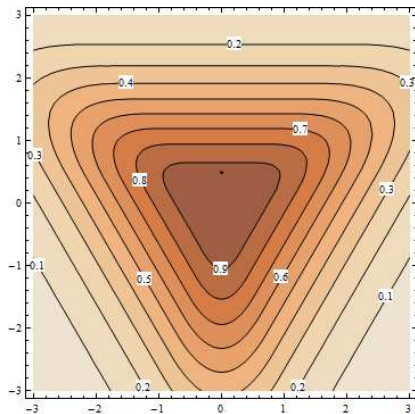
Example 5: quasi-concave distribution 1

A **quasi-concave** distribution with non-smooth HD contours.



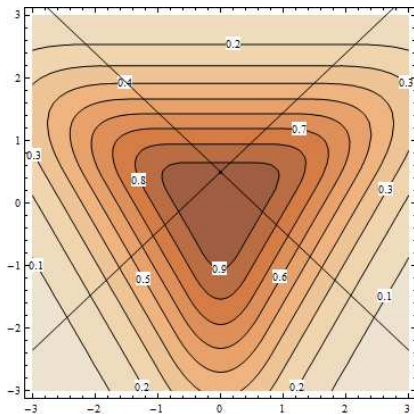
Example 6: quasi-concave distribution 2

A **strictly quasi-concave** distribution with non-smooth HD contours.



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Smooth Halfspace Depth Contours: Conclusions

Conclusion

Not even the density smoothness, strict quasi-concavity and reflectional symmetry suffices for the halfspace depth contours to be smooth at every point of \mathbb{R}^d .

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Not even the density smoothness, strict quasi-concavity and reflectional symmetry suffices for the halfspace depth contours to be smooth at every point of \mathbb{R}^d .

Can this be guaranteed at least for even **smaller classes of distributions**?

- **angularly symmetrical** and strictly quasi-concave, or merely
- **L^p symmetrical** and strictly quasi-concave?

For further discussion, see Nagy [9].

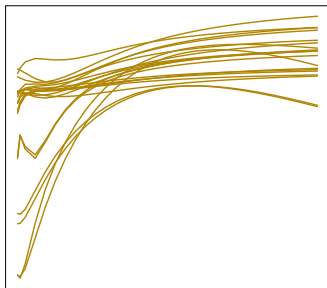
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Functional Data

$X \sim P \in \mathcal{P}(C([0, 1]))$ and X_1, \dots, X_n a r.s. from P . Consider the depth of functional observations w.r.t. P (or P_n)

$$D: C([0, 1]) \times \mathcal{P}(C([0, 1])) \rightarrow [0, 1].$$

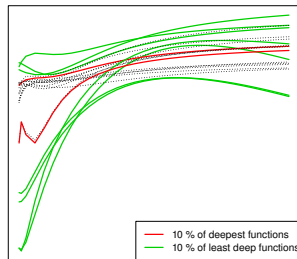
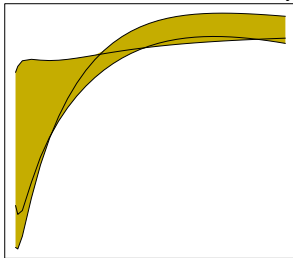


Band Depth

López-Pintado and Romo [8] for $J = 2, 3, \dots$

$$BD^J(x; P) = \frac{1}{J-1} \sum_{j=2}^J P[G(x) \subset B(x_1, x_2, \dots, x_j)],$$

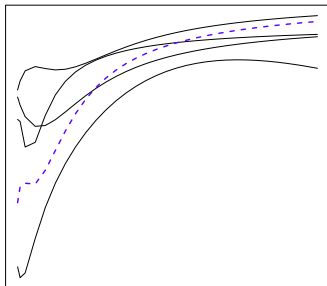
where $G(x)$ is **the graph of a function** x and $B(x_1, x_2, \dots, x_j)$ is a **band of functions** x_1, x_2, \dots, x_j



Band Depth

The sample version is a **U-statistic of order J** .

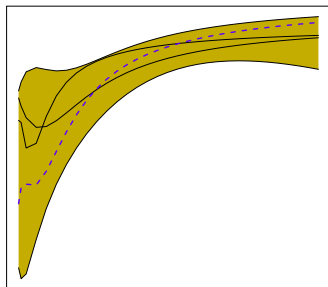
$$BD^{(J)}(x; P_n) = \frac{1}{J-1} \sum_{j=2}^J \binom{n}{j}^{-1} \sum_{1 \leq i_1 < i_2 < \dots < i_j \leq n} \mathbb{I}[G(x) \subset B(X_{i_1}, X_{i_2}, \dots, X_{i_j})].$$



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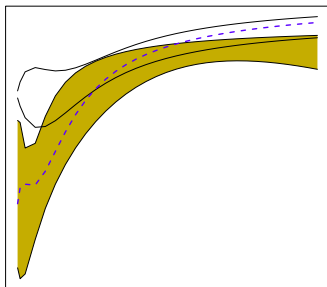
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Strong Consistency

Depth D is on a set $S \subset \mathcal{C}([0, 1])$ **consistent**

- **pointwise** if

$$D(x; P_n) - D(x; P) \xrightarrow[n \rightarrow \infty]{a.s.} 0 \text{ for all } x \in S,$$

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$$\sup_{x \in S} |D(x; P_n) - D(x; P)| \xrightarrow[n \rightarrow \infty]{\text{a.s.}} 0 \text{ for all } P \in \mathcal{P}(\mathcal{C}([0, 1])),$$

Strong Consistency

Depth D is on a set $S \subset C([0, 1])$ **consistent**

- **pointwise** if

$$D(x; P_n) - D(x; P) \xrightarrow[n \rightarrow \infty]{\text{a.s.}} 0 \text{ for all } x \in S,$$

- **uniformly** if

$$\sup_{x \in S} |D(x; P_n) - D(x; P)| \xrightarrow[n \rightarrow \infty]{\text{a.s.}} 0,$$

- **universally** if

$$\sup_{x \in S} |D(x; P_n) - D(x; P)| \xrightarrow[n \rightarrow \infty]{\text{a.s.}} 0 \text{ for all } P \in \mathcal{P}(C([0, 1])),$$

- **\mathcal{P} -uniformly** if

$$\sup_{P \in \mathcal{P}(C([0, 1]))} \sup_{x \in S} |D(x; P_n) - D(x; P)| \xrightarrow[n \rightarrow \infty]{\text{a.s.}} 0.$$

Band Depth

Band Depth (L-P López-Pintado, R Romo):

- L-P, R: Depth-based classification for functional data (DIMACS 2006)
- L-P, R: Depth-based inference for functional data (CSDA 2007)
- L-P, Jornsten: Functional analysis via extensions of the band depth (IMS Lecture Notes, 2007)
- **L-P, R: On the Concept of Depth for Functional Data (JASA 2009)**
- L-P, R: Robust depth-based tools for the analysis of gene expression data (Biostatistics 2010)
- L-P, R: A half-region depth for functional data (CSDA 2011)
- ...

Band Depth Consistency

López-Pintado and Romo [8, Thm 4]

Theorem:

Let $P \in \mathcal{P}(\mathcal{C}([0, 1]))$ with a.c. marginals. Then BD^J is uniformly consistent on every equi-continuous set S , i.e.

$$\sup_{x \in S} \left| BD^J(x; P_n) - BD^J(x; P) \right| \xrightarrow[n \rightarrow \infty]{\text{a.s.}} 0.$$

Band Depth Consistency: Proof

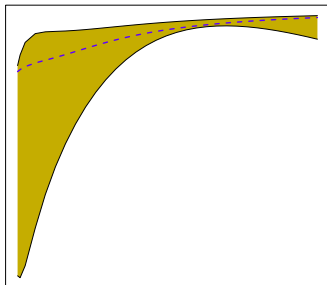
Proof: As $\lim_{\|x\| \rightarrow \infty} BD^J(x; P) = 0$, consider only $\{\|x\| < M\}$ for $M > 0$. According to Arzela-Ascoli's Theorem, a uniformly bounded set of equi-continuous functions is totally bounded. Because $BD^J(\cdot; P)$ is for P with a.c. marginals **a continuous functional**, **it is enough to prove** for $N \in \mathbb{N}$ fixed

$$\max_{\{x_i\}_{i=1}^N \subset S} \left| BD^J(x_i; P_n) - BD^J(x_i; P) \right| \xrightarrow[n \rightarrow \infty]{a.s.} 0.$$

This holds, since $BD^J(\cdot; P_n)$ is a bounded U-statistic. □

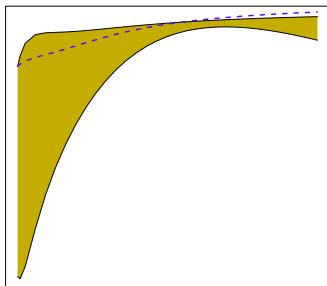
Why the Proof Does Not Work?

$BD^{(j)}(\cdot; P)$ is continuous, but $BD^{(j)}(\cdot; P_n)$ **is not!**



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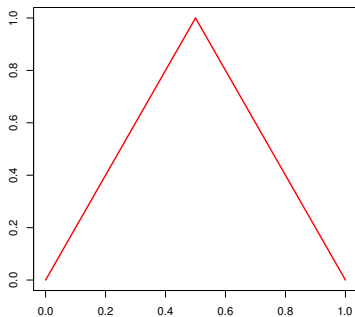
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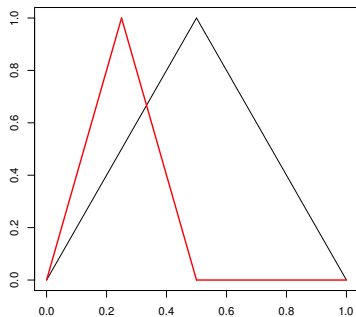
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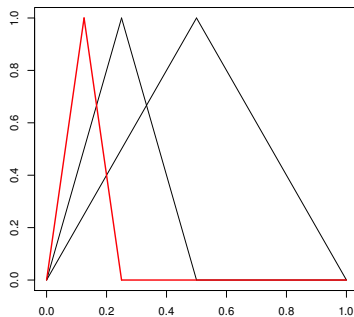
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Is Band Depth Consistent?

Starting from the theory of **empirical processes** (for $J = 2$):

- The validity of

$$\dim_{\text{VC}} \{(x_1, x_2) \mid G(x) \subset B(x_1, x_2)\}_{x \in S} = \infty$$

for $S \subset C([0, 1])$ compact suggests, that the depth **is not \mathcal{P} -uniformly consistent** (Assouad's Thm - [3, Thm 6.4.5]).

- The existence of **boolean σ -independent sequence** of functions in the class

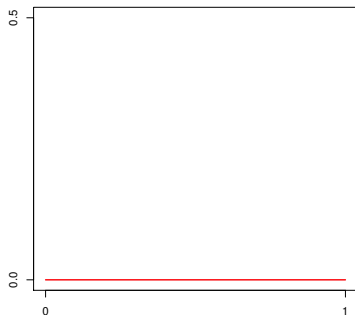
$$\{(x_1, x_2) \mid G(x) \subset B(x_1, x_2)\}_{x \in S}$$

suggest, that the depth **is not universally consistent** (van Handel's Thm - [12, Thm 1.3]).

Band Depth Consistence: Counterexample

Define $X \sim P \in \mathcal{P}(C([0, 1]))$ as follows:

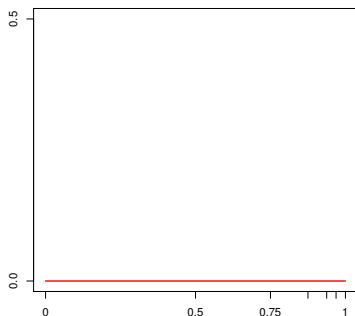
- $P(X(t) = 0 \text{ for all } t \in [0, 1]) = 0.5$.



Band Depth Consistence: Counterexample

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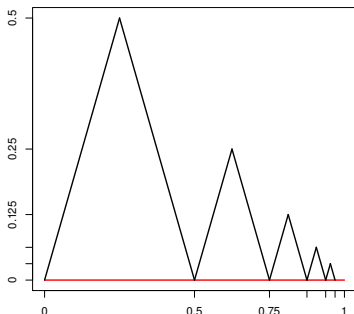
- Divide the interval $[0, 1]$ “diadically” into disjoint subintervals I_j of lengths $\{2^{-j}\}_{j \in \mathbb{N}}$.



Band Depth Consistence: Counterexample

Define $X \sim P \in \mathcal{P}(C([0, 1]))$ as follows:

- If $X \neq 0$, set X zero on every I_j with probability 0.5 or have a jump with probability 0.5. The jumps occur independently.



Band Depth Consistence: Counterexample

Let x_j be a function with **a single jump** on the interval I_j , 0 otherwise.
Then:

- $BD^2(x_j; P) = 0.25$ for all $j \in \mathbb{N}$

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$$\binom{n}{2} - 2 \binom{n/2}{2} = \frac{n^2}{4}$$

bands.

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- For such a j_n we have

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Thus, BD^2 is **not uniformly consistent** w.r.t. P .

Fixing the Continuousness

The problem of López-Pinado and Romo's proof was that the depth $BD^{(j)}(\cdot; P_n)$ was not (uniformly) continuous. Instead of measuring the outlyingness of a function from a band by an indicator, let's measure **distance from a band**, i.e. for a metric d on $C([0, 1])$ use

$$E[1 - w(d(x; B(X_1, X_2)))]$$

instead of

$$P[G(x) \subset B(X_1, X_2)] = E[\mathbb{I}[G(x) \subset B(X_1, X_2)]],$$

where $w: [0, \infty) \rightarrow [0, 1]$, $w(0) = 1$, $\lim_{t \rightarrow \infty} w(t) = 0$ is equi-continuous **smoothing function**, e.g. e^{-t} .

Consider supremum and L_1 metric for simplicity.

Fixing the Continuousness

Theorem:

Let w be a smoothing function and $S \subset C([0, 1])$ relatively compact. Then the band depths smoothed by w

$$BD^{(j)}(\cdot; \cdot, w, d) : C([0, 1]) \times \mathcal{P}(C([0, 1])) \rightarrow [0, 1]$$

are for supremum norm, as well as for L_1 norm \mathcal{P} -uniformly consistent on S .

Proof: A strengthened version of López-Pintado and Romo's proof is used. It is proved that the class

$$\left\{ BD^{(j)}(x; P, w, d) \mid x \in C([0, 1]), P \in \mathcal{P}(C([0, 1])) \right\}$$

is uniformly continuous and the properties of U-statistics are utilized (Borovskich and Koroljuk [6, Thm 2.1.4]).

Frainman-Muniz Type of Depth

Frainman and Muniz [4]

$$ID(x; P) = \int_0^1 D(x(t); P_t) dt,$$

where D is univariate “depth” like

- **halfspace depth**

$$D(x(t); P_t) = \min \{F_t(x(t)), 1 - F_t(x(t))\},$$

- **simplicial depth**

$$D(x(t); P_t) = F_t(x(t))(1 - F_t(x(t))).$$

Generalization of Fraiman-Muniz Type of Depth

The idea of Fraiman and Muniz may be easily generalized to **vector-valued functions**

$$ID(x; P) = \int_0^1 D(x(t); P_t) dt,$$

where D is usual multivariate depth,

$$x = (x_1, \dots, x_K), \text{ where } x_k: [0, 1] \rightarrow \mathbb{R}$$

and $P \in \mathcal{P}(C([0, 1])^K)$.

This is how we define **K -vector depths** and by application to differentiable functions also **K -derivatives depths** (Hlubinka and Nagy [5]).

Integral Depths Consistency

Theorem:

Let the sample version of a depth $D: \mathbb{R}^d \times \mathcal{P}(\mathbb{R}^d) \rightarrow [0, 1]$ have a form of a U-statistic and be universally consistent. Then the depth for vector-valued functions

$$ID(x; P) = \int_0^1 D(x(t); P_t) dt$$

is universally consistent on $C([0, 1])^d$, under some measurability assumptions.

Proof: Utilizing Lebesgue dominated convergence Theorem we obtain weak universal consistency, which is for U-processes equivalent to (strong) universal consistency (cf. de la Peña a Giné [2, p.227]). \square

The Theorem can be applied for example for **simplicial depth** as D .

Other Properties of Integral Depths

A range of **other properties** of integral depth for vector-valued functions can be proved (Nagy and Hlubinka [10]):

- **measurability** as a functional on $\mathcal{C}([0, 1])^K \times \mathcal{P}(\mathcal{C}([0, 1])^K)$,

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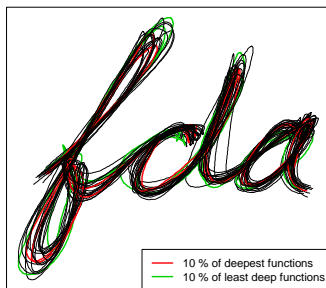
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- functional version of **affine invariance** for ID and dID ,
- **monotonicity relative to the deepest point**,
- **continuity** (or **semicontinuity**) as functional of $x \in C([0, 1])^K$,
- **qualitative robustness**, i.e. continuity as a functional of $P \in \mathcal{P}(C([0, 1])^K)$ in the weak convergence sense.

K-Vector Depth

Integral depths for vector functions

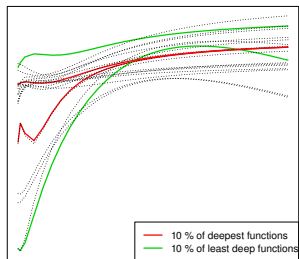
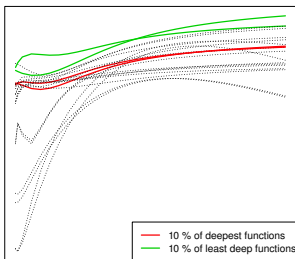
$$ID(x; P) = \int_0^1 D((x_1(t), x_2(t)); (P_{1,t}, P_{2,t})) dt,$$



K-Derivatives Depth

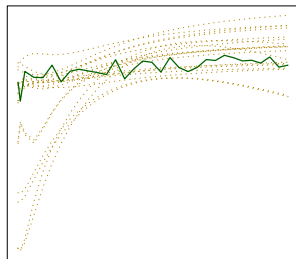
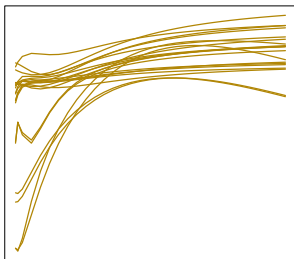
Integral depths for differentiable functions

$$dID(x; P) = \int_0^1 D((x(t), x'(t)); (P_t, P'_t)) dt,$$



Contaminated Dataset

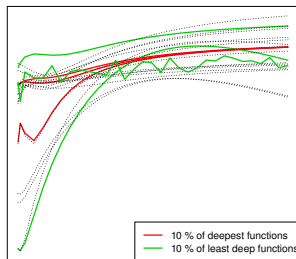
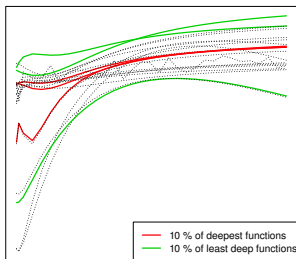
Consider now the **contaminated functional dataset**. Does the depth recognize the outlier?



K-Derivatives Depth Again

Integral depths for differentiable functions

$$dID(x; P) = \int_0^1 D((x(t), x'(t)); (P_t, P'_t)) dt,$$



Future Challenges

- Generalization of van Handel's (Assouad's) Theorem for U-processes.
- **\mathcal{P} -uniform consistency of integral depths.**

$$P_\gamma - \dim \{ \lambda [t | x(t) \in B(x_1(t), x_2(t))] \}_{x \in S} = \infty \quad \forall \gamma > 0$$

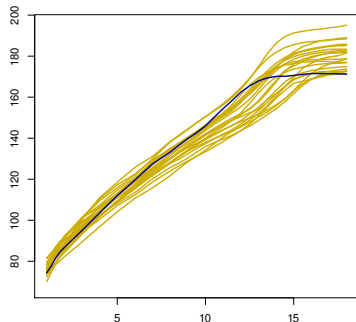
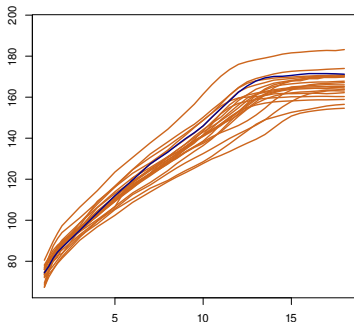
for $S \subset C([0, 1])$ compact suggests, that the depth **is not \mathcal{P} -uniformly consistent** (Alon's Thm) [1, Thm 2.2]).

Outline

- 1 **Depth Measure and its Smoothness for Multivariate Data**
 - Smoothness of Halfspace Depth Contours
- 2 **Functional Data Depth: Theory**
 - Functional Band Depths
 - Consistency
 - Counterexample
 - Fixing the Continuousness
 - Integral and Vector Depths
- 3 **Functional Data Depth: Practice**
 - Problem of Functional Data Classification
 - Using Depth for Classification
 - Simulation Study
- 4 **Conclusions**

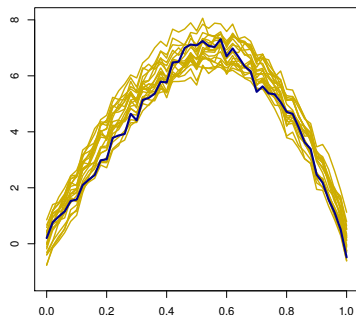
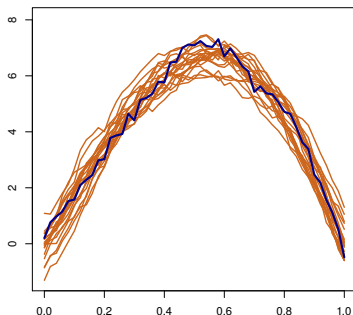
Determining the Distribution: Children's Growth Data

Let $P_1, P_2 \in \mathcal{P}(C([0, 1]))$ and $X \sim P_m$, $m \in \{1, 2\}$ is unknown. What is the distribution of X ?



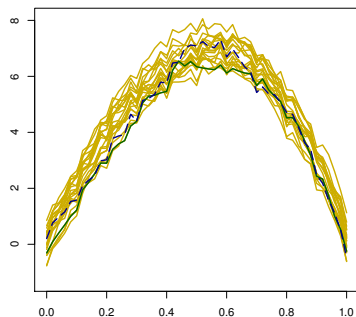
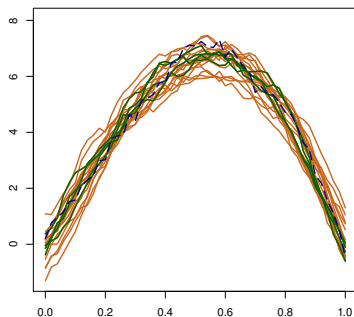
Determining the Distribution: a More Difficult Example

Let $P_1, P_2 \in \mathcal{P}(C([0, 1]))$ and $X \sim P_m$, $m \in \{1, 2\}$ is unknown. What is the distribution of X ?



Nearest Neighbor Rule

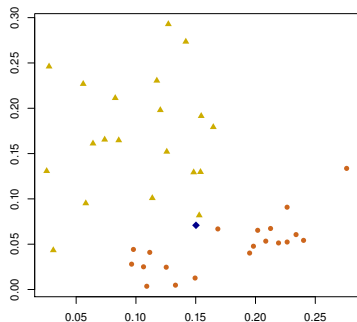
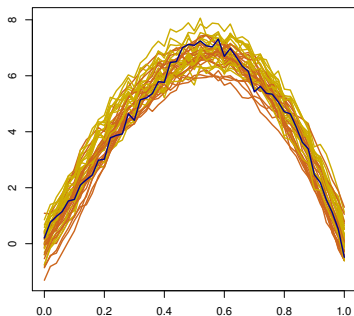
The k -nearest neighbor rule KNN with respect to a particular metric on space $\mathcal{C}([0, 1])$ (e.g. L_2 , $k = 5$):



Classification – DD-plot

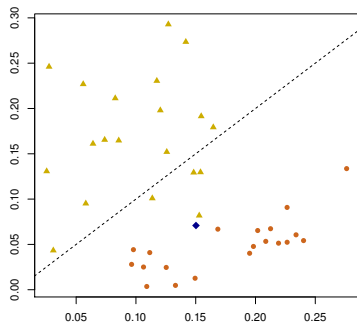
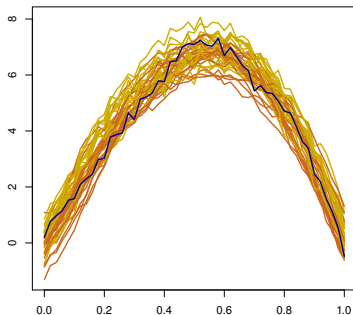
For given training samples $\mathbb{X}_1, \mathbb{X}_2$ and depth D , the **DD-transformation** of data can be computed as

$$DD: C([0, 1]) \rightarrow \mathbb{R}^2: x \mapsto (D(x; \mathbb{X}_1), D(x; \mathbb{X}_2))^T$$



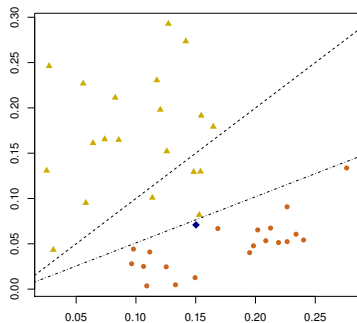
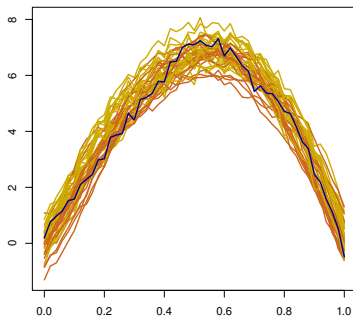
DD-plot and Highest Depth Rule

The function is assigned to the sample with **highest depth value**
 $\arg \max_{j=1,2} D(x; \mathbb{X}_j)$ (Cuevas et al. 2007)



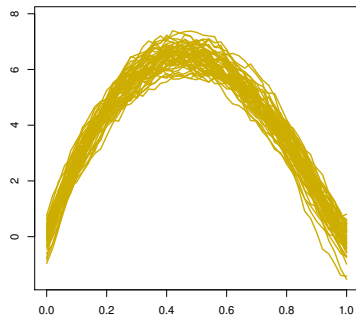
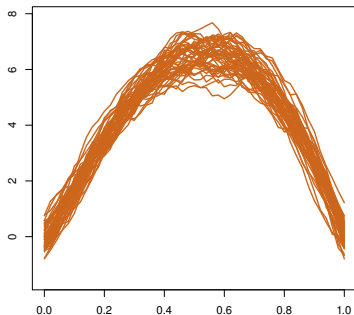
DD-plot and Li's Rule

An increasing **best separating** function (linear, or polynomial) is utilized to classify the DD-transformations (Li et al. 2010)



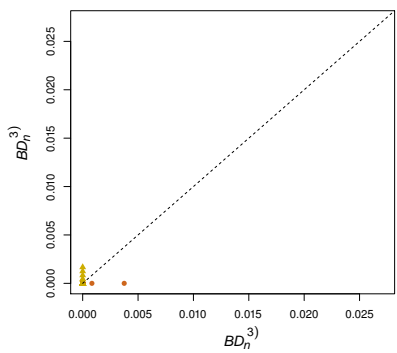
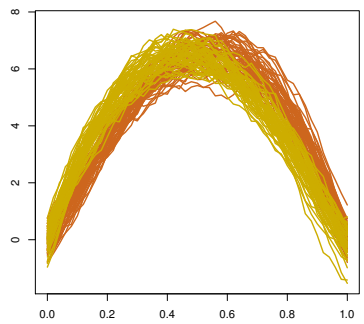
Location-shifted Model: Functions

$$m_1(t) = 30(1-t)t^{1.2}, m_2(t) = 30t(1-t)^{1.2}$$

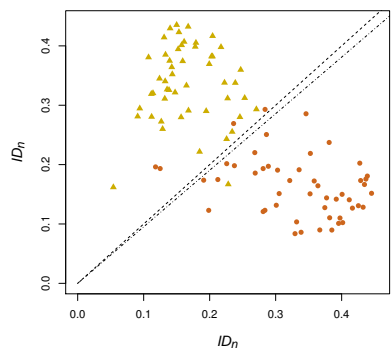
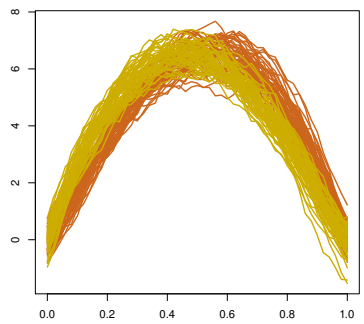


$$R_1(s, t) = 0.2 \exp\left(-\frac{|s-t|}{0.3}\right), R_2(s, t) = 0.2 \exp\left(-\frac{|s-t|}{0.3}\right)$$

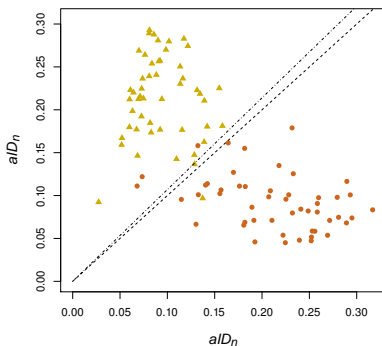
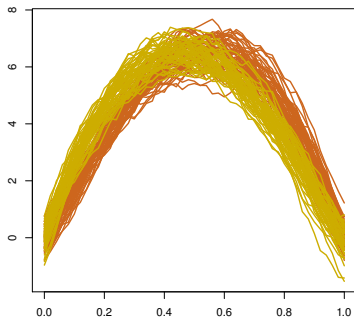
Location-shifted Model: $BD_n^{(3)}$



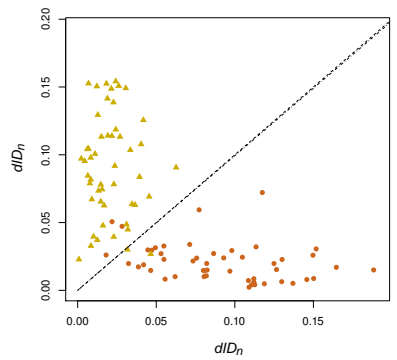
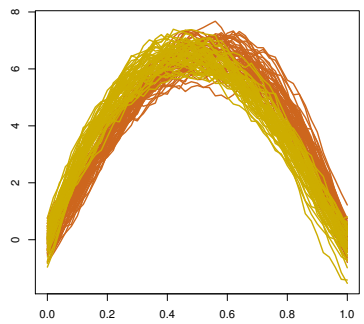
Location-shifted Model: ID_n



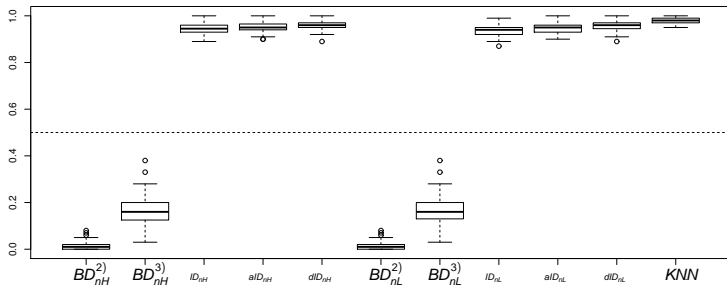
Location-shifted Model: aID_n



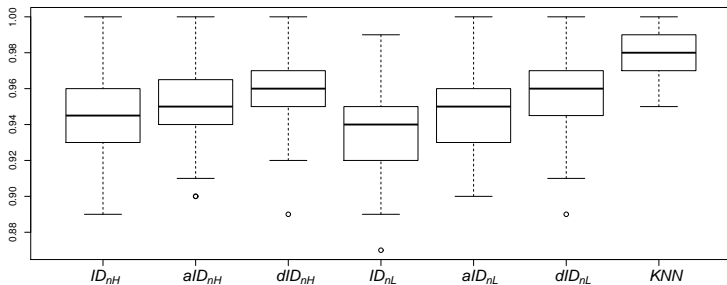
Location-shifted Model: dID_n



Location-shifted Model: Results 1

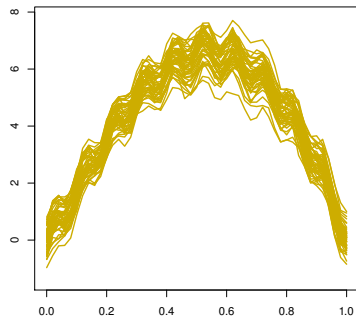
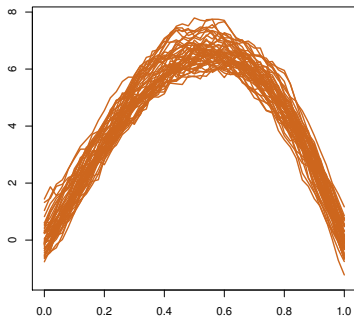


Location-shifted Model: Results 2



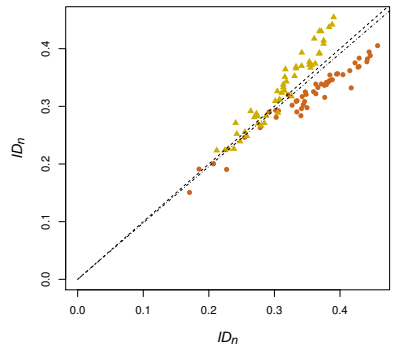
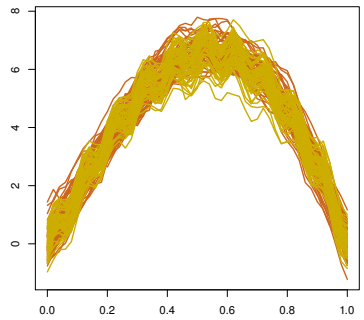
Shape-shifted Model: Functions

$$m_1(t) = 30(1-t)t^{1.2}, m_2(t) = 30(1-t)t^{1.2} + \frac{\sin(20\pi t)}{3}$$

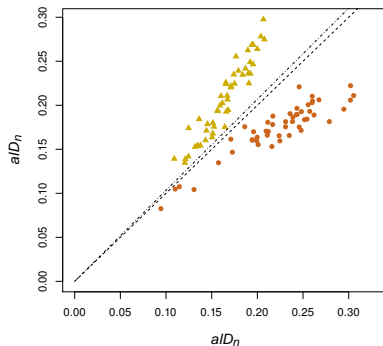
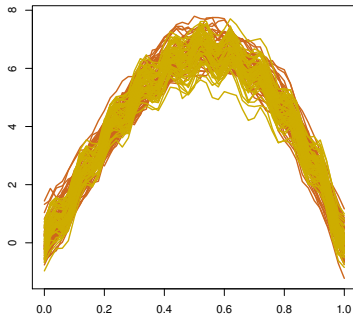


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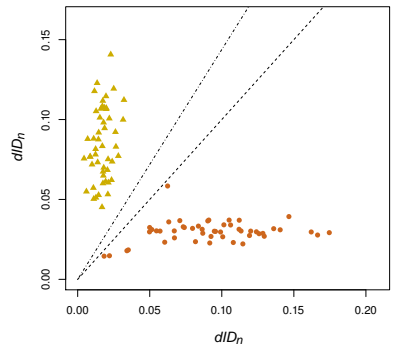
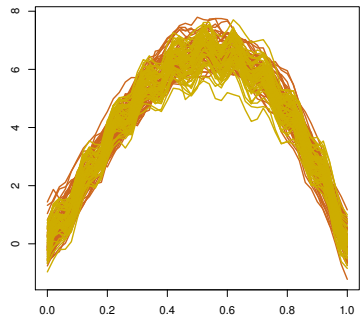
Shape-shifted Model: ID_n



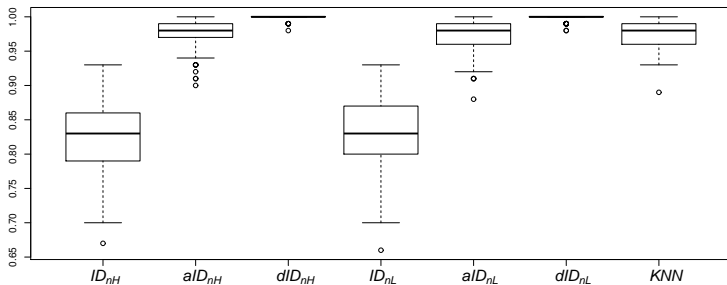
Shape-shifted Model: aID_n



Shape-shifted Model: dID_n

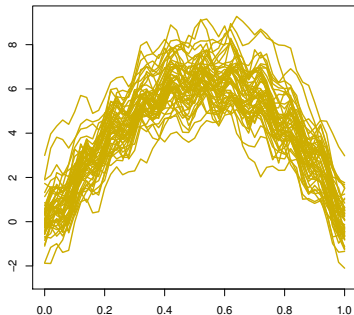
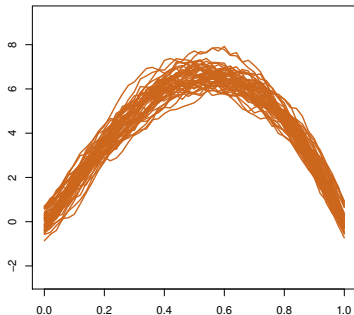


Shape-shifted Model: Results



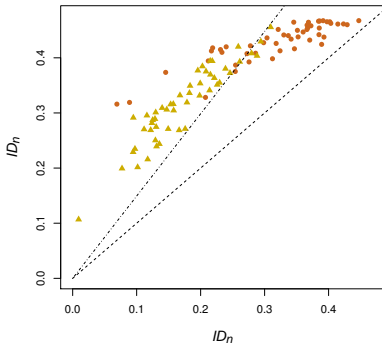
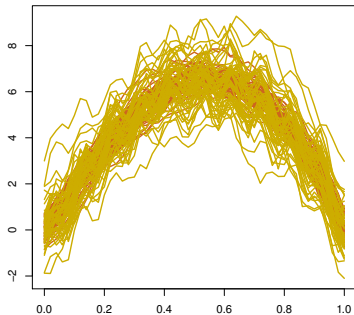
Variance Difference Model: Functions

$$m_1(t) = 30(1-t)t^{1.2}, \quad m_2(t) = 30(1-t)t^{1.2} + \frac{\sin(20\pi t)}{3}$$

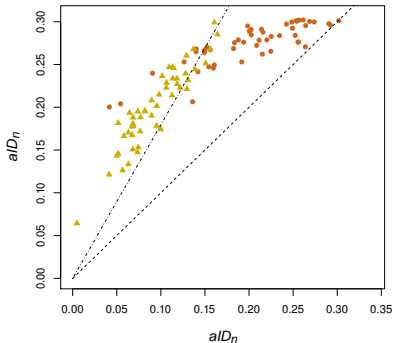
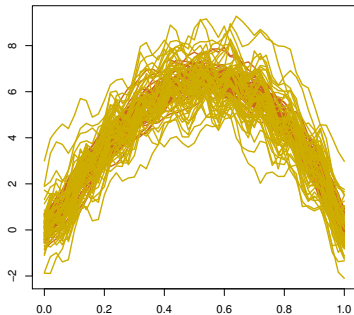


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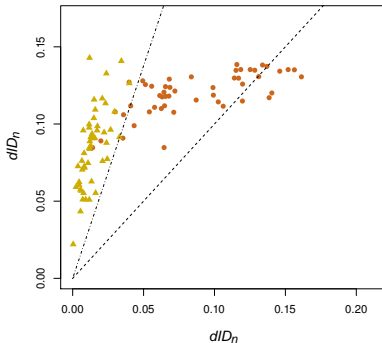
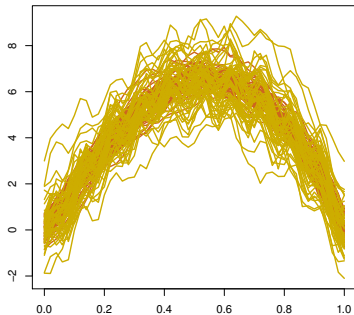
Variance Difference Model: ID_n



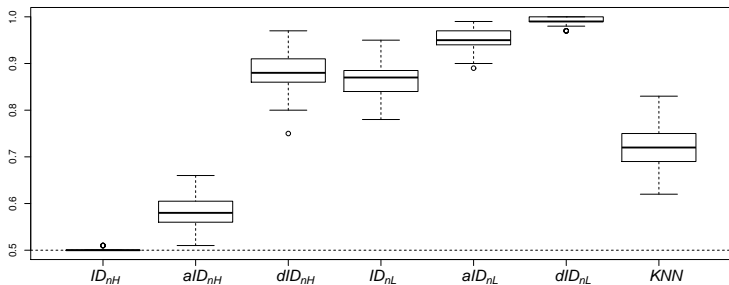
Variance Difference Model: aID_n



Variance Difference Model: dID_n



Variance Difference Model: Results



Outline

- 1 Depth Measure and its Smoothness for Multivariate Data
 - Smoothness of Halfspace Depth Contours
- 2 Functional Data Depth: Theory
 - Functional Band Depths
 - Consistency
 - Counterexample
 - Fixing the Continuousness
 - Integral and Vector Depths
- 3 Functional Data Depth: Practice
 - Problem of Functional Data Classification
 - Using Depth for Classification
 - Simulation Study
- 4 Conclusions

Depth-based Classification

How to choose a depth?

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- **Band depths fail** in the case of noisy observations.

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- **Depths including derivatives** with proper weights provide **good pattern recognition** for the location-shifted models as well as for the shape-shifted models.

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In most of the non-trivial examples the K-derivative depths classify **better than the nearest neighbor methods**.

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How to choose a DD-plot analysis method?

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The nearest neighbor rule appears to be weak in comparison with Li's rules, mainly in the variance difference models.

Conclusions: Band Depths








As far as band depths are concerned, we have seen that:

- they provide **bad results in applications**,
- **are hard to be counted** ($O(n^J)$ against $O(n)$ for integral depths),
- **need not to be uniformly consistent.**







Conclusion

Avoid using band depths, aim for integral alternatives!

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