On best approximations of matrix polynomials

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joint work with

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February 2-6, 2009 Institute of Geonics, Ostrava Seminar on Numerical Analysis (SNA) 2009 Best approximation by polynomials

$$\min_{p \in \mathcal{P}_m(K)} \| f(z) - p(z) \|$$

where f is a given (nice) function, $K \subset \mathbb{C}$ is compact, \mathcal{P}_m is s the set of polynomials of degree at most m.

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Such problems have been studied since the 1850s; numerous results on existence, uniqueness and rate of convergence for $m\to\infty$.

Best approximation results can be used for bounding and/or estimating "almost best" approximations.

Matrix function best approximation problem

We consider the matrix approximation problem

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Without loss of generality we assume that f is a given polynomial.

Does this problem have a unique solution $p_* \in \mathcal{P}_m$?

$$\min_{p \in \mathcal{M}_{m+1}} \| p(\mathbf{A}) \| = \min_{p \in \mathcal{P}_m} \| \mathbf{A}^{m+1} - p(\mathbf{A}) \|,$$

where \mathcal{M}_{m+1} is the class of monic polynomials of degree m+1, \mathcal{P}_m is the class of polynomials of degree at most m.

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- Introduced in [Greenbaum and Trefethen, 1994], paper contains uniqueness result (→ story of the proof).
- The unique polynomial that solves the problem is called the (m + 1)st ideal Arnoldi polynomial of **A**, or the (m + 1)st Chebyshev polynomial of **A**.
- Some work on these polynomials in [Toh PhD thesis, 1996], [Toh and Trefethen, 1998], [Trefethen and Embree, 2005].

2 Formulation of matrix polynomial approximation problems



Pormulation of matrix polynomial approximation problems



Given

• m linearly independent matrices $\mathbf{A}_1, \ldots, \mathbf{A}_m \in \mathbb{C}^{n imes n}$,

•
$$\mathbb{A} \equiv \operatorname{span} {\mathbf{A}_1, \ldots, \mathbf{A}_m},$$

- $\mathbf{B} \in \mathbb{C}^{n imes n} ackslash \mathbb{A}$,
- $\|\cdot\|$ is a matrix norm.

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This problem has a unique solution if $\|\cdot\|$ is strictly convex.

[see, e.g., Sreedharan, 1973]

Strictly convex norms

The norm $\|\cdot\|$ is strictly convex if for all $\mathbf{X},\,\mathbf{Y},$

$$\|\mathbf{X}\| = \|\mathbf{Y}\| = 1$$
, $\|\mathbf{X} + \mathbf{Y}\| = 2 \Rightarrow \mathbf{X} = \mathbf{Y}$.

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Which matrix norms are strictly convex? Let $\sigma_1 \ge \sigma_2 \ge \cdots \ge \sigma_n$ be singular values of X and $1 \le p \le \infty$.

The
$$c_p$$
-norm: $\|\mathbf{X}\|_p \equiv \left(\sum_{i=1}^n \sigma_i^p\right)^{1/p}$

• $p = 2 \dots$ Frobenius norm,

• $p = \infty$... spectral norm, matrix 2-norm, $\|\mathbf{X}\|_{\infty} = \sigma_1$,

• $p = 1 \dots$ trace (nuclear) norm.

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Theorem. If $1 then the <math>c_p$ -norm is strictly convex.

[see, e.g., Zietak, 1988]

Spectral norm (matrix 2-norm)

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$$\mathbf{X} = \begin{bmatrix} \mathbf{I} \\ & \varepsilon \end{bmatrix}, \qquad \mathbf{Y} = \begin{bmatrix} \mathbf{I} \\ & \delta \end{bmatrix}, \qquad \varepsilon, \ \delta \in \langle 0, 1 \rangle.$$

Then we have, for each ε , $\delta \in \langle 0, 1 \rangle$,

 $\|\mathbf{X}\| = \|\mathbf{Y}\| = 1$ and $\|\mathbf{X} + \mathbf{Y}\| = 2$

but if $\varepsilon \neq \delta$ then $\mathbf{X} \neq \mathbf{Y}$.

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Consequently: Best approximation problems in the spectral norm are not guaranteed to have a unique solution.

Matrix approximation problems in spectral norm

$$\min_{\mathbf{M}\in\mathbb{A}}\|\mathbf{B}-\mathbf{M}\|=\|\mathbf{B}-\mathbf{A}_*\|$$

 $A_* \in \mathbb{A}$ achieving the minimum is called a spectral approximation of B from the subspace \mathbb{A} .

Open question: When does this problem have a unique solution?

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Ziętak's sufficient condition

Theorem [Zietak, 1993]. If the residual matrix $\mathbf{B} - \mathbf{A}_*$ has an *n*-fold maximal singular value, then the spectral approximation \mathbf{A}_* of \mathbf{B} from the subspace \mathbb{A} is unique.

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Is this sufficient condition satisfied, e.g., for the ideal Arnoldi approximation problem?

General characterization of spectral approximations

General characterization by [Lau and Riha, 1981] and [Zietak, 1993, 1996] \rightarrow based on the Singer's theorem [Singer, 1970].

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Define $|||\cdot|||$ (trace norm, nuclear norm, c_1 -norm) and $\langle\cdot,\cdot\rangle$ by

$$|||\mathbf{X}||| = \sigma_1 + \dots + \sigma_n, \quad \langle \mathbf{Z}, \mathbf{X} \rangle \equiv \operatorname{tr}(\mathbf{Z}^*\mathbf{X}).$$

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Characterization: [Ziętak, 1996] $\mathbf{A}_* \in \mathbb{A}$ is a spectral approximation of \mathbf{B} from the subspace \mathbb{A} iff there exists $\mathbf{Z} \in \mathbb{C}^{n \times n}$, s.t.

$$|||\mathbf{Z}||| = 1, \qquad \langle \mathbf{Z}, \mathbf{X} \rangle = 0, \quad \forall \mathbf{X} \in \mathbb{A},$$

and

$$\operatorname{Re}\langle \mathbf{Z}, \mathbf{B} - \mathbf{A}_* \rangle = \| \mathbf{B} - \mathbf{A}_* \|.$$

Theorem. Let \mathbf{J}_{λ} be the $n \times n$ Jordan block. Consider the ideal Arnoldi approximation problem

$$\min_{p \in \mathcal{M}_m} \| p(\mathbf{J}_{\lambda}) \| = \min_{\mathbf{M} \in \mathbb{A}} \| \mathbf{B} - \mathbf{M} \|,$$

where $\mathbf{B} = \mathbf{J}_{\lambda}^{m}$, $\mathbb{A} = \operatorname{span} \{\mathbf{I}, \mathbf{J}_{\lambda}, \dots, \mathbf{J}_{\lambda}^{m-1}\}$. The minimum is attained by the polynomial $p_{*} = (z - \lambda)^{m}$ [Liesen and T., 2008].

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Proof. For $p=(z-\lambda)^m$, the residual matrix ${f B}-{f M}$ is given by

$$\mathbf{B} - \mathbf{M} = p(\mathbf{J}_{\lambda}) = (\mathbf{J}_{\lambda} - \lambda \mathbf{I})^m = \mathbf{J}_0^m.$$

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Theorem [Zietak, 1993]. If the residual matrix $\mathbf{B} - \mathbf{A}_*$ has an *n*-fold maximal singular value, then the spectral approximation \mathbf{A}_* of \mathbf{B} from the subspace \mathbb{A} is unique.

For the ideal Arnoldi approximation problem and the Jordan block $\mathbf{J}_{\lambda},$ we have shown that

$$\mathbf{B}-\mathbf{A}_*=\mathbf{J}_0^m.$$

One is (n - m)-fold maximal singular value of $\mathbf{B} - \mathbf{A}_*$, zero is *m*-fold singular value of $\mathbf{B} - \mathbf{A}_*$.

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The spectral approximation is unique [Greenbaum and Trefethen. 1994], but, apparently, Zietak's sufficient condition is not satisfied!

2 Formulation of matrix polynomial approximation problems



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Known results

• If A is normal, the problem reduces to the well studied scalar approximation problem on the spectrum of A,

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• For general A - only a special case of $f(\mathbf{A}) = \mathbf{A}^{m+1}$ is known to have a unique solution [Greenbaum and Trefethen, 1994].

Reformulation of the problem

Let f be a polynomial of degree $m+\ell+1$ $(m\geq 0,\ \ell\geq 0).$ Then

$$f(z) = z^{m+1}g(z) + f_m z^m + \dots + f_1 z + f_0,$$

where g is a polynomial of degree at most $\ell.$ Approximate f by p

 $p(z) = p_m z^m + \dots + p_1 z + p_0.$

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It is easy to show that

$$\min_{p \in \mathcal{P}_m} \|f(\mathbf{A}) - p(\mathbf{A})\| = \min_{h \in \mathcal{P}_m} \|\mathbf{A}^{m+1}g(\mathbf{A}) - h(\mathbf{A})\|.$$

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Without loss of generality we can consider the problem

$$\min_{h\in\mathcal{P}_m}\left\|\mathbf{A}^{m+1}g(\mathbf{A})-h(\mathbf{A})\right\|,\,$$

where g is a given polynomial of degree at most ℓ .

Matrix polynomial approximation problems

We consider the problem

$$\min_{h\in\mathcal{P}_m} \|\mathbf{A}^{m+1}g(\mathbf{A}) - h(\mathbf{A})\|,$$

where g is a given polynomial of degree at most ℓ . For $g \equiv 1$ we obtain the ideal Arnoldi approximation problem. We consider the problem

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Related problem:

$$\min_{g \in \mathcal{P}_{\ell}} \| \mathbf{A}^{m+1} g(\mathbf{A}) - h(\mathbf{A}) \|,$$

where h is a given polynomial of degree at most m. For $h \equiv 1$ we obtain the ideal GMRES approximation problem.

Matrix polynomial approx. problems - general notation

We consider matrix approximation problems of the form

$$\min_{\mathbf{M}\in\mathbb{A}}\|\mathbf{B}-\mathbf{M}\|.$$

$$\begin{array}{ll} \mathbf{B} &\equiv& \mathbf{A}^{m+1}g(\mathbf{A})\,, \qquad g\in\mathcal{P}_{\ell} \text{ given} \\ \mathbb{A} &\equiv& \operatorname{span}\left\{\mathbf{I},\mathbf{A},\ldots,\mathbf{A}^{m}\right\}, \end{array}$$

$$\begin{split} \mathbf{B} &\equiv h(\mathbf{A}), \qquad h \in \mathcal{P}_m \text{ given} \\ \mathbb{A} &\equiv \operatorname{span} \left\{ \mathbf{A}^{m+1}, \mathbf{A}^{m+2}, \dots, \mathbf{A}^{m+\ell+1} \right\}. \end{split}$$

 $\mathbf{B} \in \mathbb{C}^{n \times n} \setminus \mathbb{A}$ means that the minimum > 0.

2

Pormulation of matrix polynomial approximation problems



Uniqueness results

Theorem [Liesen and T., 2008].

$$\min_{h\in\mathcal{P}_m}\|\mathbf{A}^{m+1}g(\mathbf{A})-h(\mathbf{A})\|>0,$$

has the unique minimizer.

Uniqueness results

Theorem [Liesen and T., 2008].

$$\min_{h\in\mathcal{P}_m} \|\mathbf{A}^{m+1}g(\mathbf{A}) - h(\mathbf{A})\| > 0,$$

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2 Let A be nonsingular and $h \in \mathcal{P}_m$ given. Then the problem

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The nonsingularity in (2) cannot be omitted in general.

Idea of the proof (by contradiction)

Based on the proof by [Greenbaum and Trefethen, 1994]. Consider the problem

$$\min_{p \in \mathcal{G}_{\ell,m}^{(g)}} \| p(\mathbf{A}) \|$$

where

$$\mathcal{G}_{\ell,m}^{(g)} \equiv \left\{ z^{m+1}g + h \, : \, g \in \mathcal{P}_{\ell} \text{ is given, } h \in \mathcal{P}_m \right\}.$$

Let q_1 and q_2 be two different solutions, $||q_1(\mathbf{A})|| = ||q_2(\mathbf{A})|| = C$.

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Let q_1 and q_2 be two different solutions, $||q_1(\mathbf{A})|| = ||q_2(\mathbf{A})|| = C$. Use q_1 and q_2 to construct the polynomial

$$q_{\epsilon} = (1 - \epsilon) \, \mathbf{q} + \epsilon \, \widetilde{\mathbf{q}} \; \in \; \mathcal{G}_{\ell,m}^{(g)}$$

and show that, for sufficiently small ϵ ,

$$\|q_{\epsilon}(\mathbf{A})\| < C.$$

• We showed uniqueness of two matrix best approximation problems in spectral norm,

$$\min_{p\in\mathcal{P}_m}\|f(\mathbf{A})-p(\mathbf{A})\|$$

 and

$$\min_{p \in \mathcal{P}_{\ell}} \| h(\mathbf{A}) - \mathbf{A}^{m+1} p(\mathbf{A}) \|.$$

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• Generalization of ideal Arnoldi and ideal GMRES problems.

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- Generalization of ideal Arnoldi and ideal GMRES problems.
- Nontrivial problem for nonnormal A.
- Open question: When does the general problem

$$\min_{\mathbf{M}\in\mathbb{A}}\|\mathbf{B}-\mathbf{M}\|$$

have a unique solution?

Related papers

- J. Liesen and P. Tichý, [On best approximations of polynomials in matrices in the matrix 2-norm, submitted, June 2008.]
- A. Greenbaum and N. L. Trefethen, [GMRES/CR and Arnoldi/Lanczos as matrix approximation problems, Iterative methods in numerical linear algebra (Copper Mountain Resort, CO, 1992), SIAM J. Sci. Comput. 15 (1994), no. 2, 359–368]

More details can be found at

http://www.cs.cas.cz/tichy http://www.math.tu-berlin.de/~liesen

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