Efficient Estimation of the $A$-norm of the Error in the Preconditioned Conjugate Gradient Method

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Consider a system of linear algebraic equations

\[ \mathbf{A} \mathbf{x} = \mathbf{b} \]

where \( \mathbf{A} \in \mathbb{R}^{n \times n} \) is symmetric positive definite, \( \mathbf{b} \in \mathbb{R}^n \).


The conjugate gradient method minimizes at the \( j \)th step the energy norm of the error on the given \( j \)-dimensional Krylov subspace.
The conjugate gradient method (CG)

Given $x_0 \in \mathbb{R}^n$, $r_0 = b - Ax_0$.

CG computes a sequence of iterates $x_j$, $x_j \in x_0 + \mathcal{K}_j(A, r_0)$

so that

$$
\|x - x_j\|_A = \min_{u \in x_0 + \mathcal{K}_j(A, r_0)} \|x - u\|_A,
$$

where

$$
\mathcal{K}_j(A, r_0) \equiv \text{span}\{r_0, Ar_0, \ldots, A^{j-1}r_0\},
$$

$$
\|x - x_j\|_A \equiv (\langle x - x_j, A(x - x_j) \rangle)^{\frac{1}{2}}.
$$
given $x_0, \ r_0 = b - Ax_0, \ p_0 = r_0,$

for $j = 0, 1, 2, \ldots$

$$\gamma_j = \frac{(r_j, r_j)}{(p_j, Ap_j)}$$

$$x_{j+1} = x_j + \gamma_j p_j$$

$$r_{j+1} = r_j - \gamma_j Ap_j$$

$$\delta_{j+1} = \frac{(r_{j+1}, r_{j+1})}{(r_j, r_j)}$$

$$p_{j+1} = r_{j+1} + \delta_{j+1} p_j$$
Preconditioned Conjugate Gradients (PCG)

The CG-iterates are thought of being applied to

\[ \hat{A} \hat{x} = \hat{b}. \]

We consider symmetric preconditioning

\[ \hat{A} = L^{-1}AL^{-T}, \quad \hat{b} = L^{-1}b. \]

Change of variables

\[ M \equiv LL^T, \quad \gamma_j \equiv \hat{\gamma}_j, \quad \delta_j \equiv \hat{\delta}_j, \]

\[ x_j \equiv L^{-T}\hat{x}_j, \quad r_j \equiv L\hat{r}_j, \quad s_j \equiv M^{-1}r_j, \quad p_j \equiv L^{-T}\hat{p}_j. \]

The preconditioner \( M \) is chosen so that a linear system with the matrix \( M \) is easy to solve while the matrix \( L^{-1}AL^{-T} \) should ensure fast convergence of CG.
Algorithm of PCG

given $x_0$, $r_0 = b - Ax_0$, $s_0 = M^{-1}r_0$, $p_0 = s_0$,

for $j = 0, 1, 2, \ldots$

$$\gamma_j = \frac{(r_j, s_j)}{(p_j, Ap_j)}$$

$$x_{j+1} = x_j + \gamma_j p_j$$

$$r_{j+1} = r_j - \gamma_j Ap_j$$

$$s_{j+1} = M^{-1}r_{j+1}$$

$$\delta_{j+1} = \frac{(r_{j+1}, s_{j+1})}{(r_j, s_j)}$$

$$p_{j+1} = s_{j+1} + \delta_{j+1} p_j$$
How to measure quality of approximation?

... it depends on a problem.

- **using residual information,**
  - normwise backward error,
  - relative residual norm.

- **using error estimates,**
  - estimate of the $\mathbf{A}$-norm of the error,
  - estimate of the Euclidean norm of the error.

If the system is well-conditioned - it does not matter.
A message from history

- Using of the residual vector $r_j$ as a measure of the “goodness” of the estimate $x_j$ is not reliable [HeSt-52, p. 410].

- The function $(x - x_j, A(x - x_j))$ can be used as a measure of the “goodness” of $x_j$ as an estimate of $x$ [HeSt-52, p. 413].
Various convergence characteristics

Example using [GuSt-00], $n = 48$. 

![Graph showing various convergence characteristics](image)
Outline

1. CG and Gauss Quadrature
2. Construction of estimates in CG and PCG
3. Estimates in finite precision arithmetic
4. Rounding error analysis
5. Numerical experiments
6. Conclusions
1. CG and Gauss Quadrature
CG and Gauss Quadrature

At any iteration step $j$, CG (implicitly) determines weights and nodes of the $j$-point Gauss quadrature

$$\int_{\zeta}^{\xi} f(\lambda) \, d\omega(\lambda) = \sum_{i=1}^{j} \omega^{(j)}_{i} f(\theta^{(j)}_{i}) + R_{j}(f).$$

For $f(\lambda) \equiv \lambda^{-1}$ the formula takes the form

$$\frac{\|x - x_{0}\|^{2}_{A}}{\|r_{0}\|^{2}} = j\text{-th Gauss quadrature} + \frac{\|x - x_{j}\|^{2}_{A}}{\|r_{0}\|^{2}}.$$

This formula was a base for CG error estimation in [DaGoNa-78, GoFi-93, GoMe-94, GoSt-94, GoMe-97, . . .].
Equivalent formulas

- **Continued fractions** [GoMe-94, GoSt-94, GoMe-97]

  \[ \|r_0\|^2 C_n = \|r_0\|^2 C_j + \|x - x_j\|^2_A , \]

  The fractions \( C_n, C_j \ldots \) correspond to \( \omega(\lambda) \) and \( \omega^{(j)}(\lambda) \).

- **Warnick** [Wa-00]

  \[ r_0^T (x - x_0) = r_0^T (x_j - x_0) + \|x - x_j\|^2_A . \]

- **Hestenes and Stiefel** [HeSt-52, De-93, StTi-02]

  \[ \|x - x_0\|^2_A = \sum_{i=0}^{j-1} \gamma_i \|r_i\|^2 + \|x - x_j\|^2_A . \]

  The last formula is derived purely algebraically!
Hestenes and Stiefel formula (derivation)

Using local orthogonality between \( r_{i+1} \) and \( p_i \),

\[
\|x - x_i\|^2_A - \|x - x_{i+1}\|^2_A = \gamma_i \|r_i\|^2.
\]

Then

\[
\|x - x_0\|^2_A - \|x - x_j\|^2_A = \sum_{i=0}^{j-1} \left( \|x - x_i\|^2_A - \|x - x_{i+1}\|^2_A \right) = \sum_{i=0}^{j-1} \gamma_i \|r_i\|^2.
\]

The approach to derivation of this formula is very important for its understanding in finite precision arithmetic.
Standard derivation of this formula uses global $A$-orthogonality among direction vectors [AxKa-01, p. 274], [Ar-04, p. 8].

A local $A$-orthogonality and Pythagorean theorem should be used instead:
2. Construction of estimates in CG and PCG
Idea: Consider, for example,

\[ \| x - x_j \|^2_A = \| r_0 \|^2 [C_n - C_j] . \]

Run \( d \) extra steps. Subtracting identity for \( \| x - x_{j+d} \|^2_A \) gives

\[ \| x - x_j \|^2_A = \| r_0 \|^2 [C_{j+d} - C_j] + \| x - x_{j+d} \|^2_A . \]

When \( \| x - x_j \|^2_A \gg \| x - x_{j+d} \|^2_A \), we have a tight (lower) bound [GoSt-94, GoMe-97].
Mathematically equivalent estimates

- **Continued fractions** [GoSt-94, GoMe-97]

\[ \eta_{j,d} = \|r_0\|^2 [C_{j+d} - C_j], \]

- **Warnick** [Wa-00]

\[ \mu_{j,d} = r_0^T (x_{j+d} - x_j), \]

- **Hestenes and Stiefel** [HeSt-52]

\[ \nu_{j,d} = \sum_{i=j}^{j+d-1} \gamma_i \|r_i\|^2. \]
Construction of estimate in PCG

The $\mathbf{A}$-norm of the error can be estimated similarly as in ordinary CG.

- Extension of the Gauss Quadrature formulas based on continued fractions was published in [Me-99].

- Extension of the HS estimate: use the HS formula for $\hat{\mathbf{A}} \hat{x} = \hat{b}$ and substitution $\hat{\mathbf{A}} = \mathbf{L}^{-1} \mathbf{A} \mathbf{L}^{-T}$, $\hat{x}_j = \mathbf{L}^T x_j$, $\hat{\gamma}_i = \gamma_i$, $\hat{r}_i = \mathbf{L}^{-1} r_i$ [De-93, AxKa-01, StTi-04, Ar-04]

$$
\left\| \hat{x} - x_j \right\|_{\hat{\mathbf{A}}}^2 = \sum_{i=j}^{j+d-1} \hat{\gamma}_i \left\| \hat{r}_i \right\|_{\hat{\mathbf{A}}}^2 + \left\| \hat{x} - x_{j+d} \right\|_{\hat{\mathbf{A}}}^2.
$$

In many problems it is convenient to use a stopping criterion that relates the relative $\mathbf{A}$-norm of the error to a discretization error, see [Ar-04].
Estimating the relative $A$-norm of the error

To estimate the relative $A$-norm of the error we use the identities

$$
\| x - x_j \|_A^2 = \nu_{j,d} + \| x - x_{j+d} \|_A^2,
$$

$$
\| x \|_A^2 = \nu_{0,j+d} + 2 b^T x_0 - \| x_0 \|_A^2 + \| x - x_{j+d} \|_A^2.
$$

Define

$$
\varrho_{j,d} \equiv \frac{\nu_{j,d}}{\xi_{j+d}}.
$$

If $\| x \|_A \geq \| x - x_0 \|_A$ then $\varrho_{j,d} > 0$ and

$$
\varrho_{j,d} = \frac{\| x - x_j \|_A^2 - \| x - x_{j+d} \|_A^2}{\| x \|_A^2 - \| x - x_{j+d} \|_A^2} \leq \frac{\| x - x_j \|_A^2}{\| x \|_A^2}.
$$
3. Estimates in finite precision arithmetic
orthogonality is lost, convergence is delayed!
The identity \( \| x - x_j \|^2_A = EST^2 + \| x - x_{j+d} \|^2_A \) need not hold during the finite precision CG computations. An example: \( \mu_{j,d} = r_0^T (x_{j+d} - x_j) \) does not work!
4. Rounding error analysis
Without a proper rounding error analysis, there is no justification that the proposed estimates will work in finite precision arithmetic.

Do the estimates give good information in practical computations?

<table>
<thead>
<tr>
<th>estimate</th>
<th>CG</th>
<th>PCG</th>
</tr>
</thead>
<tbody>
<tr>
<td>$\eta_{j,d}$ (continued fractions)</td>
<td>yes*</td>
<td>yes?</td>
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<tr>
<td>$\mu_{j,d}$ (Warnick)</td>
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<td>no</td>
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<tr>
<td>$\nu_{j,d}$ (Hestenes and Stiefel)</td>
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<td>yes</td>
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</tbody>
</table>

*Based on [GrSt-92], [Gr-89], $\sqrt{\varepsilon}$ limit.
Hestenes and Stiefel estimate (CG)

[StTi-02]: Rounding error analysis based on
- detailed proof of preserving local orthogonality in CG,
- results [Pa-71, Pa-76, Pa-80], [Gr-89, Gr-97].

**Theorem:** Let \( \varepsilon \kappa(A) \ll 1 \). Then the CG approximate solutions computed in finite precision arithmetic satisfy

\[
\|x - x_j\|_A^2 - \|x - x_{j+d}\|_A^2 = \nu_{j,d} + \|x - x_j\|_A E_{j,d} + \mathcal{O}(\varepsilon^2),
\]

\[|E_{j,d}| \approx (\sqrt{\kappa(A)}) \varepsilon \|x - x_0\|_A.
\]

**Main result:** Until \( \|x - x_j\|_A \) reaches a level close to \( \varepsilon \|x - x_0\|_A \), the estimate \( \nu_{j,d} \) must work.
Hestenes and Stiefel estimate (PCG)

[StTi-04]: Analysis based on:
- rounding error analysis from [StTi-02],
- solving of

\[ \mathbf{M} s_{j+1} = r_{j+1} \]

enjoys perfect normwise backward stability [Hi-96, p. 206].

Similar result as for CG: Until \( \|x - x_j\|_A \) reaches a level close to \( \varepsilon \|x - x_0\|_A \), the estimate

\[ \nu_{j,d} = \sum_{i=j}^{j+d-1} \gamma_i(r_i, s_i) \]

must work.
5. Numerical Experiments
Estimating the $\mathbf{A}$-norm of the error

P. Benner: Large-Scale Control Problems, optimal cooling of steel profiles, PCG, $\kappa(\mathbf{A}) = 9.7e + 04$, $n = 5177$, $d = 4$, $\mathbf{L} = \text{cholinc} (\mathbf{A}, 0)$.
Estimating the $\mathbf{A}$-norm of the error

R. Kouhia: Cylindrical shell (Matrix Market), matrix s3dkt3m2, PCG, $\kappa(\mathbf{A}) = 3.62e + 11$, $n = 90499$, $d = 200$, $\mathbf{L} = \text{cholinc}(\mathbf{A}, 0)$. 

![Diagram showing the comparison of true residual norm, normwise backward error, and $\mathbf{A}$-norm of the error estimate.](image)
Estimating the relative $A$-norm of the error

R. Kouhia: Cylindrical shell (Matrix Market), matrix s3dkt3m2, PCG, $\kappa(A) = 3.62e + 11$, $n = 90499$, $d = 200$, $L = \text{cholinc}(A, 0)$.
Estimating the relative $A$-norm of the error

R. Kouhia: Cylindrical shell (Matrix Market), matrix s3rmt3m3,
PCG, $\kappa(A) = 2.40e + 10$, $n = 5357$, $d = 50$, $L = \text{cholinc}(A, 1e - 5)$.
R. Kouhia: Cylindrical shell (Matrix Market), matrix s3dkt3m2, \textbf{PCG}, \( \kappa(A) = 3.62e + 11 \), \( n = 90499 \), \( d = 100 \), \( L = \text{cholinc}(A, 0) \).
6. Conclusions

- Various formulas (based on Gauss quadrature) are mathematically equivalent to the formulas present (but somehow hidden) in the original Hestenes and Stiefel paper.

- Hestenes and Stiefel estimate is very simple, it can be computed almost for free and it has been proved numerically stable.

- We suggest the estimates $\nu_{j,d}^{1/2}$ and $\varrho_{j,d}^{1/2}$ to be incorporated into any software realizations of the CG and PCG methods.

- The estimates are tight if the $A$-norm of the error reasonably decreases.

**Open problem:** The adaptive choice of the parameter $d$. 
Thank you for your attention!

More details can be found in


http://www.cs.cas.cz/~strakos,
http://www.cs.cas.cz/~tichy