NMMO 401 Continuum mechanics

Winter 2016/2017

1. Let $\mathbb{A} \in \mathbb{R}^{3 \times 3}$ be an invertible matrix. Show that

$$I_2(\mathbb{A}) = Tr(\operatorname{cof} \mathbb{A})$$

where $\operatorname{cof} \mathbb{A} =_{\operatorname{def}} (\operatorname{det} \mathbb{A}) \mathbb{A}^{-\top}$ denotes the cofactor matrix of matrix \mathbb{A} , and $I_2(\mathbb{A}) =_{\operatorname{def}} \frac{1}{2} ((\operatorname{Tr} \mathbb{A})^2 - \operatorname{Tr} (\mathbb{A}^2))$ is the second invariant of matrix \mathbb{A} .

2. Let $\mathbb{A} \in \mathbb{R}^{3 \times 3}$ a $\mathbb{B} \in \mathbb{R}^{3 \times 3}$ be invertible matrices. Show that

$$\det(\mathbb{A} + \mathbb{B}) = \det \mathbb{A} + \operatorname{Tr}(\mathbb{A}^{\top} \operatorname{cof} \mathbb{B}) + \operatorname{Tr}(\mathbb{B}^{\top} \operatorname{cof} \mathbb{A}) + \det \mathbb{B},$$

where $\operatorname{cof} \mathbb{C} =_{\operatorname{def}} (\operatorname{det} \mathbb{C}) \mathbb{C}^{-\top}$ denotes the cofactor matrix of matrix \mathbb{C} .

3. Let us assume that the curve γ in \mathbb{R}^2 is given in terms of polar coordinates $[r, \varphi]$, see Figure 1, which means that

$$\boldsymbol{\gamma}: s \in (a,b) \mapsto \begin{bmatrix} r(s)\cos\varphi(s) \\ r(s)\sin\varphi(s) \end{bmatrix},$$

where s is the parametrisation of the curve. Further let us assume that $f : \mathbf{x} = [x, y] \in \mathbb{R}^2 \mapsto f(\mathbf{x}) \in \mathbb{R}$ is a given function. Show that

$$\int_{\gamma} f(\boldsymbol{x}) \, \mathrm{d}l = \int_{s=a}^{b} f(r(s) \cos \varphi(s), r(s) \sin \varphi(s)) \sqrt{\left(\frac{\mathrm{d}r}{\mathrm{d}s}\right)^{2} + r^{2} \left(\frac{\mathrm{d}\varphi}{\mathrm{d}s}\right)^{2}} \, \mathrm{d}s$$

Figure 1: Line integral in \mathbb{R}^2 – parametrisation in polar coordinates.

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