# Script of lecture nmma405

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## 1 Motivation for weak solution

Many principles of physics can be written in the form of a partial differential equation, see (1).

#### 1.1 Heat flow through a nonhomogeneous material

If data are not smooth, we cannot expect regularity of solutions. This situation happens for example if we are interested in heat flow through a real wall built of several material with different heat conductivity. If we are interested in stationary flow we need to solve an equation  $-\operatorname{div}(A\nabla u) = 0$  in  $\Omega \subset \mathbb{R}^d$  with a boundary condition  $u = u_0$  on  $\partial\Omega$ . The unknown temperature is  $u : \Omega \to \mathbb{R}$ . The set  $\Omega$ , the function  $u_0 : \partial\Omega \to \mathbb{R}$  and the matrix function  $A : \Omega \to \mathbb{R}^{d \times d}$ are given. The function A is influenced by the heat conductivity and can be discontinuous.

#### 1.2 Calculus of variations

Let  $L: \mathbb{R}^d \times \mathbb{R} \times \Omega \to \mathbb{R}$ , L = L(p, z, x). For  $u \in C^1(\overline{\Omega})$  we define

$$I(u) = \int_{\Omega} L(\nabla u(x), u(x), x) \,\mathrm{d}\, x.$$

We search for a local minimum or maximum of I in  $X = \{u \in C^1(\overline{\Omega}), u = 0 \text{ on } \partial\Omega$ .

**Definition 1.** We say that  $u_0 \in X$  is a local minimizer of I in X if

$$\exists \delta > 0, \forall u \in X : \|u - u_0\|_{C^1(X)} < \delta \implies I(u_0) \le I(u).$$

**Lemma 1** (1-necessary condition of minima). Let  $L \in C^1(\mathbb{R}^{2d+1})$ ,  $u_0 \in X$  be a local minimizer of I in X,  $h \in \mathcal{D}(\Omega)$ ,  $h \neq 0$ . Define for  $t \in \mathbb{R}$   $g(t) = I(u_0 + th)$ . Then g'(0) = 0, *i.e.* 

$$\forall h \in \mathcal{D}(\Omega) : \int_{\Omega} \partial_p L(\nabla u(x), u(x), x) \cdot \nabla h(x) \, \mathrm{d} \, x + \partial_z L(\nabla u(x), u(x), x) h(x) \, \mathrm{d} \, x = 0.$$
(1)

The equation (1) is a weak formulation of the PDE

$$\operatorname{div} \nabla_p L(\nabla u(x), u(x), x) + \partial_z L(\nabla u(x), u(x), x) = 0$$

for an unknown function u.

## 2 Sobolev spaces

In the whole section  $\Omega \subset \mathbb{R}^d$  is an open set.

**Definition 2.** Let  $u \in L^1_{loc}(\Omega)$ ,  $\alpha \in \mathbb{N}^d_0$  be a multi-index. A function  $v \in L^1_{loc}(\Omega)$  is called the  $\alpha^{th}$  weak derivative of u if

$$\forall \varphi \in \mathcal{D}(\Omega) : \int_{\Omega} \varphi v = (-1)^{|\alpha|} \int_{\Omega} u D^{\alpha} \varphi.$$

We denote it by  $D^{\alpha}u$ .

In the rest all derivatives will be understand in the weak sense if not explicitely differently.

**Definition 3** (Sobolev space). For  $p \in [1, +\infty]$ ,  $k \in \mathbb{N}$  we define Sobolev space

$$W^{k,p}(\Omega) = \{ u \in L^p(\Omega) | \forall \alpha \in \mathbb{N}_0^d : |\alpha| \le k \implies D^{\alpha} u \in L^p(\Omega) \}.$$

For  $u \in W^{k,p}(\Omega)$  we define

$$\|u\|_{W^{k,p}(\Omega)} = \begin{cases} \left( \int_{\Omega} \sum_{\alpha \in \mathbb{N}_0^d, |\alpha| \le k} |D^{\alpha} u|^p \right)^{\frac{1}{p}} & \text{if } p \in [1, +\infty), \\ \max_{\alpha \in \mathbb{N}_0^d, |\alpha| \le k} \|D^{\alpha} u\|_{L^{\infty}(\Omega)} & \text{if } p = +\infty. \end{cases}$$

We denote  $V \Subset \Omega$  if V is open and bounded subset of  $\Omega$  such that  $\overline{V} \subset \Omega$ . We say that  $u \in W_{loc}^{k,p}(\Omega)$  if for any  $V \Subset \Omega$ ,  $u \in W^{k,p}(V)$ . For  $u, v \in W^{k,2}(\Omega)$  we define

$$\langle u, v \rangle_{W^{k,2}(\Omega)} = \int_{\Omega} \sum_{\alpha \in \mathbb{N}_0^d, |\alpha| \le k} D^{\alpha} u D^{\alpha} v.$$

**Remark 1.** • Functions in  $W^{k,p}(\Omega)$  are determined up to a set of Lebesgue measure zero.

If we say that u ∈ W<sup>k,p</sup>(Ω) has some property, e.g. u is continuous, we mean that there is a representative with this property.

• If  $p \in [1, +\infty)$  let us define for  $u \in W^{k,p}(\Omega)$ 

$$|||u||| = \left(\sum_{\alpha \in \mathbb{N}_0^d, |\alpha| \le k} ||D^{\alpha}u||_{L^p(\Omega)}^p\right)^{\frac{1}{p}}.$$

Then  $||| \cdot |||$  is an equivalent norm on  $W^{k,p}(\Omega)$  to  $|| \cdot ||_{W^{k,p}(\Omega)}$ .

**Example 1.** Function  $f_{\alpha}(x) = |x|^{\alpha}$  for  $\alpha \in \mathbb{R}$ ,  $x \in \mathbb{R}^d$  belongs to  $W^{1,p}_{loc}(\mathbb{R}^d)$ , p > 1 if  $\alpha > 1 - \frac{d}{p}$ .

#### 2.1 Basic properties of Sobolev spaces

**Theorem 1** (2). (Properties of the weak derivative) (4, Section 5.2.3) Let  $u, v \in W^{k,p}(\Omega), k \in \mathbb{N}, p \in [1, +\infty]$  and  $\alpha \in (\mathbb{N}_0)^d, |\alpha| < k$ . Then

- 1.  $D^{\alpha}u \in W^{k-|\alpha|,p}(\Omega)$  and  $D^{\alpha}(D^{\beta}u) = D^{\beta}(D^{\alpha}u)$  for  $|\alpha| + |\beta| \le k$
- 2.  $\lambda, \mu \in \mathbb{R} \implies \lambda u + \mu v \in W^{k,p}(\Omega) \text{ and } D^{\alpha}(\lambda u + \mu v) = \lambda D^{\alpha}u + \mu D^{\alpha}v.$
- 3. if  $\tilde{\Omega} \subset \Omega$  open, then  $u \in W^{k,p}(\tilde{\Omega})$
- 4. if  $\eta \in \mathcal{D}(\Omega)$ , then  $\eta u \in W^{k,p}(\Omega)$  and

$$D^{\alpha}(\eta u) = \sum_{\beta \leq \alpha} \binom{\alpha}{\beta} D^{\beta} \eta D^{\alpha-\beta} u.$$

**Remark 2.** For  $\alpha, \beta \in \mathbb{N}_0^d$ ,  $\alpha! = \prod_{j=1}^d \alpha_j!$  and the number  $\binom{\alpha}{\beta}$  is defined by  $\alpha!/((\alpha - \beta)!\beta!)$ .

- **Example 2.** 1. If d = 1 and f(x) = sgn(x) then for any  $p \in [1, +\infty]$ ,  $f \notin W^{1,p}(-1, 1)$ .
  - 2. If d = 1 and f(x) = |x| then for any  $p \in [1, +\infty]$ ,  $f \in W^{1,p}(-1, 1)$ .
  - 3.  $W^{1,1}(-1,1) = AC(-1,1)$
  - 4. Cantor function c is continuous on (0,1), with c' = 0 a.e. in (0,1), but for all  $p \ge 1$ ,  $c \notin W^{1,p}(0,1)$ . The function c is not absolutely continuous.

Let  $h \in \mathcal{D}(\mathbb{R}^d)$ , spt  $h \subset U(0,1)$ ,  $\int_{\mathbb{R}^d} h = 1$ . We define  $h^j(x) = j^d h(jx)$  for  $x \in \mathbb{R}^d$ .

**Definition 4.** For  $u \in W^{k,p}(\Omega)$  we denote  $u^j = u \star h^j$  where the expression on the right hand side is well defined.

**Lemma 2** (3). (3, Lemma 2.1.3) Let  $u \in W^{k,p}(\Omega)$ ,  $p \in [1, +\infty)$ , then for all  $\alpha \in \mathbb{N}_0^d$ ,  $|\alpha| \leq k$  there holds  $(D^{\alpha}u)^j = D^{\alpha}(u^j)$  and  $u^j \to u$  in  $W^{k,p}_{loc}(\Omega)$ .

**Theorem 2** (4). (3, Theorem 2.1.4)

Let  $u \in L^p(\Omega)$ ,  $p \ge 1$ . Then  $u \in W^{1,p}(\Omega)$  if and only if u has a representative  $\tilde{u}$  that is absolutely continuous on  $\lambda^{d-1}$  a.e. line segments in  $\Omega$  parallel to the coordinate axis and whose classical partial derivatives (that exits almost everywhere) belong to  $L^p(\Omega)$ .

Proof was not presented.

**Corollary 1** (5). (3, 2.1.11) Let  $f : \mathbb{R} \to \mathbb{R}$  be a Lipschitz function and  $u \in W^{1,p}(\Omega)$ ,  $p \ge 1$ . If  $f \circ u \in L^p(\Omega)$  then  $f \circ u \in W^{1,p}(\Omega)$  and for a. e.  $x \in \mathbb{R}$  $\nabla(f \circ u)(x) = f'(u(x))\nabla u(x)$ .

**Definition 5.** For a function  $u: \Omega \to \mathbb{R}$  let  $u^+ = \max(u, 0), u^- = \min(u, 0)$ .

**Corollary 2** (6). (3, 2.1.8) Let  $u \in W^{1,p}(\Omega)$ ,  $p \ge 1$ . Then  $u^+, u^- \in W^{1,p}(\Omega)$ and

$$Du^{+} = \begin{cases} Du & \text{if } u > 0\\ 0 & \text{if } u \le 0 \end{cases} \qquad Du^{-} = \begin{cases} Du & \text{if } u < 0\\ 0 & \text{if } u \ge 0 \end{cases}$$

a.e. in  $\Omega$ .

**Theorem 3** (7). (3, 2.2.2) Let  $T : \mathbb{R}^d \to \mathbb{R}^d$  be a bi-Lipschitzian mapping such that  $T : \Omega' \to \Omega$  and

$$\exists M > 0, \forall x, y \in \Omega, \forall x', y' \in \Omega' : \frac{|T(x') - T(y')| \le M|x' - y'|}{|T^{-1}(x) - T^{-1}(y)| \le M|x - y|}.$$

If  $u \in W^{1,p}(\Omega)$ ,  $p \ge 1$ , then  $v = u \circ T \in W^{1,p}(V)$  where  $V = T^{-1}(\Omega)$  and for a. e.  $x \in \Omega'$  and any  $\xi \in \mathbb{R}^d$ 

$$\nabla u(T(x))\nabla T(x)\xi = \nabla u(x)\xi$$

**Remark 3** (8). In the situation of the previous theorem there is C > 0 such that for any  $U \subset \Omega$ ,  $V = T^{-1}U$  open sets,  $||u||_{W^{1,p}(U)} \leq C||v||_{W^{1,p}(V)} \leq C^2 ||u||_{W^{1,p}(U)}$ .

**Theorem 4** (8). (Basic properties of Sobolev spaces) Let  $k \in \mathbb{N}$ .

- 1. If  $p \in [1, +\infty]$ ,  $(W^{k,p}(\Omega), \|\cdot\|_{k,p})$  is a Banach space.
- 2.  $(W^{k,2}(\Omega), \langle \cdot, \cdot \rangle_{k,2})$  is a Hilbert space.
- 3. If  $p \in [1, +\infty)$ ,  $W^{k,p}(\Omega)$  is separable.
- 4. If  $p \in (1, +\infty)$ ,  $W^{k,p}(\Omega)$  is reflexive.

**Theorem 1** (9,10). (2, Theorem 3.8) Let  $p \in [1, +\infty)$ ,  $N \in \mathbb{N}$  be a number of multiindices  $\alpha \in \mathbb{N}_0^d$  such that  $|\alpha| \leq m$ . For every  $L \in W^{m,p}(\Omega)^*$  there exists an element  $(v \in L^{p'}(\Omega))^N$  such that, writing the vector v in the form  $(v)_{\alpha \in \mathbb{N}_0^d, |\alpha| \leq N}$  we have for all  $u \in W^{m,p}(\Omega)$ 

$$L(u) = \sum_{\alpha \in \mathbb{N}_0^d, |\alpha| \le N} \langle D^{\alpha} u, v \rangle.$$
(2)

Moreover  $||L||_{W^{m,p}(\Omega)^*} = \inf ||v||_{L^{p'}(\Omega)^N} = \min ||v||_{L^{p'}(\Omega)^N}$ , the infimum being taken over, and attained on the set of all  $v \in L^{p'}(\Omega)^N$  for which (2) holds for every  $u \in W^{m,p}(\Omega)$ .

#### 2.2 Approximation and extension of Sobolev functions

**Lemma 3** (11). (Partition of unity) (3, Lemma 2.3.1) Let  $E \subset \mathbb{R}^d$ ,  $\mathcal{G}$  be a collection of open sets such that  $E \subset \bigcup_{U \in \mathcal{G}} U$ . Then there is a family  $\mathcal{F}$  of nonnegative functions  $f \in \mathcal{D}(\mathbb{R}^d)$  such that  $0 \leq f \leq 1$  and

- 1.  $\forall f \in \mathcal{F}, \exists U \in \mathcal{G} : \operatorname{spt} f \subset U$
- 2.  $\forall K \subset E, K \text{ compact} : \operatorname{spt} f \cap K \neq \emptyset \text{ for only finitely many } f \in \mathcal{F}$
- 3.  $\sum_{f \in \mathcal{F}} f(x) = 1$  for every  $x \in E$
- 4. if E is compact, the family  $\mathcal{F}$  is finite
- 5. family  $\mathcal{F}$  is at most countable

**Theorem 5** (12). (3, Theorem 2.3.2) The set  $C^{\infty}(\Omega) \cap W^{k,p}(\Omega)$  is dense in  $W^{k,p}(\Omega)$ . The set  $\{f \in C^{\infty}(\Omega), \exists R > 0 : \operatorname{spt} f \subset U(0,R)\} \cap W^{k,p}(\Omega)$  is dense in  $W^{k,p}(\Omega)$ .

**Lemma 4** (13). Let  $u \in L^p(\mathbb{R}^d)$ ,  $p \in [1, +\infty)$ . For  $h \in \mathbb{R}^d$ ,  $h \neq 0$  and  $x \in \mathbb{R}^d$ define  $u_h(x) = u(x+h)$ . Then  $u_h \to u$  in  $L^p(\mathbb{R}^d)$  as  $h \to 0$ .

**Lemma 5** (14). Let  $V = U(0, R) \cap \{x \in \mathbb{R}^d; x_d > 0\}$ ,  $\epsilon > 0$ ,  $u \in W^{k,p}(\{x \in \mathbb{R}^d; x_d > 0\})$  with spt  $u \subset V$ . Then there is a function  $v \in C^{\infty}(\{x \in \mathbb{R}^d; x_d \geq 0\})$  such that spt  $v \subset U(0, 2R) \cap \{x \in \mathbb{R}^d; x_d \geq 0\}$  and  $||u - v||_{W^{k,p}(V)} < \epsilon$ .

**Theorem 6** (15). (4, Section 5.3.3, Theorem 3), (2, Theorem 3.18) Let  $k \in \mathbb{N}$ ,  $p \in [1, +\infty)$ ,  $\Omega \subset \mathbb{R}^d$  be bounded with  $C^1$  boundary. Then  $C^{\infty}(\overline{\Omega})$  is dense in  $W^{k,p}(\Omega)$ .

**Lemma 6** (16). Let us equip  $X = \{U \in C^1(\{x \in \mathbb{R}^d | x_d \ge 0\}) | \operatorname{spt} U \subset U(0, R)\}$ with a norm  $\|\cdot\|_X = \|\cdot\|_{W^{1,p}(U(0,R)) \cap \{x \in \mathbb{R}^d | x_d \ge 0\}}$  and  $Y = \{U \in C^1(\mathbb{R}^d) | \operatorname{spt} U \subset U(0,2R))\}$  with a norm  $\|\cdot\|_Y = \|\cdot\|_{W^{1,p}(U(0,2R))}$ . Then there is a linear mapping  $\tilde{E}: X \to Y$  such that

$$||E||_{\mathcal{L}((X,\|\cdot\|_X),(Y,\|\cdot\|_Y))} < C(p,R).$$

and  $\tilde{E}u = u$  on  $\{x \in \mathbb{R}^d | x_d \ge 0\}$  for any  $u \in X$ .

**Theorem 7** (17). (4, Section 5.4, Theorem 1) Assume  $\Omega \subset \mathbb{R}^d$  open, bounded and with  $C^1$  boundary. Fix  $V \subset \mathbb{R}^d$  open such that  $\Omega \Subset V$ . Then there is a bounded linear operator  $E: W^{1,p}(\Omega) \to W^{1,p}(\mathbb{R}^d)$  such that for all  $u \in W^{1,p}(\Omega)$ 

- 1. Eu = u a.e. in  $\Omega$
- 2. spt  $Eu \subset V$
- 3.  $||E|| \leq C$  with  $C = C(p, \Omega, V)$

#### 2.3 Embeddings of Sobolev spaces

We introduce a notation

$$\int_{\mathbb{R}^{d-1}} \widehat{f \, \mathrm{d} \, x_i} = \int_{\mathbb{R}^{d-1}} f \, \mathrm{d} \, x_i \dots \mathrm{d} \, x_{i-1} \, \mathrm{d} \, x_{i+1} \dots \mathrm{d} \, x_d.$$

**Lemma 7** (18). (4, Section 5.6, Theorem 1) Let  $d \ge 2$ , for  $i \in \{1, \ldots, d\}$ ,  $u_i \in C_c^1(\mathbb{R}^{d-1})$  and  $u_i$  be independent of  $x_i$ . Then

$$\int_{\mathbb{R}^d} \prod_{i=1}^d |u_i| \le (\prod_{i=1}^d \int_{\mathbb{R}^{d-1}} |u_i|^{d-1} \widehat{\mathrm{d} x_i})^{\frac{1}{d-1}}.$$

**Lemma 8** (19). (4, Section 5.6, Theorem 1) Let d > 2,  $u \in C_c^1(\mathbb{R}^d)$ . Then for  $p \in [1, d)$ ,  $p^* = \frac{dp}{d-p}$ , i.e.  $-\frac{d}{p^*} = 1 - \frac{d}{p}$ 

$$||u||_{L^{p^*}(\Omega)} \le p \frac{d-1}{d-p} ||\nabla u||_{L^p(\mathbb{R}^d)}.$$

**Theorem 8** (20). Let  $p \in [1, d)$ , d > 2. Then  $W^{1,p}(\mathbb{R}^d) \hookrightarrow L^{p^*}(\mathbb{R}^d)$ .

**Definition 6.** For  $p \in [1, +\infty]$  we define  $W_0^{k,p}(\Omega) = \overline{\mathcal{D}(\Omega)}^{\|\cdot\|_{k,p}}$ 

**Theorem 9** (21). Let  $p \in [1, d)$ , d > 2,  $\Omega$  bounded. Then for all  $q \in [1, p^*]$  exists C > 0 such that for all  $u \in W_0^{1,p}(\Omega)$  there holds  $\|u\|_{L^q(\Omega)} \leq C \|\nabla u\|_{L^p(\Omega)}$ .

**Remark 4.**  $\|\cdot\|_{1,p}$  and  $\|\nabla\cdot\|_p$  are equivalent norms on  $W_0^{1,p}(\Omega)$  if  $\Omega$  is bounded.

**Theorem 10** (22). Let  $p \in [1, d)$ , d > 2,  $\Omega \subset \mathbb{R}^d$  bounded with  $C^1$  boundary. Then

 $\exists C_p > 0, \forall u \in W^{1,p}(\Omega) : \|u\|_{L^{p^*}(\Omega)} \le C_p \|u\|_{W^{1,p}(\Omega)}.$ 

**Lemma 9** (24). (5, Lemma 7.16) Let  $u \in C^1(\mathbb{R}^d)$ ,  $\Omega \subset \mathbb{R}^d$  bounded convex,  $x \in \Omega$ . Then

$$|u(x) - \int_{\Omega} u| \leq \frac{R^d}{d|\Omega|} \int_{\Omega} |\nabla u(y)| |y - x|^{1-d} \,\mathrm{d}\, y.$$

**Theorem 11** (25-Sobolev-Poincaré inequality). Let  $\Omega \subset \mathbb{R}^d$  be bounded and convex. Then

$$\forall q < p^*, \exists C > 0, \forall u \in W^{1,p}(\Omega) : \|u - \int_{\Omega} u\|_{L^q(\Omega)} \le C \|\nabla u\|_{L^p(\Omega)}.$$

**Remark 5.** (3, Corollary 4.2.3) Previous theorem holds also if  $p \ge 1$  and  $q = p^*$ .

**Lemma 10** (26). Let  $u \in C_c^1(\mathbb{R}^d)$ ,  $\alpha = 1 - \frac{d}{p}$ . Then

$$\forall x, y \in \mathbb{R}^d : \frac{|u(x) - u(y)|}{|x - y|^{\alpha}} \le C(p, d) \|\nabla u\|_{L^p(\mathbb{R}^d)}, \quad |u(x)| \le C(p, d) \|u\|_{W^{1, p}(\mathbb{R}^d)}.$$

**Definition 7.** We define for  $\alpha \in (0,1]$  and  $f: \Omega \to \mathbb{R}$  a

$$[f]_{C^{0,\alpha}(\overline{\Omega})} := \sup\{\frac{|f(x) - f(y)|}{|x - y|^{\alpha}}; x, y \in \Omega, x \neq y\},\\ \|f\|_{C^{0,\alpha}(\Omega)} = \|f\|_{L^{\infty}(\Omega)} + [f]_{C^{0,\alpha}(\overline{\Omega})}.$$

We define  $C^{0,\alpha}(\overline{\Omega}) = \{f: \Omega \to \mathbb{R}; \|f\|_{C^{0,\alpha}(\overline{\Omega})} < +\infty\}.$ 

**Theorem 12** (27). (6, Theorem 1.3.3) Let  $\alpha \in (0, 1]$ . The space  $(C^{0,\alpha}(\overline{\Omega}), \|\cdot\|_{0,\alpha})$  is a Banach space.

**Theorem 13** (28). Let  $p \in (d, +\infty]$ ,  $\alpha = 1 - \frac{d}{p}$ , then  $W^{1,p}(\mathbb{R}^d) \hookrightarrow C^{0,\alpha}(\mathbb{R}^d)$ .

**Theorem 14** (29). Let  $p \in (d, +\infty]$ ,  $\Omega \subset \mathbb{R}^d$  bounded with  $C^1$  boundary. Then  $W^{1,p}(\Omega) \hookrightarrow C^{0,\alpha}(\overline{\Omega})$ .

**Theorem 15** (30). (4, Theorem 5.5.1) Let  $d \in \{2, ...\}$ ,  $\Omega \subset \mathbb{R}^d$  be bounded with  $C^1$  boundary,  $p \in [1, +\infty)$ ,  $p^{\#} = \frac{(d-1)p}{d-p}$  if p < d. Let

$$q \in \begin{cases} [1, p^{\#}] & \text{ if } p < d, \\ [1, +\infty) & \text{ if } p = d, \\ [1, +\infty] & \text{ if } p > d. \end{cases}$$

Then there is a bounded linear operator  $\operatorname{Tr} : W^{1,p}(\Omega) \to L^q(\partial\Omega)$  such that for  $f \in C^{\infty}(\overline{\Omega})$  the equality  $\operatorname{Tr} f = f|_{\partial\Omega}$  holds on  $\partial\Omega$ .

**Theorem 16** (31). (2, Theorem 6.2), (2, Theorem 5.4) Let  $d \in \{2, ...\}$ ,  $\Omega \subset \mathbb{R}^d$  be bounded with  $C^1$  boundary,  $p \in [1, +\infty)$ .

case 
$$p < d$$
 — If  $q \in [1, p^*)$  the embedding  $W^{1,p}(\Omega) \hookrightarrow L^q(\Omega)$  is compact.  
— If  $q \in [1, p^{\#})$  the embedding  $W^{1,p}(\Omega) \hookrightarrow L^q(\partial\Omega)$  is compact.

 $\begin{array}{ll} case \ p=d & - \ I\!f \ q \in [1,+\infty) \ the \ embeddings \ W^{1,p}(\Omega) \ \hookrightarrow \ L^q(\Omega) \ and \ W^{1,p}(\Omega) \ \hookrightarrow \\ L^q(\partial\Omega) \ are \ compact. \end{array}$ 

case 
$$p > d$$
 – If  $\alpha \in [0, 1 - \frac{d}{p})$  the embedding  $W^{1,p}(\Omega) \hookrightarrow C^{0,\alpha}(\overline{\Omega})$  is compact.  
– If  $\alpha \in [0, 1 - \frac{d}{p})$  the embeddings  $W^{1,p}(\Omega) \hookrightarrow C^{0,\alpha}(\partial\Omega)$  is compact.

This theorem was presented in a different form without proof.

**Theorem 17** (32). Let  $\Omega$  be bounded with  $C^1$  boundary,  $p \in [1, +\infty)$ . Then

$$W_0^{1,p}(\Omega) = \{ u \in W^{1,p}(\Omega) | \operatorname{Tr} u = 0 \text{ on } \partial\Omega. \}$$

#### 2.4 Difference quotients and weak derivatives

**Definition 8.** Let  $u \in L^1_{loc}(\Omega)$ ,  $i \in \{1, \ldots, d\}$ . The *i*-th difference quotient of size  $h \in \mathbb{R} \setminus \{0\}$  is  $D^h_i u(x) = \frac{1}{h}(u(x+he_i)-u(x))$  for  $x \in \Omega$  s.t.  $x+he_i \in \Omega$ .

**Theorem 18** (32). *i)* Let  $p \in [1, +\infty)$ ,  $u \in W^{1,p}(\Omega)$ . Then there is C > 0 such that for all  $V \subseteq \Omega$ ,  $i \in \{1, \ldots, d\}$ ,  $|h| < \frac{1}{2}(\operatorname{dist}(V, \partial\Omega))$  there holds  $\|D_i^h u\|_{L^p(V)} \leq C \|\partial_i u\|_{L^p(\Omega)}$ .

ii) Let  $p \in (1, +\infty)$ ,  $u \in L^p(\Omega)$  and there is C > 0,  $V \Subset \Omega$ ,  $i \in \{1, \ldots, d\}$ such that for all  $|h| < \frac{1}{2}(\operatorname{dist}(V, \partial \Omega))$  there holds  $\|D_i^h u\|_{L^p(V)} \leq C$ . Then the weak derivative  $\partial_i u$  exists and  $\|\partial_i u\|_{L^p(V)} \leq C$ .

## 3 Linear elliptic PDE's of second order

In this section we will assume

**Assumption 1** (33). The set  $\Omega$  and functions  $A = (a_{ij})_{i,j=1}^d : \Omega \to \mathbb{R}^{d \times d}$ ,  $b = (b_i)_{i=1}^d : \Omega \to \mathbb{R}^d$ ,  $c, f : \Omega \to \mathbb{R}$ ,  $g, u_0 : \partial\Omega \to \mathbb{R}$  are given with the following properties.

- $\Omega \subset \mathbb{R}^d$  with  $C^1$  boundary, a bounded domain
- there is  $\alpha > 0$  such that for all  $\xi \in \mathbb{R}^d$  and a.e.  $x \in \Omega$  there holds  $\alpha |\xi|^2 \leq A\xi \cdot \xi$
- for all  $i, j \in \{1, \ldots, d\}$  there holds  $a_{ij}, b_i, c \in L^{\infty}(\Omega)$
- $f \in L^2(\Omega)$
- $g \in L^2(\partial \Omega)$
- $u_0$  is a trace of a function from  $W^{1,2}(\Omega)$ , we denote it again  $u_0 \in W^{1,2}(\Omega)$

We will study the equation

$$-\operatorname{div}(A\nabla u) + b \cdot \nabla u + cu = f \quad \text{in } \Omega \tag{3}$$

with two types of boundary conditions. We will prescribe either Dirichlet boundary condition

$$u = u_0 \quad \text{on } \partial\Omega \tag{4}$$

or Neumann boundary condition

 $A\nabla u \cdot \nu = g$  on  $\partial\Omega$ , here  $\nu$  denotes the normal unit vector to  $\Omega$ . (5)

**Definition 9.** We say that  $u : \Omega \to \mathbb{R}$  is a weak solution to the problem (3) with the boundary condition (4) if  $u \in W^{1,2}(\Omega)$ ,  $u - u_0 \in W^{1,2}_0(\Omega)$ , i.e. Tr  $u = u_0$ , and

$$\forall \varphi \in W_0^{1,2}(\Omega) : \int_{\Omega} A \nabla u \cdot \nabla \varphi + b \cdot \nabla u \varphi + c u \varphi = \int_{\Omega} f \varphi.$$
 (6)

We say that  $u : \Omega \to \mathbb{R}$  is a weak solution to the problem (3) with the boundary condition (5) if  $u \in W^{1,2}(\Omega)$  and

$$\forall \varphi \in W^{1,2}(\Omega) : \int_{\Omega} A \nabla u \cdot \nabla \varphi + b \cdot \nabla u \varphi + c u \varphi = \int_{\Omega} f \varphi + \int_{\partial \Omega} g \operatorname{Tr}(\varphi).$$
(7)

#### 3.1 Existence of a weak solution by Riesz Theorem

**Theorem 19.** (7, Theorem 19) Let H be a real Hilbert space. Define for  $y \in H$ ,  $f_y \in H^*$  by  $f_y(x) = \langle x, y \rangle$  for all  $x \in H$ . The mapping  $I : H \to H^*$ ,  $I(y) = f_y$  is linear isometry of H onto  $H^*$ .

**Theorem 20** (35). Let Assumption 1 hold. Moreover let for all  $i, j \in \{1, ..., d\}$ and a.e.  $x \in \Omega$   $a_{ij}(x) = a_{ji}(x)$ , b(x) = 0.

- 1. Then there is  $\gamma < 0$  such that if  $c > \gamma$  on  $\Omega$  then a weak solution of (3) and (4) exists. It satisfies  $\|u\|_{W^{1,2}(\Omega)} \leq C(\|f\|_{L^2(\Omega)} + \|u_0\|_{W^{1,2}(\Omega)})$  for a suitable C > 0 independent of f and  $u_0$ .
- 2. If c > 0 on  $\Omega$  then there is a weak solution of (3) and (5). It satisfies  $\|u\|_{W^{1,2}(\Omega)} \leq C(\|f\|_{L^2(\Omega)} + \|g\|_{L^2(\partial\Omega)})$  for a suitable C > 0 independent of f and g.

The solutions are unique.

**Lemma 11** (36 Lax Milgram). (4) Let H be a real Hilbert space with a scalar product  $\langle \cdot, \cdot \rangle_H$  and an induced norm  $\|\cdot\|_H$ . Let  $B : H \times H \to \mathbb{R}$  be a bilinear mapping that is

- (elliptic)  $\exists m > 0, \forall u \in H : m ||u||_{H}^{2} \leq B(u, u)$
- (bounded)  $\exists M > 0, \forall u, v \in H : B(u, v) \le M \|u\|_H \|v\|_H$

Then for every  $F \in H^*$  there is a unique  $u \in H$  such that  $\forall v \in H : B(u, v) = F(v)$ . Moreover,  $\|u\|_H \leq \frac{1}{m} \|F\|_{H^*}$ .

**Theorem 21** (37). Let Assumption 1 hold. Then there is  $\gamma \in \mathbb{R}$  such that if  $c > \gamma$  on  $\Omega$  then there is a weak solution u of (3) and (4) or (5). The solution is unique and satisfies  $||u||_{W^{1,2}(\Omega)} \leq C(||f||_{L^2(\Omega)} + ||u_0||_{W^{1,2}(\Omega)})$ , resp.  $||u||_{W^{1,2}(\Omega)} \leq C(||f||_{L^2(\Omega)} + ||g||_{L^2(\Omega)}).$ 

**Theorem 22** (38). *Let* 

- $A: \mathbb{R}^d \to \mathbb{R}^{d \times d}, b: \mathbb{R}^d \to \mathbb{R}^d, c, f: \mathbb{R}^d \to \mathbb{R}$
- $A, b, c \in L^{\infty}(\mathbb{R}^d), f \in L^2$

There is  $\gamma \in \mathbb{R}$  such that  $c > \gamma$  implies existence of  $u \in W^{1,2}(\mathbb{R}^d)$  such that

$$\forall \varphi \in W^{1,2}(\mathbb{R}^d) : \int_{\mathbb{R}^d} A \nabla u \cdot \nabla \varphi + b \cdot \nabla u \varphi + c u \varphi = \int_{\mathbb{R}^d} f \varphi.$$

The solution is unique and  $||u||_{W^{1,2}(\mathbb{R}^d)} \leq C ||f||_{L^2(\mathbb{R}^d)}$ .

#### 3.2 Application of Fredholm Theorems

We introduce the differential operator

$$Lu = -\operatorname{div}(A\nabla u) + b \cdot \nabla u + cu - \operatorname{div}(du)$$
(8)

and its formal adjoint

$$L^*u = -\operatorname{div}(A^T \nabla u) + d \cdot \nabla u + cu - \operatorname{div}(bu)$$
(9)

We consider here only homogeneous Dirichlet boundary condition u = 0 on  $\partial \Omega$ .

If we assume sufficient regularity of functions c and d we may apply the theory developed in the previous section to get existence of a weak solutions to the problem Lu = f in  $\Omega$  and u = 0 on  $\partial\Omega$ . The statement  $u \in W_0^{1,2}(\Omega)$  solves the problem Lu = f in  $\Omega$  with the boundary condition u = 0 on  $\partial\Omega$  is understood in the weak sense in what follows.

We will assume that Assumption 1 hold and moreover for simplicity  $b, d, \in W^{1,\infty}(\Omega)$ .

- **Theorem 23** (39-Fredholm alternative). 1. (a) Either for all  $f \in L^2(\Omega)$ there exists a unique  $u \in W_0^{1,2}(\Omega)$  a weak solution of Lu = f in  $\Omega$ , u = 0 on  $\partial\Omega$ 
  - (b) or there is  $u \in W_0^{1,2}(\Omega) \setminus \{0\}$  a weak solution of Lu = 0 in  $\Omega$ , u = 0 on  $\partial\Omega$ .
  - 2. In case 1b) denote  $\operatorname{Ker} L = \{u \in W_0^{1,2}(\Omega); Lu = 0\} \neq \emptyset$ ,  $\operatorname{Ker} L^* = \{u \in W_0^{1,2}(\Omega); L^*u = 0\}$ . Then dim  $\operatorname{Ker} L = \dim \operatorname{Ker} L^*$ .
  - 3. In case 1b) there is a weak solution to Lu = f in  $\Omega$ , u = 0 on  $\partial\Omega$  if  $f \in L^2(\Omega)$  and for all  $\varphi \in \text{Ker } L^*$ ,  $\int_{\Omega} f\varphi = 0$ .

**Theorem 24** (40). (4, Section 6.2, Theorem 5) Let  $\Omega$  be a bounded domain. There is at most countable set  $\Sigma \subset \mathbb{R}$  such that the following is equivalent:

- 1.  $\lambda \notin \Sigma$
- 2.  $\forall f \in L^2(\Omega), \exists ! u \in W_0^{1,2}(\Omega)$  a weak solution of the problem  $Lu = \lambda u + f$ in  $\Omega, u = 0$  on  $\partial \Omega$ .

If  $\Sigma$  is not finite, then  $+\infty$  is its only cluster point.

**Remark 6.** The set  $\Sigma$  is called (real) spectrum of L.

**Theorem 25** (41). Let the operator L satisfy: A be symmetric ( $\forall i, j \in \{1, ..., d\}$ :  $a_{ij} = a_{ji}$ ),  $\forall j \in \{1, ..., d\}$ :  $b_j = d_j$ . Let  $\Sigma$  be the set from Theorem 24. Then

- 1.  $\Sigma$  is infinite. If we denote  $\Sigma = \{\lambda_k\}_{k=1}^{+\infty}$  then  $\lambda_k \to +\infty$  as  $k \to +\infty$ .
- 2. There exists an orthonormal basis  $\{w_k\}_{k=1}^{+\infty}$  of  $L^2(\Omega)$  such that  $w_k \in W^{1,2}(\Omega)$  and it solves  $Lw_k = \lambda w_k$  in  $\Omega$ ,  $w_k = 0$  on  $\partial\Omega$  for some  $\lambda \in \Sigma$ .

3. If b = d = 0 and  $c \ge 0$  on  $\Omega$ , then  $\Sigma \subset (0, +\infty)$ .

**Theorem 26** (43-maximum principle). Let  $u_0 \in L^{\infty}(\partial\Omega) \cap \operatorname{Tr}(W^{1,2}(\Omega)), c \geq 0$ on  $\Omega$  and  $u \in W^{1,2}(\Omega)$  is a weak solution to  $-\operatorname{div}(A\nabla u) + cu = 0$  in  $\Omega$ ,  $u = u_0$ on  $\partial\Omega$ . Then  $u \in L^{\infty}(\Omega)$  and  $||u||_{L^{\infty}} \leq ||u_0||_{L^{\infty}(\partial\Omega)}$ .

**Theorem 27** (44). Let  $a_{ij} \in C^1(\overline{\Omega})$ ,  $b_i, c \in L^{\infty}(\Omega)$  for all  $i, j \in \{1, \ldots, d\}$ ,  $f \in L^2(\Omega)$ ,  $u \in W^{1,2}(\Omega)$  be a weak solution of Lu = f in  $\Omega$ , u = 0 on  $\partial\Omega$ . Then  $u \in W^{1,2}(\Omega)$  and  $\|u\|_{W^{2,2}(\Omega)} \leq C(\|f\|_{L^2(\Omega)} + \|u\|_{L^2(\Omega)})$ . The constant C > 0 is independent of f and u.

## 4 Nonlinear elliptic PDE's of second order

#### 4.1 Basics of Calculus of Variations

Setting:

- 1.  $\Omega \subset \mathbb{R}^d$  open bounded set with smooth boundary
- 2.  $L: \mathbb{R}^d \times \mathbb{R} \times \overline{\Omega} \to \mathbb{R}$  a function called Lagrangian,  $L = L(p, z, x), \ p \in \mathbb{R}^d, \ z \in \mathbb{R}, \ x \in \Omega.$
- 3.  $g: \partial \Omega \to \mathbb{R}$

We are looking for a minimizer of

$$I(w) = \int_{\Omega} L(\nabla w(x), w(x), x) \, \mathrm{d} \, x$$

on the set of functions  $X = \{w; w = g \text{ on } \partial \Omega\}.$ 

We will assume coercivity of L

$$\exists q \in (1, +\infty), \exists \alpha > 0, \beta \ge 0, \forall p \in \mathbb{R}^d, z \in \mathbb{R}, x \in \Omega : L(p, z, x) \ge \alpha |p|^q - \beta.$$
(10)

**Remark 7.** • If L is coercive then  $I(w) \to +\infty$  as  $\|\nabla w\|_{L^q(\Omega)} \to +\infty$ .

•

$$\inf_{w \in X} I(w) = \inf\{I(w); w \in X, \|\nabla w\|_q \le \left(\frac{2L(w_0) + \beta'}{\alpha'}\right)^{\frac{1}{q}}\}$$

for any  $w_0 \in X$  and suitable  $\alpha'$  and  $\beta'$ .

**Definition 10.**  $X = \{ w \in W^{1,q}(\Omega); \text{ Tr } w = g \text{ on } \partial \Omega \}.$ 

**Lemma 12** (45). Let R > 0,  $A = \{w \in X; \|\nabla w\|_{L^q(\Omega)} < R\}$ , then there is R' > 0 such that  $A \subset U(0, R') \subset W^{1,q}(\Omega)$ .

**Corollary 3** (46). Choose  $w_k \subset X$  such that  $I(w_k) \to \inf_{w \in X} I(w)$ , then  $\exists R' > 0, \forall k \in : ||w_k||_{1,q} \leq R'$ , i.e. minimizing sequences are bounded.

**Definition 11.** We say that I is weakly sequentially lower semicontinuous on  $W^{1,q}(\Omega)$  if  $I(u) \leq \liminf_{k \to +\infty} I(w_k)$ , whenever  $w_k \rightharpoonup u$  in  $W^{1,q}(\Omega)$ .

**Theorem 28** (47). Assume that L is smooth ( $C^2$  is definitely enough/too much), bounded below and in addition

the mapping 
$$p \to L(p, z, x)$$
 is convex for any  $z \in \mathbb{R}, x \in \Omega$ . (11)

Then I is weakly sequentially lower semicontinuous on  $W^{1,q}(\Omega)$ .

**Theorem 29** (48). Assume that L satisfies the coercivity condition (10), and is convex with respect to the variable p, see (11), and X is not empty. Then there is (at least one) function  $u \in X$  solving  $I(u) = \inf_{w \in X} I(w)$ .

**Theorem 30** (49). Suppose that L is smooth and independent of z and

$$\exists q > 1, \theta > 0, \forall p \in \mathbb{R}^d, \xi \in \mathbb{R}^d, x \in \Omega : \sum_{i,j=1}^d \partial_{p_i} \partial_{p_j} L(p,x) \xi_i \xi_j \ge \theta |\xi|^q.$$

Then there is at most one minimizer of I.

*Proof.* Theorem was presented in a student's presentation.

**Definition 12.** We say that  $u \in X$  is a weak solution to the boundary value problem

$$-\operatorname{div} \nabla_p L(\nabla u, u, x) + \partial_z L(\nabla u, u, x) = 0 \quad in \ \Omega,$$
(12)

with boundary condition u = g on  $\partial \Omega$  for the Euler Lagrange equation provided

$$\forall v \in W_0^{1,q}(\Omega) : \int_{\Omega} \nabla_p L(\nabla u, u, x) \cdot \nabla v + \partial_z L(\nabla u, u, x)v = 0.$$

**Theorem 31** (50). Assume L verifies the growth conditions

$$\exists C > 0, \forall p \in \mathbb{R}^d, z \in \mathbb{R}, x \in \Omega : |L(p, z, x)| \le C(|p|^q + |z|^q + 1) \\ \exists C > 0, \forall p \in \mathbb{R}^d, z \in \mathbb{R}, x \in \Omega : |\nabla_p L(p, z, x)| + |\nabla_z L(p, z, x)| \le C(|p|^{q-1} + |z|^{q-1} + 1)$$

and  $u \in X$  satisfies  $I(u) = \inf_{w \in X} I(w)$ . Then u is a weak solution of (12).

*Proof.* Just a sketch of a proof. Computation was shown in a presentation but without precise reasoning for interchange of limit passage and integration.  $\Box$ 

#### 4.2 Existence of a weak solution by method of Brower and Minty

Assumption 2 (51). Let  $a: \Omega \times \mathbb{R} \times \mathbb{R}^d \to \mathbb{R}^d$ , q > 1 satisfy

• a is a Caratheodory function, i.e. for a.e.  $x \in \Omega$  the mapping  $(z, p) \rightarrow a(x, z, p)$  is continuous and for all  $z \in \mathbb{R}, p \in \mathbb{R}^d$  the mapping  $x \rightarrow a(x, z, p)$  is measurable

- (boundedness)  $\exists C > 0, \forall x \in \Omega, z \in \mathbb{R}, p \in \mathbb{R}^d : |a(x, z, p)| \le C(1+|p|)^{q-1}$
- (coercivity)  $\exists C_1, C_2 > 0, \forall x \in \Omega, z \in \mathbb{R}, p \in \mathbb{R}^d : C_1 |p|^q c_2 \le a(x, z, p) \cdot p.$
- (monotony)  $\forall x \in \Omega, z \in \mathbb{R}, p_1, p_2 \in \mathbb{R}^d : (a(x, z, p_1) a(x, z, p_2)) \cdot (p_1 p_2) \ge 0$
- **Remark 8.** Monotony is an assumption of a similar type as convexity in variational techniques.
  - Coercivity was needed also for variational techniques.
  - Boundedness was not needed for variational techniques.

We consider the next problem: for a given a, f and  $u_0$  find a solution u to the partial differential equation

$$-\operatorname{div} a(x, u, \nabla u) = f \quad \text{in } \Omega \tag{13}$$

with Dirichlet boundary condition  $u = u_0$  on  $\partial \Omega$ .

**Definition 13** (weak formulation of (13)). Let  $f \in W_0^{1,q}(\Omega)^*$ ,  $u_0 : \partial\Omega \to \mathbb{R}$ and  $a : \Omega \times \mathbb{R} \times \mathbb{R}^d \to \mathbb{R}^d$ . We call  $u \in W^{1,q}(\Omega)$  a weak solution of the problem (13) with boundary condition  $u = u_0$  on  $\partial\Omega$  if  $\operatorname{Tr} u = u_0$  on  $\partial\Omega$  and

$$\forall \varphi \in W^{1,q}_0(\Omega) : \int_\Omega a(x,u,\nabla u) \cdot \nabla \varphi = \rangle f, \varphi \langle .$$

Remark 9. Under Assumption 2 all terms in the definition are well defined.

**Theorem 32** (52). If  $f \in (W_0^{1,q})^*$ , Assumption 2 holds and  $u_0 \in W^{1,q}(\Omega)$ , then there is a weak solution of the problem (13) with boundary condition  $u = u_0$  on  $\partial\Omega$ .

**Lemma 13.** Let R > 0,  $m \in \mathbb{N}$ ,  $\Phi : \mathbb{R}^m \to \mathbb{R}^m$  be continuous such that for all  $c \in \partial U(0, R) : \Phi(c) \cdot c \geq 0$ . Then there is a  $c_0 \in \overline{U(0, R)}$  such that  $\Phi(c_0) = 0$ .

*Proof.* The proof rests on Brower fixed point theorem but was not presented.  $\Box$ 

**Theorem 33** (53). Let assumptions of Theorem 32 hold. Let a be independent of z, i.e.  $a: \Omega \times \mathbb{R}^d \to \mathbb{R}^d$ , a = a(x, p), and strictly monotone in p, i.e.

$$\forall p_1, p_2 \in \mathbb{R}^d, p_1 \neq p_2, a.e. \ x \in \Omega : (a(x, p_1) - a(x, p_2)) \cdot (p_1 - p_2) > 0.$$

Then the weak solution to the problem (13) with the boundary condition  $u = u_0$ in  $\partial \Omega$  is unique.

*Proof.* Will be proved in presentation.

## 5 Did not fit into schedule

**Theorem 34** (54-Maximum principle). Let Assumption 2 hold, a be strictly monotone in p, for all  $z \in \mathbb{R}$  and a.e.  $x \in \Omega$  a(x, z, 0) = 0, f = 0 and  $u_0 \in L^{\infty}(\partial\Omega) \cap \operatorname{Tr} W^{1,q}(\Omega)$ . Let  $u \in W^{1,q}(\Omega)$  be a weak solution to (13) with the boundary condition  $u = u_0$  on  $\partial\Omega$ . Then  $u \in L^{\infty}(\Omega)$  and  $\|u\|_{L^{\infty}(\Omega)} \leq \|u_0\|_{L^{\infty}(\partial\Omega)}$ .

*Proof.* The theorem was not presented.

**Theorem 35** (55-local regularity). Let Assumption 2 hold, a be independent of z and x, f = 0 and

$$\begin{aligned} \exists \theta > 0, \forall p_1, p_2 \in \mathbb{R}^d : (a(p_1) - a(p_2)) \cdot (p_1 - p_2) \ge \theta(|p_1| + |p_2|)^{q-2} |p_1 - p_2|^2 \\ \exists C > 0, \forall p_1, p_2 \in \mathbb{R}^d : |a(p_1) - a(p_2)| \le C(|p_1| + |p_2|)^{q-2} |p_1 - p_2|. \end{aligned}$$

Let  $u \in W^{1,q}(\Omega)$  be a weak solution to (13) with the boundary condition  $u = u_0$ on  $\partial\Omega$  and B be a ball of radius R > 0 such that  $B \subset 2B \subset \Omega$ . Then  $|\nabla u|^{\frac{q}{2}} \in W^{1,2}(B)$  and

$$\int_{B} |\nabla|\nabla u|^{\frac{q}{2}}|^{2} \leq \frac{C}{R^{2}} \int_{2B} |\nabla u|^{q}.$$

Proof. Theorem was not presented.

# 5.1 Existence of a weak solution by Banach fixed point theorem

**Theorem 36** (56-nonlinear Lax Milgram). Let X be a real Hilbert space,  $T : X \to X$  Lipschitz continuous, i.e.

$$\exists M > 0, u, v \in X : \|Tu - Tv\|_X \le M \|u - v\|_X$$

and strongly monotone, i.e.

$$\exists m > 0, \forall u, v \in X : (Tu - Tv, u - v)_X \ge m \|u - v\|_X^2.$$

Then for any  $F \in X$  exists a unique  $u \in X$  such that Tu = F.

*Proof.* The theorem was not presented.

**Example 3.** For any  $f \in L^2(\Omega)$  there is a weak solution to the problem  $-\operatorname{div}\left(\operatorname{arctg}(1+|\nabla u|^2)\nabla u\right) = -\operatorname{div} f$  in  $\Omega$  with homogeneous Dirichlet boundary condition u = 0 on  $\partial\Omega$ .

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*Proof.* The example was not presented.

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