

Week 6:

Box-Jenkins methodology

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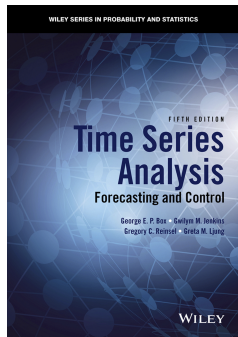
- ▶ AutoRegressive Integrated Moving Average (ARIMA) models
- ▶ 1970s, popularized by Box and Jenkins
- ▶ rely on autocorrelation patterns in the data

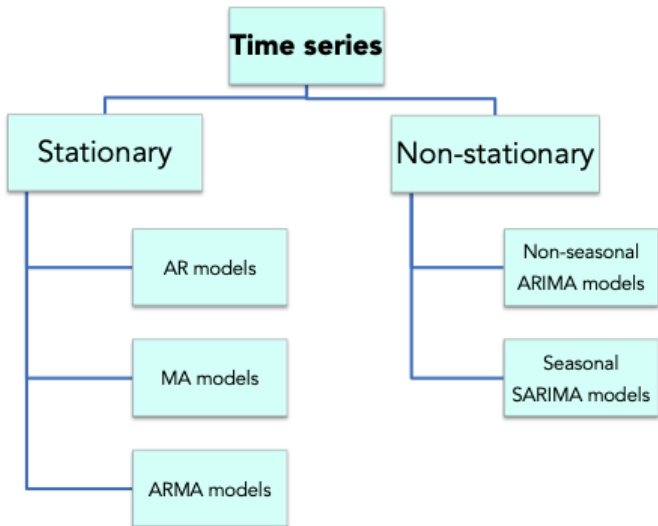


George E. P. Box
1919 – 2013



Gwilym M. Jenkins
1932 – 1982





Notions and definitions from Stochastic Processes II

Time series $\{Y_t\}$

- ▶ strict stationarity
- ▶ (weak) stationarity
- ▶ white noise WN
- ▶ autocovariance function $\{\gamma_k\}$
- ▶ autocorrelation function (ACF) $\{\rho_k\}$
- ▶ partial autocorrelation function (PACF) $\{\rho_{kk}\}$

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- ▶ Hilbert space $L_2 = \{X : \text{random variable } EX^2 < \infty\}$ with inner product

$$\langle X, Y \rangle = EXY$$

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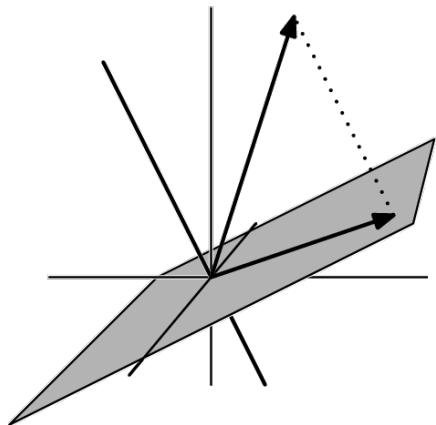
- ▶ orthogonality: $X \perp Y$ if $\langle X, Y \rangle = 0$
- ▶ projection on subspace \mathcal{H} :

$$X = \underbrace{P_{\mathcal{H}}X}_{\in \mathcal{H}} + \underbrace{(X - P_{\mathcal{H}}X)}_{\perp \mathcal{H}}$$

and

$$\|X - P_{\mathcal{H}}X\|^2 = \min_{Y \in \mathcal{H}} \|X - Y\|^2$$

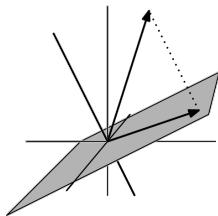
Projection principal



$$X - P_{\mathcal{H}}X \perp V \quad \text{for all } V \in \mathcal{H}$$

Projection principal II.

Let $\{Y_t\}$ be a stochastic process and $\mathcal{H} = \mathcal{H}_1^k = \{\sum_{i=1}^k c_i Y_i\}$.



Then

$$P_{\mathcal{H}}X = \sum_{i=1}^k \beta_i Y_i,$$

where β_1, \dots, β_k minimize $E(X - \sum_{i=1}^k \alpha_i Y_i)^2$ among all linear combinations. Computation of β 's:

$$\langle X - \sum_{i=1}^k \beta_i Y_i, Y_j \rangle = 0, \quad \text{for all } j = 1, \dots, k,$$

$$E(X - \sum_{i=1}^k \beta_i Y_i) Y_j = 0$$

Partial ACF

$\{Y_t\}$ weakly stationary, centered:

$$\rho_{kk} = \text{cor}(Y_{k+1} - \hat{Y}_{k+1}, Y_1 - \hat{Y}_1),$$

where

$$\hat{Y}_{k+1} = P_{\mathcal{H}_2^k} Y_{k+1},$$

$$\hat{Y}_1 = P_{\mathcal{H}_2^k} Y_1,$$

with

$$\dots, Y_1, \underbrace{Y_2, Y_3, \dots, Y_k}_{\mathcal{H}_2^k}, Y_{k+1}, \dots$$

Recall $P_{\mathcal{H}_2^k} Y_{k+1} = \sum_{i=2}^k \beta_i Y_i$, such that β_2, \dots, β_k minimize $E(Y_{k+1} - \sum_{i=2}^k \alpha_i Y_i)^2$ among all linear combinations.

Alternative definition of partial ACF

If

$$P_{\mathcal{H}_1^k} Y_{k+1} = \phi_1 Y_k + \phi_2 Y_{k-1} + \cdots + \phi_k Y_1,$$

then

$$\rho_{kk} = \phi_k.$$

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then

$$\rho_{kk} = \phi_k.$$

Computation: The projection implies

$$\langle Y_{k+1} - P_{\mathcal{H}_1^k} Y_{k+1}, Y_j \rangle = 0, \quad j = 1, \dots, k,$$

which gives

$$\begin{pmatrix} \rho_1 \\ \rho_2 \\ \vdots \\ \rho_k \end{pmatrix} = \begin{pmatrix} \rho_0 & \rho_1 & \rho_2 & \cdots & \rho_{k-1} \\ \rho_1 & \rho_0 & \rho_1 & \cdots & \rho_{k-2} \\ \vdots & & & & \\ \rho_{k-1} & \rho_{k-2} & \rho_{k-3} & \cdots & \rho_0 \end{pmatrix} \begin{pmatrix} \phi_1 \\ \phi_2 \\ \vdots \\ \phi_k \end{pmatrix} \quad (1)$$

\rightsquigarrow solve to get $\rho_{kk} = \phi_k$

Notions and definitions

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Sample estimates

- ▶ sample mean
- ▶ sample autocovariance function $\{c_k\}$
- ▶ sample ACF $\{r_k\}$
- ▶ sample PACF $\{r_{kk}\}$

Practical recommendation: $n > 50$, $k < n/4$

Sample PACF

PACF

$$\begin{pmatrix} \rho_0 & \rho_1 & \rho_2 & \dots & \rho_{k-1} \\ \rho_1 & \rho_0 & \rho_1 & \dots & \rho_{k-2} \\ \vdots & & & & \\ \rho_{k-1} & \rho_{k-2} & \rho_{k-3} & \dots & \rho_0 \end{pmatrix}^{-1} \begin{pmatrix} \rho_1 \\ \rho_2 \\ \vdots \\ \rho_k \end{pmatrix} = \begin{pmatrix} \phi_1 \\ \phi_2 \\ \vdots \\ \phi_k \end{pmatrix}$$

↪ Sample PACF: replace ρ_k by r_k ,

Sample PACF

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↪ Sample PACF: replace ρ_k by r_k , i.e.

$$\begin{pmatrix} 1 & r_1 & r_2 & \dots & r_{k-1} \\ r_1 & 1 & r_1 & \dots & r_{k-2} \\ \vdots & & & & \\ r_{k-1} & r_{k-2} & r_{k-3} & \dots & 1 \end{pmatrix}^{-1} \begin{pmatrix} r_1 \\ r_2 \\ \vdots \\ r_k \end{pmatrix} = \begin{pmatrix} \hat{\phi}_1 \\ \hat{\phi}_2 \\ \vdots \\ r_{kk} \end{pmatrix}$$

Sample PACF

PACF

$$\begin{pmatrix} \rho_0 & \rho_1 & \rho_2 & \dots & \rho_{k-1} \\ \rho_1 & \rho_0 & \rho_1 & \dots & \rho_{k-2} \\ \vdots & & & & \\ \rho_{k-1} & \rho_{k-2} & \rho_{k-3} & \dots & \rho_0 \end{pmatrix}^{-1} \begin{pmatrix} \rho_1 \\ \rho_2 \\ \vdots \\ \rho_k \end{pmatrix} = \begin{pmatrix} \phi_1 \\ \phi_2 \\ \vdots \\ \rho_{kk} \end{pmatrix}$$

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↪ recursive Durbin–Levinson Algorithm

Asymptotics for sample ACF for iid

Proposition. If $\{Y_t\}$ are iid and let K be fixed, then

$$\sqrt{n} \begin{pmatrix} r_1 \\ r_2 \\ \vdots \\ r_K \end{pmatrix} \xrightarrow{D} \mathbf{N}_K(\mathbf{0}, \mathbf{I}_K), \quad n \rightarrow \infty$$

Application

- ↪ for n large r_1, \dots, r_K approximately iid $\mathbf{N}(0, 1/n)$
- ↪ r_k lies outside $\left(-\frac{u_{0.975}}{\sqrt{n}}, \frac{u_{0.975}}{\sqrt{n}}\right)$ with asymptotic probability 5% for each $1 \leq k \leq K$, independently
- ↪ **bounds in plots**
- ↪ more general situation: Bartlett's formula (later)

Asymptotics for sample PACF for iid

If $\{Y_t\}$ are iid, then

$$\sqrt{n} \begin{pmatrix} \widehat{\phi}_1 \\ \widehat{\phi}_2 \\ \vdots \\ r_{kk} \end{pmatrix} = \underbrace{\begin{pmatrix} 1 & r_1 & r_2 & \dots & r_{k-1} \\ r_1 & 1 & r_1 & \dots & r_{k-2} \\ \vdots & & & & \\ r_{k-1} & r_{k-2} & r_{k-3} & \dots & 1 \end{pmatrix}^{-1}}_{\xrightarrow{P} I_K} \cdot \underbrace{\sqrt{n} \cdot \begin{pmatrix} r_1 \\ r_2 \\ \vdots \\ r_k \end{pmatrix}}_{\xrightarrow{D} N_K(\mathbf{0}, I_K)},$$

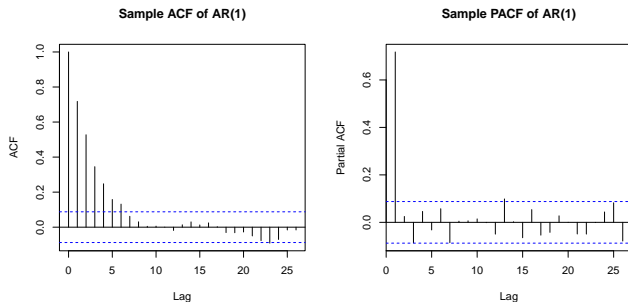
so

$$\sqrt{nr_{kk}} \xrightarrow{D} N(0, 1), \quad n \rightarrow \infty.$$

↪ more general situation: Quenouille's approximation (later)

Correlograms

- ▶ plot of $\{r_k\}$ or $\{r_{kk}\}$



- ▶ bounds:

$$\left(-\frac{u_{0.975}}{\sqrt{n}}, \frac{u_{0.975}}{\sqrt{n}} \right)$$

- ▶ try to determine the model from **truncation point** k_0
- ▶ now: basic TS models and how their $\{\rho_k\}$ and $\{\rho_{kk}\}$ look like

Basic models

Motivation: Wold decomposition: $\{Y_t\}$ is weakly stationary purely nondeterministic (i.e. it does not contain a component process whose future values can be perfectly predicted from the past values), then

$$Y_t = \sum_{i=1}^{\infty} \psi_i \varepsilon_{t-i} + \varepsilon_t,$$

where $\{\varepsilon_t\}$ is a WN, $\sum_{i=1}^{\infty} \psi_i^2 < \infty$.

Linear process: MA(∞) $Y_t = \sum_{i=1}^{\infty} \psi_i \varepsilon_{t-i} + \varepsilon_t$

\hookrightarrow if $\sum \psi_i^2 < \infty \rightsquigarrow$ convergence in mean square

\hookrightarrow if $\sum |\psi_i| < \infty \rightsquigarrow$ convergence almost surely

Linear process

Let $\sum_{i=1}^{\infty} |\psi_i| < \infty$, $\{\varepsilon_t\}$ WN

$$Y_t = \sum_{i=1}^{\infty} \psi_i \varepsilon_{t-i} + \varepsilon_t = \psi(\mathbf{B})\varepsilon_t$$

↪ B lag operator: $BX_t = X_{t-1}$, $B^k X_t = X_{t-k}$

↪

$$\psi(z) = \sum_{i=0}^{\infty} \psi_i z^i \quad \text{with } \psi_0 = 1$$

converges absolutely for all $|z| \leq 1$

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↪ invertible if

$$\varepsilon_t = \sum_{i=0}^{\infty} \pi_i Y_{t-i} = \pi(B)Y_t$$

with $\sum_{i=1}^{\infty} |\pi_i| < \infty$. If it holds then $\pi(z) = \psi(z)^{-1}$.

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↪ **useless model for practice**: infinite number of unknown ψ_i

Innovations

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- ▶ Let Y_t be invertible. Then

$$\varepsilon_t = Y_t - \sum_{i=1}^{\infty} \psi_i \varepsilon_{t-i} = Y_t - P_{\mathcal{H}_{-\infty}^{t-1}} Y_t$$

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- ▶ If $\{Y_t\}$ normal and $\mathcal{F}_{t-1} = \sigma\{Y_s, s \leq t-1\}$, then

$$P_{\mathcal{H}_{-\infty}^{t-1}} Y_t = E[Y_t | \mathcal{F}_{t-1}]$$

and

$$\varepsilon_t = Y_t - E[Y_t | \mathcal{F}_{t-1}]$$

$\rightsquigarrow \varepsilon_t$ corresponds to **unpredictable movements** in values of Y_t

Moving Average Process MA(q)

Let $\{\varepsilon_t\}$ WN($0, \sigma^2$):

$$Y_t = \sum_{i=1}^q \theta_i \varepsilon_{t-i} + \varepsilon_t = \theta(B)\varepsilon_t$$

for

$$\theta(z) = 1 + \theta_1 z + \cdots + \theta_q z^q$$

Properties:

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$$\frac{1}{\theta(z)}$$

analytic for $|z| \leq 1$, i.e. if the roots of $\theta(z)$ lie outside the unit circle

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- ▶ ACF:

$$\rho_k = 0 \text{ for } k > q$$

↪ truncation point $k_0 = q$

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\rightsquigarrow truncation point $k_0 = q$

- ▶ PACF: $\{\rho_{kk}\}$ no truncation point

Important Exercises

1. Consider MA(q) process $\{Y_t\}$.

- ▶ Compute EY_t , $\text{Var } Y_t$.
- ▶ Compute ACF ρ_k .

2. Consider MA(1) process $Y_t = \varepsilon_t + \theta_1\varepsilon_{t-1}$

- ▶ Express the ACF.
- ▶ Express the invertibility condition in terms of θ_1 .

3. Consider MA(2):

$$Y_t = \varepsilon_t + \theta_1\varepsilon_{t-1} + \theta_2\varepsilon_{t-2}$$

- ▶ Express the ACF.
- ▶ Express the invertibility condition in terms of the set for (θ_1, θ_2) .

PACF of MA

MA(1): $Y_t = \varepsilon_t + \theta_1 \varepsilon_{t-1}$

↪ then

$$\rho_{kk} = \frac{(-1)^{k+1} \theta_1^k (1 - \theta_1^2)}{1 - \theta_1^{2(k+1)}} = \frac{(-1)^{k+1} \theta_1^k}{1 + \theta_1^2 + \theta_1^4 + \dots + \theta_1^{2k}}$$

(not easy to show)

↪ no truncation point k_0

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MA(q):

↪ ρ_{kk} has no truncation point k_0

↪ $\rho_{kk} \rightarrow 0$ as $k \rightarrow \infty$

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MA(q):

↪ ρ_{kk} has no truncation point k_0

↪ $\rho_{kk} \rightarrow 0$ as $k \rightarrow \infty$

↪ ρ_{kk} *bounded by a linear combination of geometrically decreasing sequences and sinusoids with geometrically decreasing amplitudes*

(see shape of ACF for AR(p))

Autoregressive Process AR(p)

$$Y_t = \varphi_1 Y_{t-1} + \dots + \varphi_p Y_{t-p} + \varepsilon_t,$$

or

$$\varphi(B)Y_t = \varepsilon_t$$

for $\varphi(z) = 1 - \varphi_1 z - \dots - \varphi_p z^p$

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Properties:

- ▶ stationary if roots of $\varphi(z) = 0$ lie outside the unit circle
- ▶ in that case centered and

$$\text{Var}(Y_t) = \frac{\sigma^2}{1 - \varphi_1^2 - \dots - \varphi_p^2}$$

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 \rightsquigarrow no truncation point
- ▶ PACF

$$\rho_{kk} = 0 \quad \text{for } k > p$$

\rightsquigarrow truncation point $k_0 = p$

Important Exercises

1. Consider a stationary AR(p) process
 - ▶ Compute $\text{Var}(Y_t)$.
 - ▶ Derive the Yule Walker equations.
 - ▶ Discuss the form of $\{\rho_k\}$, i.e. the form of a solution of a general system of difference equations.

2. Consider an AR(1) model $Y_t = \varphi_1 Y_{t-1} + \varepsilon_t$.
 - ▶ Express the stationarity condition in terms of φ_1 .
 - ▶ Compute ACF.
 - ▶ Show that $\rho_{kk} = 0$ for $k > 1$.

3. Consider an AR(2) model $Y_t = \varphi_1 Y_{t-1} + \varphi_2 Y_{t-2} + \varepsilon_t$.
 - ▶ Express the stationarity condition in terms of φ_1 and φ_2 .
 - ▶ Compute ACF.
 - ▶ Show that $\rho_{kk} = 0$ for $k > 2$.