Universal algebra and the constraint satisfaction problem

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Common framework for many practical problems

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- This is the last time when the word "practical" appears

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 universal algebra (not just group or semigroup theory)
- Long term goal: go beyond CSP

Definition

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Instance of the CSP is a list of constraints – expression of the form $R_1(x, y, z), R_2(t, z), R_1(y, y, z), \ldots$ where R_i are relations on a common domain A(subsets of A^k or mappings $A^k \rightarrow \{true, false\}$). Assignment = mapping variables \rightarrow domain

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- Robust CSP: Find an almost satifying assignment given an almost satisfiable instance

Interesting subproblems ... restrict the set of allowed relations

Definition

 $\mathbb{A} = (A; R_1, R_2, \dots): \text{ relational structure with } A \text{ finite } \\ \begin{array}{l} \text{Instance of } CSP(\mathbb{A}): \text{ Expression of the form} \\ R_1(x, y, z), \ R_2(t, z), \ R_1(y, y, z), \ \dots \end{array} \\ \text{where each } R_i \text{ is in } \mathbb{A}. \end{array}$

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where each R_i is in \mathbb{A} .

- ▶ What is the computational complexity for fixed A?
- This talk: Mainly decision $CSP(\mathbb{A})$
- Other interesting problems:
 - restrict something else than the set of allowed relations
 - allow infinite A
 - ▶ allow weighted relations: mappigs $A^k \to Q \cup \{\infty\}$
 - (approximate) counting, Max-CSP, Approx Max-CSP

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Examples:

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► HORN-3-SAT: $\mathbb{A} = (\{0,1\}; x, \neg x, x \land y \rightarrow z)$

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- Digraph reachability: $\mathbb{A} = (\{0, 1\}; x, \neg x, x \leq y)$
- Graph reachability: $\mathbb{A} = (\{0,1\}, x, \neg x, x = y)$

$$\blacktriangleright (\mathsf{NP-c}) \ \mathsf{3-SAT}: \ \mathbb{A} = (\{0,1\}; x \lor y \lor z, x \lor y \lor \neg z, \dots)$$

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- ► (P-c) HORN-3-SAT: $\mathbb{A} = (\{0,1\}; x, \neg x, x \land y \rightarrow z)$
- q-LIN: $\mathbb{A} = (GF(q); affine subspaces).$
- (NL-c) Digraph reachability: $\mathbb{A} = (\{0, 1\}; x, \neg x, x \leq y)$
- (L-c) Graph reachability: $\mathbb{A} = (\{0,1\}, x, \neg x, x = y)$

Decision CSP as model checking problem

 $CSP(\mathbb{A})$: Instance: Sentence ϕ in the language of \mathbb{A} with \exists and \land Question: ls ϕ true in \mathbb{A} ? $CSP(\mathbb{A})$: Instance: Sentence ϕ in the language of \mathbb{A} with \exists and \land Question: Is ϕ true in \mathbb{A} ?

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From 2^7 cases only 3 interesting (others reduce to these or are boring)

- ► $\{\exists, \forall, \land, (=)\}$ (qCSP) open
- ► {∃, ∀, ∧, ∨} (Positive equality free) solved - tetrachotomy P, NP-c, co-NP-c, PSPACE-c B.Martin, F.Madelaine 11

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- Feder and Vardi suggested that tractability is tied to "closure properties"
- \blacktriangleright \rightarrow algebraic approach Bulatov, Jeavons, Krokhin'00

Most of the definitions will be imprecise

Almost no theorem is true as stated

PP and UA
- If A "can simulate" B then
 CSP(A) is at least as hard as CSP(B).
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 "can simulate" means "positively primitively (pp) interprets"
- Special case of pp-interpretability is pp-definability
- Assume A, B have the same domain.
 A pp-defines B = relations in B definable using relations in A, and ∃, =, ∧.

•
$$\mathbb{A} = (A; R)$$
, where R is ternary

▶ Each instance of CSP(𝔅), eg.

T(z), S(x,y)

• can be rewritten to an equivalent instance of $CSP(\mathbb{A})$

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► Thus CSP(A) is at least as hard as CSP(B)

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Similar conjectures and hardness results about L, NL Larose, Tesson

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Theorem

The following are equivalent.

```
1. A does not interpret (=cannot simulate) 3-SAT
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2. . . .

... Taylor, Hobby, McKenzie, Bulatov, Maróti, Siggers, ...33. ...

34. Pol(\mathbb{A}) contains an operation t such that $t(a, a, \dots, a) = a$ and $t(a_1, a_2, \dots, a_k) = t(a_2, \dots, a_k, a_1)$ for all $a, a_i \in A$ *B*, *Kozik'10*

Better understanding of pre-algebraic results

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- Far broader special cases solved. The dichotomy conjecture is true:
 - ▶ if |A| = 3 Bulatov'06
 - if |A| = 4 Marković et al.
 - ▶ if A contains all unary relations Bulatov'03, Barto'11
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- Local consistency (constraint propagation) Barto, Kozik'09, Bulatov
- All known tractable cases solvable by a combination of these two

Local consistency

Roughly: A has bounded width iff CSP(A) can be solved by checking local consistency
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• if A has width (k, l) for some k, l then A has bounded width Various equivalent formulations (bounded tree width duality, definability in Datalog)

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Consider the instance

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- ▶ By looking at {x, z, w} we see (using x = z and z = w) that x = w.
- By looking at $\{x, w\}$ we now see a contradiction

In fact, \mathbb{A} has width (2,3), that is, such reasoning is always sufficient for an instance of $CSP(\mathbb{A})$.

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- ► If A can simulate q-LIN then A does not have bounded width Larose, Zádori'07
- ► Thus the "obvious" necessary condition for bounded width is that A cannot simulate *q*-LIN.
- It is sufficient:

Theorem

The following are equivalent.

- 1. A cannot simulate q-LIN
- 2. A has bounded width B, Kozik'09
- 3. A has width (2,3) B; Bulatov

Task: Find an almost satisfying assignment given an almost satisfiable instance

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Theorem (B, Kozik'12)

The following are equivalent (assuming $P \neq NP$)

- A cannot simulate q-LIN
- ► CSP(A) has a robust polynomial algorithm
- canonical semidefinite programming relaxation correctly decides CSP(A)

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- The stronger condition is sufficient Bulatov'08, Dyer and Richerby'10

Final remarks

For decision CSPs

- Easy criterion for hardness
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- Applicability of known algorithms understood
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Beyond CSPs

- ▶ ???
- There is ≥ 1 examples Raghavendra



We need coffee!



Thank you!