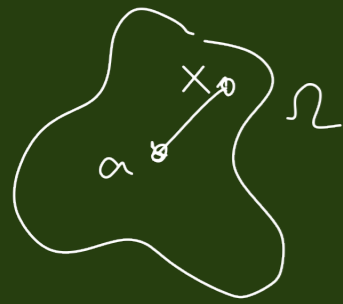


Důkaz 120.25 (c) Bůho $a=0$, tj. $\forall x \in \Omega \forall t \in [0,1] : tx \in \Omega$



Položme: $u(x) = \int_{\gamma_x} f \cdot d\gamma_x$, $\gamma_x(t) = tx$, $t \in [0,1]$.

CHCEME: $\nabla u = f$

jest

$$\frac{\partial u}{\partial x_i}(x) = \frac{\partial}{\partial x_i} \int_0^1 \langle f(tx), x \rangle dt = \frac{\partial}{\partial x_i} \int_0^1 \sum_{j=1}^m f_j(tx) x_j dt$$

$$= \int_0^1 \sum_{j=1}^m \frac{\partial}{\partial x_i} (f_j(tx) x_j) dt = \int_0^1 \left(\sum_{j=1}^m \frac{\partial f_j}{\partial x_i}(tx) tx_j + f_n'(tx) \right) dt,$$

$$f_n'(x) = \int_0^1 \frac{d}{dt} (t f_n'(tx)) dt \stackrel{\text{R}\ddot{\text{P}}}{=} \int_0^1 \left(f_n'(tx) + t \sum_{j=1}^m \frac{\partial f_n'}{\partial x_j}(tx) \cdot x_j \right) dt,$$

takže $\forall i \in \{1, \dots, m\} : \frac{\partial u}{\partial x_i} = f_i$, tedy $\nabla u = f$. □

PŘÍKLAD $\mathbb{R}^2 \setminus \{0\}$.. není hvězdicovita!

$$f(x) = \left(\frac{-x_2}{|x|^2}, \frac{x_1}{|x|^2} \right)$$

pak $\text{curl } f = 0$, ale f není potenciálem!

POZNÁMKY - různá značení

- proměnné v \mathbb{R}^m ,

$x \in \mathbb{R}^m$, $x = (x_1, \dots, x_m)$
 $[x, y, z] \in \mathbb{R}^3$, $[x, y] \in \mathbb{R}^2$

$$\int_c g ds, \int_c f \cdot dc \quad \left(\int_a^b g(c(t)) \|c'(t)\| dt, \int_a^b \langle f(c(t)), c'(t) \rangle dt \right)$$

$$\int_{\underline{\Phi}} g ds, \int_{\underline{\Phi}} f \cdot d\underline{\Phi} \quad \left(\int_G g(\underline{\Phi}(t)) \text{vol } \underline{\Phi}'(t) dt, \int_G \langle f(\underline{\Phi}(t)), \frac{\partial \underline{\Phi}}{\partial t_1}(t) \times \dots \times \frac{\partial \underline{\Phi}}{\partial t_{n-1}}(t) \rangle dt \right)$$

Jina' značen' $\int \vec{f} ds$, $\int f ds$, $\oint \dots$

Integrace vektorových funkcí

$$\int_{\mathbb{R}^n} f d\mathcal{H}^k, \int_{\mathbb{R}^k} f dx^k$$

možnost zápisu:

$$\int f_1 dx + f_2 dy + f_3 dz$$

$$\mathbb{R}^3 \mathbb{R}^3 \quad \int f_2 dy + f_1 dx$$

$$f = (f_1, f_2, f_3)$$

3.30 - 3.35

plošiny: $\int f_1 dydz + f_2 dzdx + f_3 dxdy$

$$A = (f_1, f_2, f_3)$$

PŘÍKLADY -- pole s konstantní rotací v \mathbb{R}^2

$$F = (0, x)$$

$$\text{curl } F = 1$$

$$F = (-y, 0)$$

--

$$\text{curl } F = 2$$

$$F = (-y, x)$$

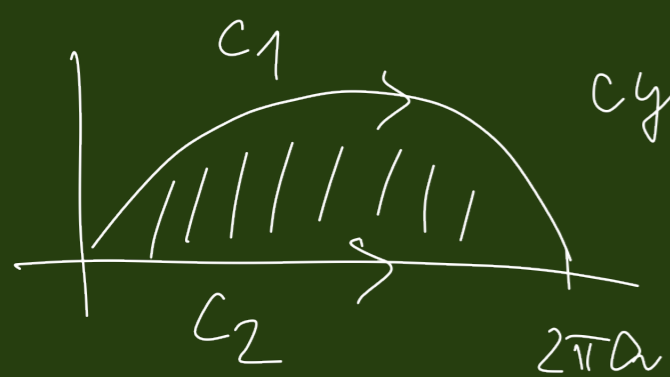
lze využít pro výpočet obsahu
(použití Greenovy věty)

obral, elipsuhun : $\Omega = \text{elipsuh}$, $c = H(\Omega) = \text{elipse}$

$$c(t) = \begin{pmatrix} a \cos t \\ b \sin t \end{pmatrix}, \quad t \in [0, 2\pi], \quad c'(t) = \begin{pmatrix} -a \sin t \\ b \cos t \end{pmatrix},$$

$F = (-y, x)$, $\text{curl } F = 2$, $\text{tolise } 2\pi$

$$\begin{aligned} \mathcal{H}^2(\Omega) & \stackrel{\text{GREEN}}{=} \frac{1}{2} \int_C F \cdot dc = \frac{1}{2} \int_0^{2\pi} (-b \sin t, a \cos t) \begin{pmatrix} -a \sin t \\ b \cos t \end{pmatrix} dt \\ & = \frac{ab}{2} \int_0^{2\pi} (\sin^2 t + \cos^2 t) dt = \underline{\underline{\pi ab}}. \end{aligned}$$



cycloida

$$\varphi(t) = \begin{pmatrix} a(t - \sin t) \\ a(1 - \cos t) \end{pmatrix}, \quad t \in [0, 2\pi]$$



$$c_2(t) = (t, 0), \quad c_2'(t) = (1, 0), \quad F = (0, x), \quad \text{curl } F = 1$$

$$\mathcal{H}^2(\Omega) \stackrel{\text{GR}}{=} \int_C F \cdot dc = \underbrace{\int_0^{2\pi a} (0, x) \begin{pmatrix} 1 \\ 0 \end{pmatrix} dt}_0 = \int_0^{2\pi} (0, a(1 - \cos t)) \begin{pmatrix} a(1 - \cos t) \\ a \sin t \end{pmatrix} dt$$

$= 0$ (over c_2)

$$\varphi'(t) = \begin{pmatrix} a(1 - \cos t) \\ a \sin t \end{pmatrix}$$

$$= - \int_0^{2\pi} a^2 (t \sin t - \sin^2 t) dt = a^2 \int_0^{2\pi} \sin^2 t dt - a^2 \int_0^{2\pi} t \sin t dt$$

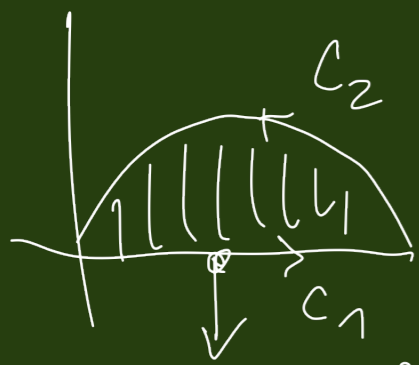
$$= \frac{3\pi a^2}{2}$$

PŘÍKLAD (3.4a) $\int_C e^x (1 - \cos y) dx - e^x (y - \sin y) dy$

$\underbrace{\hspace{10em}}_{+1} \qquad \underbrace{\hspace{10em}}_{+2}$

$f = (f_1, f_2)$

$C = H(\Omega), \quad \Omega = \{ [x, y] \in \mathbb{R}^2, 0 < x < \pi, 0 < y < \sin x \}$



Rěšen parametrizace C

$C = \begin{cases} C_1(t) \\ C_2(t) \end{cases}$

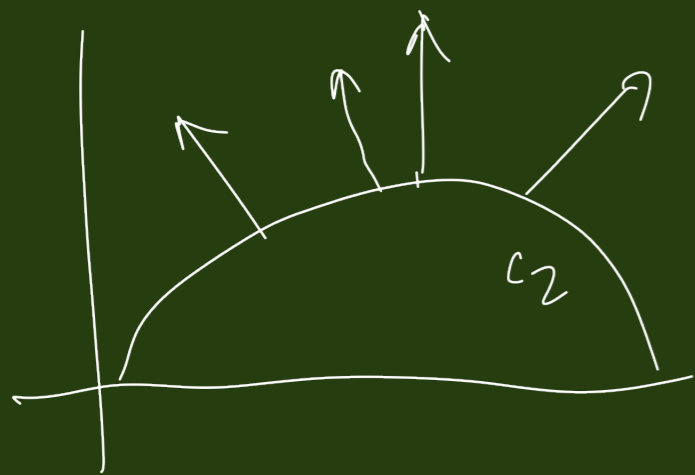
$C_1(t) = \begin{pmatrix} t \\ 0 \end{pmatrix}, t \in [0, \pi], C_1'(t) = \begin{pmatrix} 1 \\ 0 \end{pmatrix}$

$C_2(t) = \begin{pmatrix} 2\pi - t \\ -\sin t \end{pmatrix}, t \in [\pi, 2\pi], C_2'(t) = \begin{pmatrix} -1 \\ -\cos t \end{pmatrix}$

C je PCR, jednoduchá a uzavřená

test orientace $\exists t_0: \det(\nu_\Omega(C(t_0)), C'(t_0))$

na $C_1: t_0 \in (0, \pi): h(x, y) = -y, Dh(x, y) = \begin{pmatrix} 0 \\ -1 \end{pmatrix}, \det \dots = \frac{1}{\|0 \ 1\|} \begin{pmatrix} 0 & 1 \\ -1 & 0 \end{pmatrix} = 1 > 0$



$$c_2(t) = \begin{pmatrix} 2\pi - t \\ -\sin t \end{pmatrix}, \quad c_2'(t) = \begin{pmatrix} -1 \\ -\cos t \end{pmatrix}, \quad t \in (\pi, 2\pi)$$

$$h(x,y) = y - \sin x, \quad \nabla h(x,y) = \begin{pmatrix} -\cos x \\ 1 \end{pmatrix}$$

$$t \in (\pi, 2\pi) : \quad \nu_\Omega = \frac{h}{\|\nabla h\|}, \quad \det(\nu_\Omega, c_2') = \frac{1}{\|\nabla h\|} \det \begin{pmatrix} -\cos(2\pi - t) - 1 \\ 1 & -\cos t \end{pmatrix}$$

$$= \frac{1}{\|\nabla h\|} (\cos t \cdot \cos(2\pi - t) + 1) > 0, \quad \text{ORIENTATION OK}$$

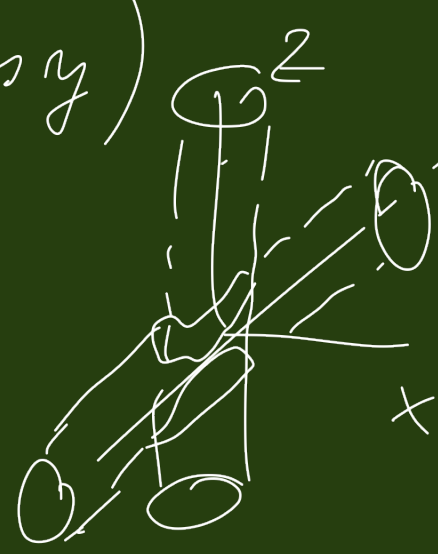
$$f \in \mathcal{C}^1(\mathbb{R}^2), \quad \text{curl } f = -e^x (y - \sin y) + e^x \sin y = -y e^x \quad (\text{SAD})$$

$$f = \left(e^x (1 - \cos y), -e^x (y - \sin y) \right)$$

$$\text{Te dy} \int_c f \cdot dc \stackrel{G \rightarrow}{=} \int_\Omega -y e^x dx^2 \stackrel{\text{Fub}}{=} \int_0^1 \int_0^{\pi \sin x} -y e^x dy dx = \underline{\underline{\frac{-(e^\pi - 1)}{5}}}$$


PRÍKLAD: $\underline{I} = \int_C f \cdot dc$, $f = (-y, x - z^2 \sin y, z^3 + 2z \cos y)$

$C = \{ [x, y, z] \in \mathbb{R}^3, x^2 + y^2 = 1, x^2 + z^2 = 1, z \geq 0 \}$.




Řešení: $C = H(\Omega)$, $\Omega = \{ [x, y, z] \in \mathbb{R}^3, x^2 + y^2 < 1, z = \sqrt{1 - x^2} \}$

parametrizace Ω : „případ graf“ $z = g(x, y)$



pak lze parametrizovat: $\varphi(x, y) = \begin{pmatrix} x \\ y \\ g(x, y) \end{pmatrix}$, pak

$$\frac{\partial \varphi}{\partial x} = \begin{pmatrix} 1 \\ 0 \\ \frac{\partial g}{\partial x} \end{pmatrix}, \quad \frac{\partial \varphi}{\partial y} = \begin{pmatrix} 0 \\ 1 \\ \frac{\partial g}{\partial y} \end{pmatrix}, \quad \frac{\partial \varphi}{\partial x} \times \frac{\partial \varphi}{\partial y} = \begin{pmatrix} -\frac{\partial g}{\partial x} \\ -\frac{\partial g}{\partial y} \\ 1 \end{pmatrix}$$


orientace: přímět c do xy -roviny je kladně orientován

\Rightarrow orientace OK, neboť ν má 3. složku kladnou

$$f = (-y, x - z^2 \sin y, z^3 + 2z \cos y)$$

$$\text{curl } f = (0, 0, 2), \quad G = \{ [x, y] \in \mathbb{R}^2, x^2 + y^2 < 1 \}$$

$$\text{Tedy } \int_G \stackrel{\text{STOKES}}{(0, 0, 2)} \cdot \begin{pmatrix} \frac{x}{\sqrt{1-x^2}} \\ 0 \\ 1 \end{pmatrix} d\mathcal{H}^2 = 2 \mathcal{H}^2(G) = \underline{\underline{2\pi}}$$

21. ČÍSELNÉ ŘADY II

21.1. PŘEROVNÁVÁNÍ ŘAD

OTÁZKA: $\sum_{n=1}^{\infty} a_n$, $a_n \in \mathbb{R}$

jestliže známe součet $\sum_{n=1}^{\infty} a_n$, co lze říci

o součtu $\sum_{n=1}^{\infty} a_{\pi(n)}$, kde $\pi: \mathbb{N} \rightarrow \mathbb{N}$ je
bijekce

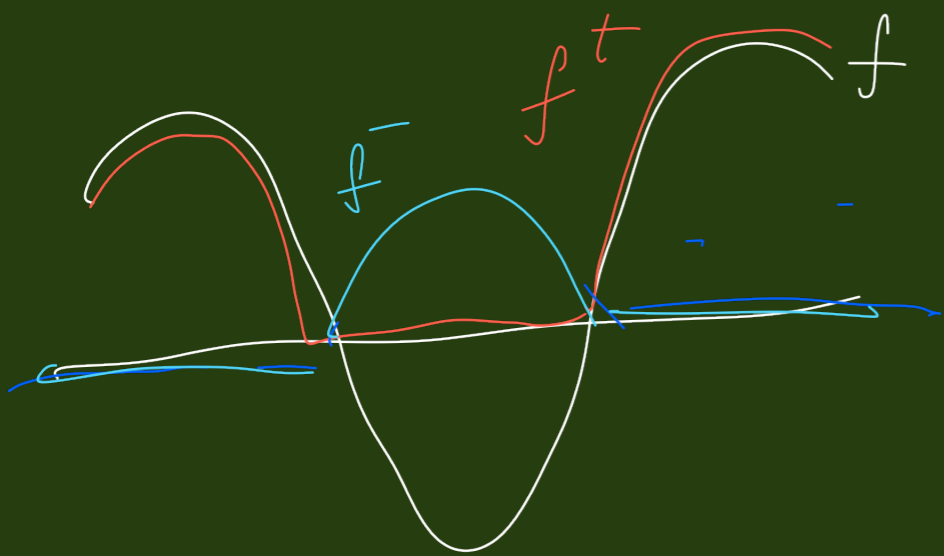
$$a_1 + a_2 + a_3 + \dots = S \quad \Rightarrow \quad a_3 + a_{17} + a_{26} + \dots = ??$$

DEFINICE. Necht $a \in \mathbb{R}$. Kladnou částí a rozumné číslo

$a^+ = \max \{a, 0\}$, zápornou částí a rozumné číslo

$a^- = \max \{-a, 0\}$. Je-li M množina a $f: M \rightarrow \mathbb{R}$, pak

značíme $f^+ = \max \{f, 0\}$, $f^- = \max \{-f, 0\}$.



POZNÁMKY. Platí ($\forall a \in \mathbb{R}$)

- $0 \leq a^+, a^-$, $a^+, a^- \leq |a|$
- $a = a^+ - a^-$
- $|a| = a^+ + a^-$